

Compact image sensor camera

IV-S30

User's Manual (Introduction and Hardware)

< Controller >
-IV-S31M
-IV-S32M
-IV-S33M

Thank you for purchasing the SHARP IV-S30 compact image sensor camera. Read this introductory user's manual carefully to thoroughly familiarize yourself with the functions and proper procedures for operation. Store this user's manual in a safe place. We are confident that the manual will be helpful whenever you encounter a problem.

In addition to this manual, there are two other IV-S30 manuals as follows. Read them in conjunction with this manual.

IV-S30(IV-S31M/S32M/S33M) ———— User's Manual (Introduction and Hardware: **This manual**)

IV-S30(IV-S31M/S32M/S33M) ———— User's Manual (Function and Operation)

Manual type	Major subjects	How to use
IV-S30 (IV-S31M/S32M/S33M) User's Manual (Introduction and Hardware)	<ul style="list-style-type: none"> - Outline of the IV-S30 (features and functions) - Description of the hardware - Startup method - Operation using the simplified menus - General performance specifications. 	<ul style="list-style-type: none"> - Become acquainted with the IV-S30 - Learn how to install the IV-S30 and wire it up - Learn how to execute positioning and existence inspections with simple setting operations.
IV-S30 (IV-S31M/S32M/S33M) User's manual (Function and Operation)	<ul style="list-style-type: none"> - Detailed explanations of all the measurement functions. - Operation using the standard menus. - Details of inputting and outputting data and communications with other devices. - Troubleshooting 	<ul style="list-style-type: none"> - Learn how to specify measurement /inspection conditions, good or NG judgment conditions, etc. - Learn how to connect a programmable controller or personal computer. - Learn what to do if a problem occurs.

Notes

- This manual was written with the utmost care. However, if you have any questions or inquiries concerning the product, please feel free to contact our dealers or service agents.
- Copying all or part of this booklet is prohibited.
- The contents of this manual may be revised or modified for improvement without prior notice.

Important

- When you install the IV-S30 at an European site, use only equipment that complies with the EMC standards. Take the steps described below using the specified cable and EMC core.
- Install a noise filter on the DC power source input lines.
 - Use shielded wires for input/output lines.
 - Install ferrite cores on input/output lines.

Safety Precautions

Read this user's manual and the attached documents carefully before installing, operating, or performing any maintenance, in order to keep the machine working correctly. Make sure you understand all of the equipment details, safety information, and cautions before using this machine. In this user's manual, the safety precautions are divided into "Dangers" and "Cautions" as follows.

 **Danger** : Improper handling is likely to lead to death or serious injury.

 **Caution** : Improper handling may lead to injury or damage to equipment.

Even when only a  **Caution** is given, serious results may occur depending on the circumstances. In all cases, important points are described. Be sure to follow the advice given.

The following symbols are used to prohibit or explain required action.

 : This means do not do what is described. For example, prohibited disassembly is shown as .

 : This means an action you must take. For example, a ground connection that must be made is shown as .

(1) Installation

Caution

- Use only in the environments specified in the instruction manual, or user's manual. Electric shock, fire or malfunction may result if used in high temperature, high humidity, dusty or corrosive environments, or if excessive vibration or impact occurs.
- Install the equipment only as described in the manual. An improper installation may cause the equipment to fail, breakdown, or malfunction.
- Never leave wire cuttings or any other foreign matter lying about. A fire, breakdown or malfunction may result from inappropriate objects left near the equipment.

(2) Wiring

Caution

- Do not connect any camera not specified by SHARP to the IV-S31M/S32M/S33M controller. Connecting any other camera to the controller may damage the controller or the camera.
- Connect only to the specified power source. Connection to the wrong power source may cause a fire.
- Wiring should be performed by a qualified electrician. Improper wiring may lead to a fire, machine failure or electric shock.

(3) Use

Danger

- Don't touch the terminals while the power is turned ON or you may receive an electric shock.
- Assemble an external emergency stop circuit and interlock circuit (external to the IV-S30 compact image sensor camera). Otherwise a breakdown or damage to other equipment may occur due to a problem with the IV-S30.

Caution

- Take special care to follow all safety guidelines if you are changing the parameters for the operating conditions or performing an "enforced output," "run," or "stop" during operation. Misoperation may damage the machine or cause an accident.
- Turn ON the power supplies in the specified sequence. Turning ON the supplies in the wrong order may lead to a machine breakdown or cause an accident.

(4) Maintenance

 **Warning**

- The IV-S32M/S33M controller contains a lithium battery. Do not expose the IV-S32M / S33M directly to flames as the battery may explode and seriously injure people nearby.

 **Prohibit**

- Don't disassemble or modify the camera.
Fires, breakdowns or malfunctions may occur, if the camera is disassembled.

 **Caution**

- Turn OFF the power source before connecting or disconnecting the IV-S30.
If you don't, electric shocks, malfunctions or breakdowns may occur.

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Chapter 2: Precautions for Use

Chapter 3: System Configuration

Chapter 4: Part Names and Functions

Chapter 5: Connection and Installation Methods

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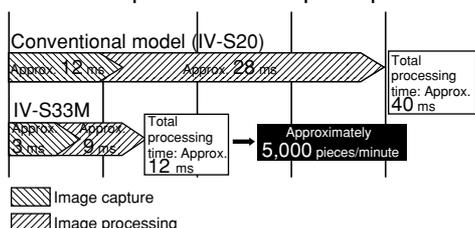
Chapter 1: Outline

This compact image sensor camera system, the IV-S30 (using the IV-S33M controller), dramatically reduces overall processing time, thanks to a camera with double and quadruple speeds, SHARP's partial-image capture function, and a high-speed gray search function. It will not only contribute to high-speed, high-efficiency inspection and measurement processes, but it will also help you keep your prices competitive.

1-1 Features

■ It is now possible to inspect every item in a production run, thanks to high-speed processing

High-speed camera offers double and quadruple speeds. SHARP's unique partial-image capture function and high-speed gray search function provide higher overall speed. This system can inspect approximately 5,000 * pieces per minute (using the IV-S33M controller). Such high speed makes it possible to inspect all the chips or parts in a production lot.



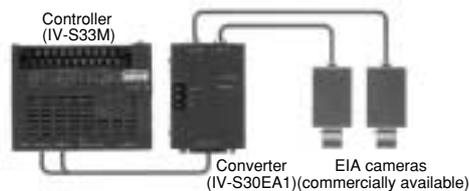
* The total processing times above are true when the measurement conditions are: a 64 x 64 model; a 160 x 160 search, contraction is set to 3; the shutter speed is 1 ms; and a partial image that is 33% of the total image area is specified.

■ The camera diameter is only 17 mm, so it can be installed in a very limited space.

The IV-S30C2/C4 camera is capable of capturing images at 4 times the speed of the standard camera, progressive scanning, and it uses a square grid. It is as small as your thumb. It can be installed in virtually any tiny space in even the smallest machines.

■ Conventional EIA (data) cameras can be used with the controller

The IV-S33M controller can connect two EIA specification cameras using a converter. Just by replacing the controller in the image processing section, you can achieve high-speed processing at decreased cost.



■ Simple and speedy setting makes for easy setups

No need to create a measuring program. You just set the measuring conditions using the remote keypad. In addition, the IV-S33M can automatically set the binary conversion threshold value and evaluation conditions by just pressing the SET key.

■ NG displays and data are transferred quickly, for truly useful NG handling

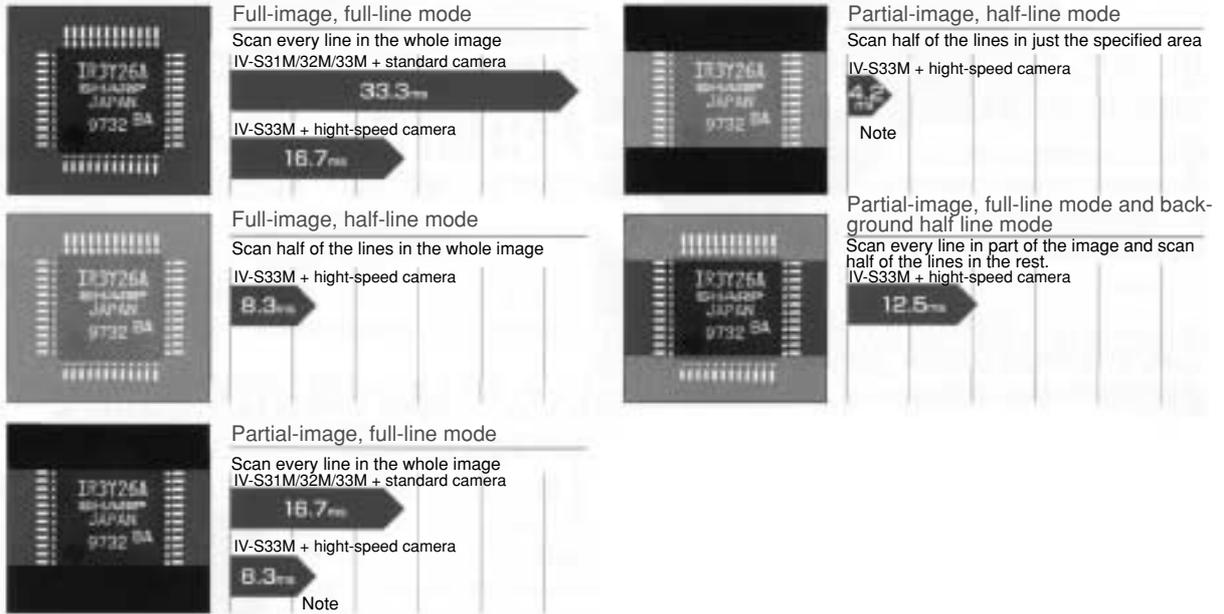
The IV-S33M can check an NG image and a part's NG history while measuring. Using the USB communication bus, NG images can be transferred to a personal computer in less than 7 seconds. The causes of NG products can be fed back to the design section, leading to quick improvements in the quality of your products.

■ Customize to your own specification

An IV-S30LB1 image processing library and IV-S30SP parameter setting support software are both available. Using these tools, the menu screen can be modified to suit your specialized needs to create your own unique image processing system.

• **High-speed processing now possible using a high-speed camera and a partial-image capture function**

The IV-S30 (with the IV-S33M controller) can use double and quad-speed cameras that employ progressive type CCDs. Using SHARP's unique, partial-image capture function, the IV-S30 offers very high-speed image capturing. By selecting the best of five image capturing modes to match your inspection and measurement conditions, this system helps reduce the processing time even further.



* The Partial-image modes are available when scanning 240 out of 480 vertical lines.

* Standard camera: IV-S30C1/C2, High-speed camera: IV-S30C3/C4

* Full-line mode: Scan odd and even lines. Half-line mode: Scan only the odd lines.

Note: The scan time will vary with the position of the partial image to scan. (In the cases given above, there is a maximum of 0.4 ms of difference.)

• **Our high-precision gray search is also high speed**

We normalize images to a 256 grayscale standard, and perform a high-precision gray search by detecting features in sub-pixel units.

The IV-S30 can shorten this process using 9 ms high-speed processing * (IV-S33M)



* When the search area is 256 x 256 pixels, the model is 64 x 64 pixels, and contraction is set to 3.

• **Shorten the cycle time by connecting two cameras**

The IV-S33M can be simultaneously connected to two IV-S30C3/C4 high-speed cameras or two IV-S30C1/C2 standard cameras. By connecting two cameras, your system can reduce the processing time by positioning two areas at the same time, and then inspecting two areas at the same time. By triggering the cameras at the same time, the system can capture two images, and display the images above and below each other, or left and right.

* Combined use of a high-speed camera and a standard camera is not possible.

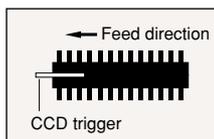
- **You can cut your camera costs by using your current camera (IV-S33M)**

Two, commercially available EIA cameras can be connected using an IV-S33EA1 special converter. This means that you can use your current EIA cameras the same as before, and just replace your image processing section with the IV-S33M. Installation and adjustment of lighting, camera, and lenses is easy and can cut your costs.

- **CCD trigger function does not need an external sensor**

After a trigger window is setup, the IV-S30 does not need an external sensor if it is scanning moving objects. To set up a trigger, you can select from binary image conversion, average density, and gray search techniques. The gray search mode is useful for a workpiece for which you cannot easily establish the density range.

* The gray search trigger function is only available on the IV-S33M.



- **Shutter speed freely set**

The shutter speed can be set anywhere between 1/30 and 1/10000 second for each object type. Practically, this means that the light level can be adjusted without changing the lighting equipment for each object type. The random shutter function is used to close the shutter when a trigger event is detected, so that precise still images of moving objects can be scanned.

- **Easily and automatically set threshold value and judgement criteria (IV-S33M)**

Using the SET key, the IV-S33M can automatically set the threshold values (binary conversion, density difference, and edge width), that used to be set by entering numbers manually. To determine the upper and lower limits of the OK and NG criteria, you only need to measure an OK workpiece. Therefore, you no longer need to rely on skill, or experience to make accurate measurements at high speed.

- **Automatic search reference images (IV-S33M)**

The controller automatically searches for the maximum contrast area within the measurement area, and detects it virtually instantly. Mistake-free work can now be performed quickly.

* This can be used for mis-collation checks of printed matters.

- **Simple measurements of position, detection of the same workpiece and counting quantities (IV-S33M)**

By using the degree of match inspection functions for multiple workpieces and position measurement for multiple workpieces, the controller can detect up to 128 workpieces in one image that meet or exceed a specified degree of match with the reference image. The controller can count quantities and measure the positions of workpieces that have complicated structures of light levels and are difficult to convert to binary images.

- **Effective when checking for angular deviation, very good as a robotic eye**

The controller can detect objects turned through a full 360° of orientation. It can inspect printing at great angles off the main axis, and can be used in robotic inspection machines.

- **CE approval applied for, widely accepted in international markets**

The reliability of the IV-S30 means that it can be used in units destined for overseas markets.

- **Integrated measuring programs allow the controller to be used for inspection and measurement immediately**

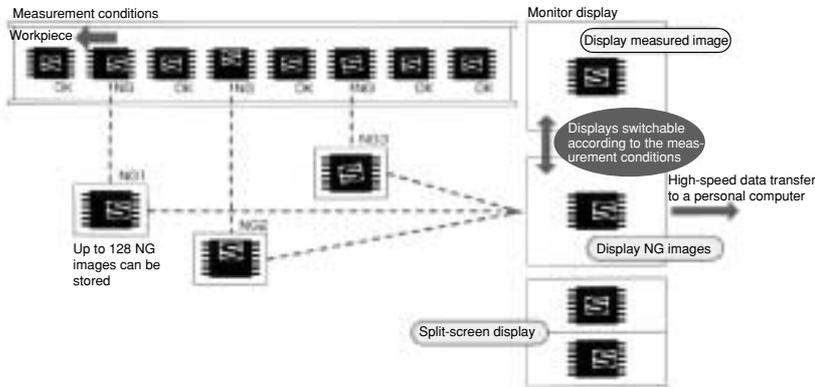
Simple operations on the remote keypad let you select the desired measuring program to suit your application. Since there is no need to develop measuring programs, this unit is easy set up and you can start measuring products the same day you receive it.

- Various measuring programs

Positional deviation measurement, degree of match inspection, distance and angle measurement, lead inspection, area measurement by binary conversion, counting by binary conversion, label measurement by binary conversion, point measurement, BGA/CSP inspection*¹, multiple position measurement*², and multiple degree of match inspection*².

*¹ IV-S32M/S33M only, *² IV-S33M only.

- **Measure a large number of object types: the IV-S30 can register up to 64 object types**
The IV-S30 can keep track of more than one set of measurement conditions. The shape of an object, its position and your desired measurements are all programmable. Therefore, it can be used on a production line that produces multiple, slightly or greatly different models.
(IV-S33M: Maximum 64 items, IV-S32M: Maximum 32 items, IV-S31M: Maximum 16 items)
- **Integrated micro PC function**
The IV-S30 has a micro PC function that allows it to determine unknown values by calculating the inspected and measured results and then output signals to lamps and plungers. You can construct a complete, simple inspection process with a single controller.
- **Displays and transfers NG images while measurements are being made (IV-S32M/S33M)**
The IV-S33M can check an NG image history (up to 128 images) while measuring, or simultaneously display a measured image and an NG image by splitting the screen. While measuring, the controller can send NG images over the USB bus (12 Mbps) to a personal computer at high speed (approximately 7 seconds per image). Since you can collect and analyze NG images in real time, the NG rate can be decreased by finding the cause and making corrections immediately.
(The IV-S32M can display NG images when measurements are stopped.)



1-2 Controller

[1] Software version of the controllers

This manual describes the controllers (IV-S31M/S32M/S33M) and their respective software versions below.

Controller	Software version
IV-S31M	V2.02
IV-S32M	V2.02
IV-S33M	V1.01

[2] Differences between types of controllers

The controller models (IV-S31M/S32M/S33M) have the following specifications.

Item		IV-S31M	IV-S32M	IV-S33M
Number of object types handled		16	32	64
Maximum number of reference images/ total number of images		300/3	600/8	600/8
Gray search time*		18 ms	12 ms	9 ms
Connecting camera	Standard camera (IV-S30C1)	○	○	○
	Micro camera (IV-S30C2)	○	○	○
	High-speed camera (IV-S30C3)	-	-	○
	Micro, high-speed camera (IV-S30C4)	-	-	○
	EIA camera (commercially available)	-	-	○
Split display of two camera images on the left and right sides of the screen		-	-	○
Number of NG images that can be stored (Maximum 128 images)		-	○	○
Calendar/timer		-	○	○
BGA/CSP inspection		-	○	○
Input terminal block	Object type be changed	X1 to X4	X1 to X5	X1 to X6
	External input	X5 to X7	X6, X7	X7
Power consumption		7W	7W	7W

("○": Compatible/available, "-": Not compatible/unavailable)

* The gray search times given above are true when the search area is 256 x 256 pixels, the model is 64 x 64 pixels, and the contraction value is set to 3.

For other specifications, see pages 8-1 to 8-3 in "Chapter 8: Specifications."

[3] Upgrade details

(1) IV-S33M

This manual describes the IV-S33M using software version V1.01.

The upgrade details (functions added to version V1.00) for the IV-S33M software (system program) are as follows.

■ Newly added functions in software version V1.01 (compared with V1.00)

Item	Added function
Halt on NG measurement	"NO (NG measurement display)" has been added on the "②HALT ON NG MEAS" line in the "OBJECT TYPE SYS." menu.
NG image display screen	When the MONITOR OUTPUT is set to "CAM1&2", the screen displays the camera number (Camera 1: C1, Camera 2: C2) next to the measurement display screen.
Strobe output	On the setting screen, a strobe output is now available when switching from a dynamic image to a static image. ("⑥STROBE OUT" on [I/O CONDITIONS])

For details about using the added functions (standard menu), see the "IV-S30 (IV-S31M/S32M/S33M) User's Manual, Function and Operation"

(2) IV-S31M/S32M

This manual describes the IV-S31M/S32M using software version V2.02.

The upgrade details (functions added to version V1.15) for the IV-S31M/S32M software (system program) are as follows.

■ Newly added functions in software version V2.02 (compared with V1.15)

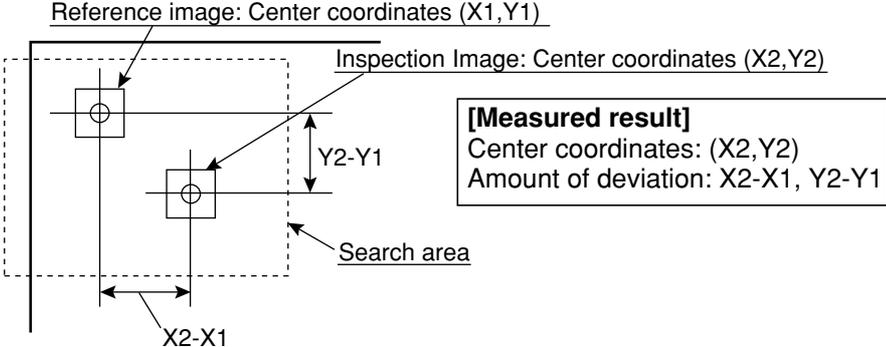
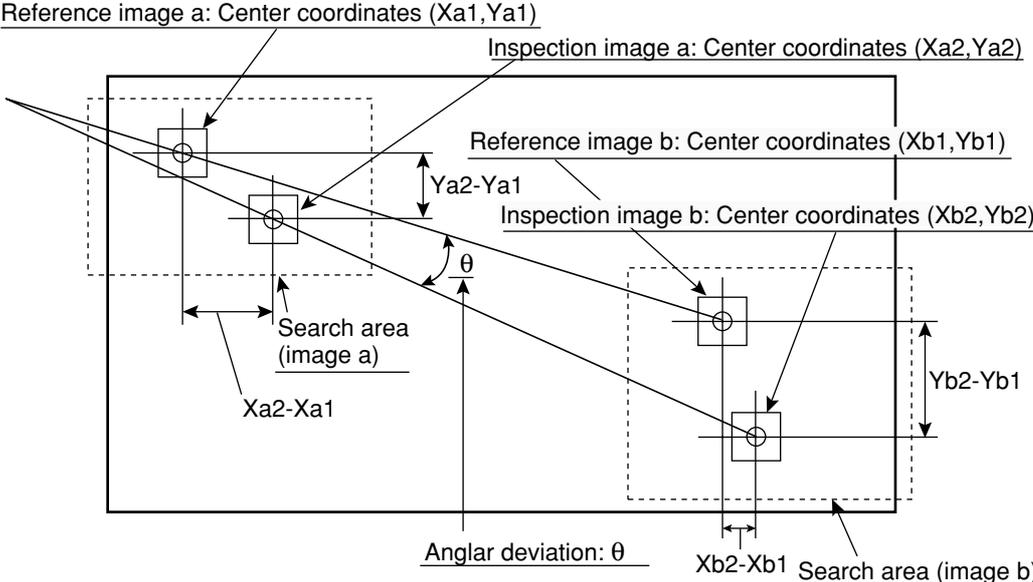
Item	Added function
NG image (IV-S32M only)	NG image display function added. Therefore, the "①DISP NG IMAGE" line (display NG images) on the [OBJECT TYPE SYS.] menu is deleted. Added "NG-IMG-INIT" (initialize NG images) on the "④INITIALIZATION" line of the [SYSTEM COND] menu.
CCD trigger	Added "YES (GRAY SRC)" on the "①TRIG CCD START " line of the [OBJECT TYPE I/O] menu.
Measurement program	Added "MULTI-POSI" and "MULTI MATCHES" for use as the measurement programs.
Light level inspection	Added the "④MATCHING (AVG-GRAYS, DIFF. ABS)" line on the [MEAS COND] menu. <Degree of match inspection, multiple degree of match inspection>
Contrast search	Added "CONTRAST SR" to the "REF IMG AREA" choices on the [Gray search] menu. <Positional deviation measurement, degree of match inspection, multiple position measurement, multiple degree of match inspection>
Use camera setting	Added the "②SELECT CAMERA (CAM1&2, CAM1&NG-IMG)" line on the [TYPE MEAS COND] menu.
Automatic light level difference and edge width detection	Added an "AUTO. REGI" (automatic registration) choice on the [Edge detection] menu. <Positional deviation measurement, lead inspection, multiple position measurement>
Automatic threshold value setting	Added an "AUTO REGIST" choice on the [Binary area cond] menu. <BGA/CSP inspection (IV-S32M), area measurement by binary conversion, object counting by binary conversion, object identification (labeling) by binary conversion>
Binary mask	Added "MANUAL" to the "①MASK SET" line on the [BINARY IMG MASK] menu. ⇒ Added a polygonal window setting.
Object identification (labeling) by binary conversion	Added "MID-PNT " (middle point) to the "BINARY CHARACTER" choices on the [MEAS COND] menu.
Evaluation condition	Added "CONDITION SET" on the [EVALUATION COND] menu. <All measurement programs>
Numerical calculation	- Added "FUNCTION (SUM, AVG, REG) " on the [NUMERIC CALC] menu. - Increased the number of digits below the decimal from 2 to 4, for the upper and lower value settings on the [NUMERIC CALC] menu. <All measurement programs>
Reference image	Made it possible to display a reference image using the number previously registered on the [Gray search] menu. <Positional deviation measurement, degree of match inspection, multiple position deviation measurement, multiple degree of match inspection>
Extension function	Added the "⑩EXTENSION FUNC. 2 (crosshair cursor display)" line on the [TYPE RUN COND].
Positional correction	Made it possible to set the correction registration in two stages ⇒ Added (0 to 1) on the "①MODE" line on the [POSITION CORRECT] menu.
Window group move	Added the "⑦MOVE ALL WINDOW" line on the [OBJECT TYPE SYS.]
Rotation angle unit	Added the "④ANGLE UNIT" line on the [MEAS COND] menu of the positional deviation measurement.

For details about the added functions (standard menu), see the "IV-S30 (IV-S31M/S32M/S33M) User's Manual, Function and Operation"

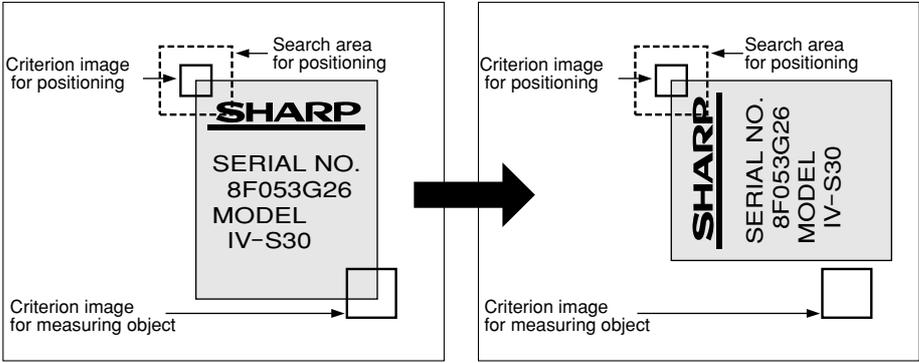
1-3 Measurement program

The IV-S30 integrates the following eight measurement programs: Positional deviation, degree of match inspection, lead inspection, BGA/CSP inspection (IV-S32M/S33M), area measurement by binary conversion, object counting by binary conversion, object identification (labeling) measurements by binary conversion, multiple position measurement (IV-S33M), multiple degree of match inspection, point measurements and distance and angle measurement. You can select operating condition parameters to suit your application of the IV-S30.

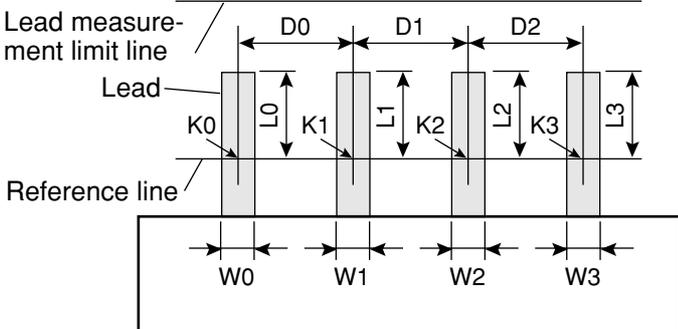
[1] Positional deviation measurement

<p>Purpose</p>	<p>The gray scale search function makes it possible to measure positional deviation as well as the absolute position. - It is also possible to detect the position of sub-pixel units with great accuracy. - A rotation angle of 360° can be detected. (When a one point gray search is selected).</p>
<p>Application</p>	<p>Used to determine the position of machine parts and substrates.</p>
<p>Example</p>	<p>[Determining the location of the positioning (the fiducial mark) mark that identifies the position of the substrate] (1) 1 point search: Detecting the deviation in position in X and Y directions</p>  <p>[Measured result] Center coordinates: (X2, Y2) Amount of deviation: X2-X1, Y2-Y1</p> <p>(2) 2 point search: Determining positional deviation in X and Y directions as well as rotational deviation</p>  <p>[Measured result] - Center coordinates of image a: (Xa2, Ya2) - Amount of deviation of image a: Xa2-Xa1, Ya2-Ya1 - Center coordinates of image b: (Xb2, Yb2) - Amount of deviation of image b: Xb2-Xb1, Yb2-Yb1 - Deviation angle: θ</p> <p>- The deviation angle θ, determined in the 2-point search, is used to readjust the rotation of the image for measurements 1 to 4.</p>

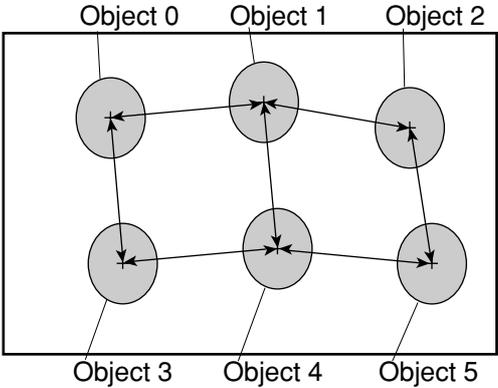
[2] Degree of match inspection

<p>Purpose</p>	<p>Compare a good criterion image to a test image by inspecting matching levels using the gray scale search function. (Determine whether the part is acceptable or NG by checking similarities between the criterion image and the workpiece (test) image.) A matching level comparison using binary images is also possible.</p>
<p>Application</p>	<p>Detect positional deviation of labels, detect contamination of different parts, inspect the mounting of electronic parts on PC boards, detect mis-prints, inspect for missing electric parts such as terminals, and simple letter inspection.</p>
<p>Example</p>	<p>[Detecting label deviations on packages]</p>  <p>▲ Good label</p> <p>▲ NG label</p> <p>[Measured results]</p> <ul style="list-style-type: none"> - Degree of match compared with the reference image - Detected coordinates (X/Y) of the measurement image. - Light level in the measured image (average light level/absolute value of difference) <p>- Inspection procedure</p> <ol style="list-style-type: none"> ① Conduct a gray scale search of the criterion image position ② Correct the position of the object being measured from the coordinates for the criterion image obtained in item ① above. ③ If the matching level of the test image is low, the IV-S30 can determine that the label position is NG.

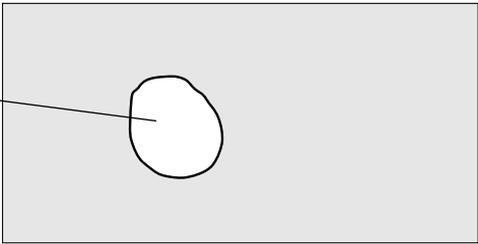
[3] Lead inspection

<p>Purpose</p>	<p>Based on positional information obtained from the gray scale search function, inspect the condition of the IC leads and connector pins. (No. of lead pins that can be detected in one image: Max. 128.)</p>
<p>Application</p>	<p>Inspect the IC leads and connector pins</p>
<p>Example</p>	<p>[Inspect the layout of the IC leads and connector pins]</p>  <p>[Lead inspection]</p> <ul style="list-style-type: none"> - Number of leads K - D0 to D2: Distance between leads - W0 to W3: Lead width - L0 to L3: Lead length <p>- Inspection procedure</p> <ol style="list-style-type: none"> ① Determine the measurement points (K0 to K3) from the mid points of the leads and the reference line. ② Calculate the distances between the leads (D0 to D2) using the measurement points. ③ Calculate the lead lengths (L0 to L3) from the measurement points (K0 to K3) toward the lead measurement limit line. ④ Calculate the lead widths (W0 to W3) centering the measurement points.

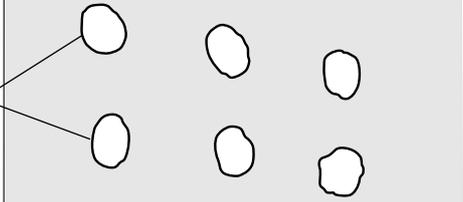
[4] BGA/CSP inspection (IV-S32M/S33M)

Purpose	Measure the center of gravity, area of each object, number of objects, and fillet diameter using the object identification function after binary conversion.
Application	Inspecting BGA/CSP solder balls.
Example	<p>[Measurement of 6 balls]</p>  <p>[Measured results]</p> <ul style="list-style-type: none"> - Number of objects: K - Area of each object: R0 to R127 - Distance between centers of gravity: (DX0, DY0) to (DX127, DY127) - Fillet diameters: FX, FY <p>- Inspection procedure</p> <pre> graph LR A[Image capture] --> B[Binary conversion] B --> C[Object identification (numbering)] C --> D[Measure centers of gravity] C --> E[Fillet diameters] F[Area of each object] --> G[Ball size] H[Distance between centers of gravity for pairs of balls] --> I[Distance between balls] H --> J[Number of balls] </pre>

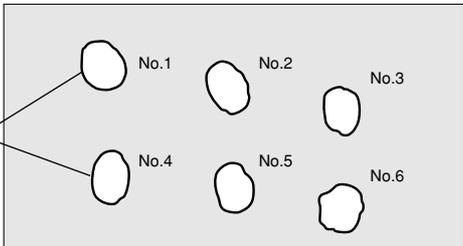
[5] Area measurement by binary conversion

Purpose	Detect the existence/absence and size of a workpiece when “the workpiece is one point” or “measurement position is fixed.” - Convert the specified pixel area to binary values and measure the size of the white area.
Application	Check for the existence of bearings inserted by a bearing insert machine, prevent contamination of different parts in automobile production lines, determine the type of waterproof caps, check for the existence/absence of bottle labels, inspect the circuit traces on PWBs, check for the presence of grease, check for existence of frozen foods.
Example	 <p>[Measured result]</p> <ul style="list-style-type: none"> - Workpiece area <p>- Inspection procedure</p> <pre> graph LR A[Capture image] --> B[Convert to binary values] B --> C[Measure (area)] </pre>

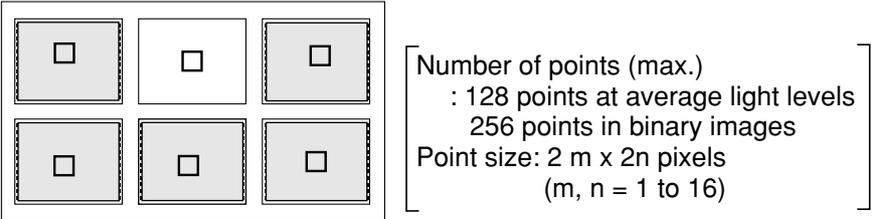
[6] Object counting by binary conversion

<p>Purpose</p>	<p>Checks the number of objects (max. 3000 pcs.) when there is more than one object in an image arranged arbitrary. - When the specified pixel field has been converted to a binary image, the white areas are measured or identified as separate objects and counted.</p>
<p>Application</p>	<p>Counting pieces of food or parts</p>
<p>Example</p>	<div style="display: flex; align-items: center;"> <div style="margin-right: 20px;"> <p>Workpiece</p>  </div> <div style="margin-left: 20px;"> <p>[Measured result] - Number of workpieces/total area size</p> </div> </div> <p>- Inspection procedure</p> <pre> Capture image → Convert to binary values → Measure (quantity, total area size) </pre>

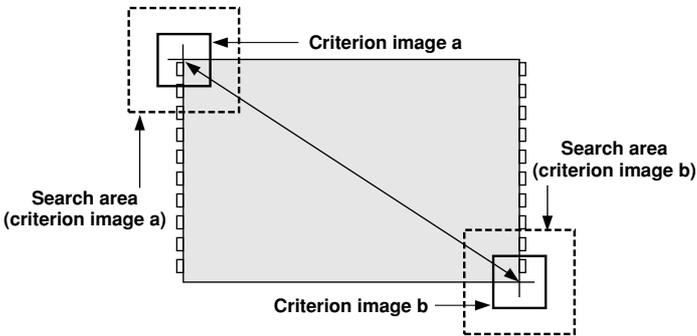
[7] Object identification (labeling) by binary conversion

<p>Purpose</p>	<p>When there are several objects and the measuring position is arbitrary, the presence or absence of objects and the size of the objects can be determined. - The specified pixel area is converted to a binary image. The number of objects, total size of the white area (the objects) and the area, center of gravity, main axis angle, fillet diameter, center point, and circumference of each white area can be measured.</p>
<p>Application</p>	<p>Counting the number of food products or parts, measuring the sloped angle or center of gravity of parts, and measuring the size of food products.</p>
<p>Example</p>	<p>[Measurement of 6 objects]</p> <div style="display: flex; align-items: center;"> <div style="margin-right: 20px;"> <p>Objects</p>  </div> <div style="margin-left: 20px;"> <p>[Measured result] - Object identification (numbering), number of objects present, total area. - Center point (IV-S33M only), area, center of gravity, main axis angle, fillet diameter, circumference, and center point of each object.</p> </div> </div> <p>- Inspection procedure</p> <pre> Image capture → Convert to binary values → Object identification (numbering) → Measurement (area, gravity center, main axis angle, fillet diameter, circumference, and center point) </pre>

[8] Point measurements

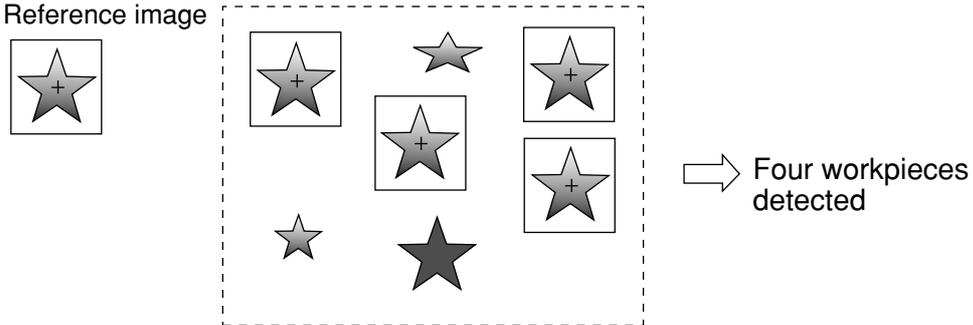
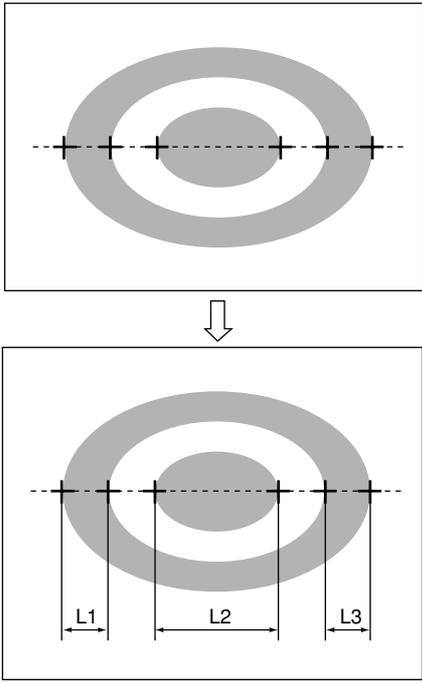
<p>Purpose</p>	<p>The presence or absence of target objects is examined.</p> <ul style="list-style-type: none"> - A simple black or white evaluation is made in the specified pixel area of binary images. - The light level in the specified pixel area is averaged, and a decision is made whether or not it is within the specified lightness range in gray scale images.
<p>Applications</p>	<p>Checking the presence or absence of packed parts, inspecting the working condition of LEDs or fluorescent character display tubes, and sorting household electric appliances.</p>
<p>Example</p>	<p>[Inspection at 6 points]</p>  <p>- Inspection procedures</p> <pre> graph LR A[Image capture] --> B[Binary conversion] A --> C[Average light level] B --> D[Black/white evaluation of points] C --> E[Light level evaluation of points] </pre>

[9] Distance and angle measurement

<p>Purpose</p>	<p>Measure the distance and angle of two points using the center detection function in a gray scale search and the edge detection function, as well as center of gravity detection by functions.</p> <ul style="list-style-type: none"> - This function can measure the following distances and angles: distance between two points, X coordinate distance, Y coordinate distance, the angle between three points, the horizontal angle of two points, and the vertical angle of two points. - The following points and lines can be set: center point, circle center point, gravity center, point where two straight lines cross, line passing through two points.
<p>Application</p>	<p>Measurement of mounted electronic parts</p>
<p>Example</p>	<p>[Measuring IC packages]</p>  <p>Register criterion image a and b by matching edges of the IC package.</p> <p>- Measurement procedures</p> <ol style="list-style-type: none"> ① Find the center points of criterion images a and b using a 2-point gray scale search. ② Determine the distance between the two center points.

[10] Multiple position measurement (IV-S33M)

1

<p>Purpose</p>	<p>The IV-S33M can detect up to 128 workpieces whose images exceed the specified matching level (gray search) or threshold value (edge detection) compared with the reference image.</p> <ul style="list-style-type: none"> - The positional deviation measurement needs to have a number of positions registered for measurement. However, this measurement only requires you to register one position and reduces the set up time.
<p>Applica-tion</p>	<p>Measure the position of workpieces with a complicated light level that cannot be converted into binary images.</p>
<p>Example</p>	<p>● Gray search</p>  <p>[Measured results]</p> <ul style="list-style-type: none"> - Number of images detected - Coordinates and degree of match detected for each image <p>● Edge detection</p>  <p>[Measured results]</p> <ul style="list-style-type: none"> - Number of points detected - Coordinates detected for each points <p>This is useful for obtaining the distance between the coordinates of a position.</p> <ul style="list-style-type: none"> - L1 to L3 can be calculated by measuring distances and angles.

[11] Multiple degree of match inspection (IV-S33M)

Purpose	Using the gray search function, the IV-S33M can detect up to 128 workpieces whose captured image exceeds the required degree of match with the reference image.
Applica-tion	Inspect (or count) workpieces that have complicated light levels and cannot be converted into binary images
Exam-ple	<div style="display: flex; align-items: center; justify-content: space-around;"> <div style="text-align: center;"> <p>Reference image</p>  </div> <div style="border: 1px dashed gray; padding: 10px; display: flex; flex-wrap: wrap; justify-content: space-around;">     </div> <div style="text-align: center;"> <p>⇒ Four workpieces detected</p> </div> </div> <p>[Measured results]</p> <ul style="list-style-type: none"> - Number of images detected - Degree of match, density (average/absolute difference), and detected coordinates

Chapter 2: Precautions for Use

Pay attention to the points below when handling the IV-S30.

(1) Installation

- Each device in the IV-S30 system must be installed in an environment as specified in this manual. (Operating ambient temperature: 0 to 45°C, operating ambient humidity: 35 to 85%RH (non-condensing.))
- Do not install the devices in the following locations. Installation in any of these locations may cause electrical shock, fire, or malfunction of the devices.
 1. Places exposed to direct sunlight
 2. Places with exposed to corrosive gases
 3. Places with excessive amounts of dust, salt, or metal powder in the air.
 4. Places exposed to water

(2) Mounting

Make sure to tighten the mounting and terminal screws securely and check everything before supplying power. A loose screw may cause faulty operation.

(3) Power source

- Do not use the IV-S30 (power supply for the controller) power supply with any other equipment.
- Do not turn OFF the power while the menu is displayed or while communicating with external equipment. Turning OFF the power may erase the data settings.

(4) Measurement settings

Make sure to specify 4000 ms (4 seconds) or less for the measurement processing time on each measurement item (MEASUREMENT 0 CAMERA 1, MEASUREMENT 0 CAMERA 2, and MEASUREMENT 1 to 4). For example, if the various tasks require 7000 ms of measurement processing time, assign 3500 ms to MEASUREMENT 1 and 3500 ms to MEASUREMENT 2 so that each of the assigned processing times is less than 4000 ms.

If the measurement processing time exceeds 4000 ms, the IV-S31M/S32M/S33M assumes that an abnormal operation has occurred and may try to reset the system.

(5) Data saving

- The data set by using the remote keypad is temporarily stored in the memory (RAM) of the IV-S30. However, it is not stored in the flash memory yet. Therefore, make sure to save the data settings before returning to the operation screen from any condition settings menu by pressing the SET key. If you do not save the data, the data will disappear when you turn OFF the power to the IV-S30 controller.
- We recommend that you save the data settings and reference images on a floppy diskette using the IV-S30SP parameter setting support software for the IV-S30.

(6) Storing the devices

Do not put any object on top of any of the devices, or the device may malfunction.

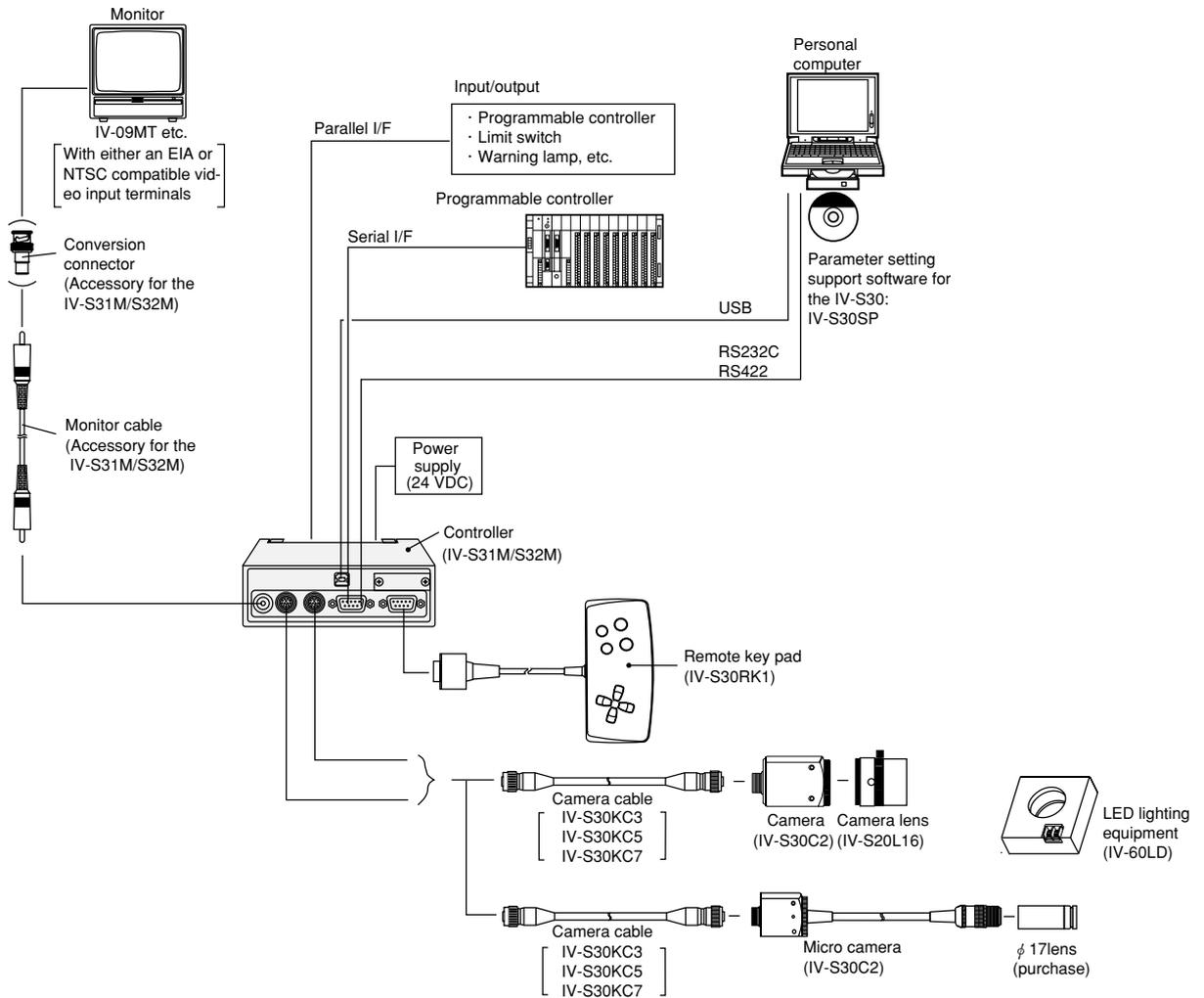
(7) Maintenance

Be careful not to get any dirt or stains on the CCD surface or camera lens. This may cause mis measurement.

Chapter 3: System Configuration

3-1 Basic system configuration

[1] When the IV-S31M/S32M is used as the controller



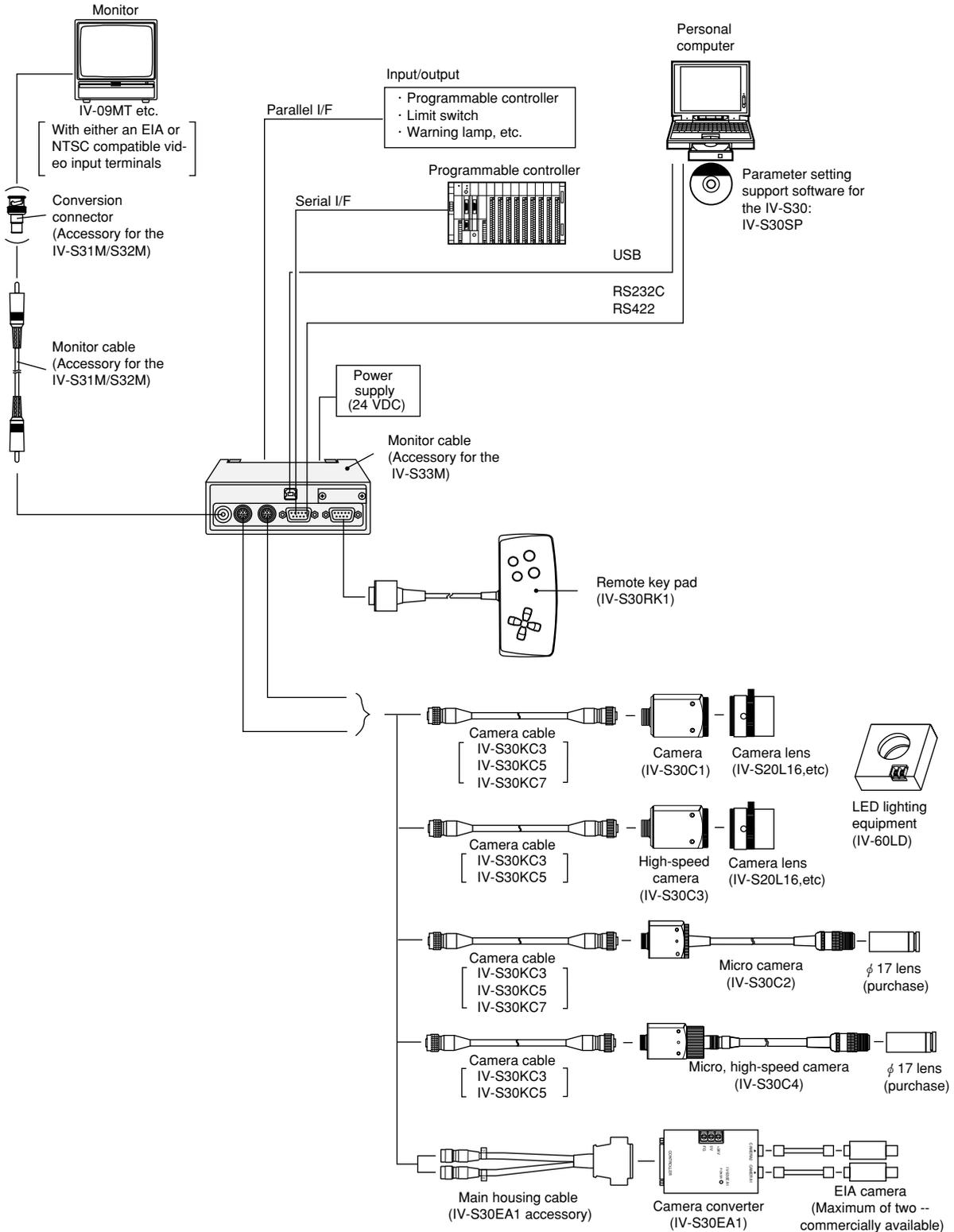
- A maximum of two cameras can be connected to the IV-S31M/S32M.
- An IV-S20C1 camera (for the IV-S20) also can be connected using a camera conversion cable (IV-S30HC).

Product lines

Item name		Model name	Specification or details
Camera	Standard	IV-S30C1	Camera main housing (without lens or camera cable)
	Micro	IV-S30C2	Camera main housing (without lens or camera cable)
Camera cable		IV-S30KC3	Cable for IV-S30C1/C2 camera, 3 m
		IV-S30KC5	Cable for IV-S30C1/C2 camera, 5 m
		IV-S30KC7	Cable for IV-S30C1/C2 camera, 7 m
Camera lens		IV-S20L16	C mount lens with a 16 mm focal length
Remote keypad		IV-S30RK1	Keys for remote entry
Parameter setting support software		IV-S30SP	Runs on Windows95/98/NT4.0
Image processing library		IV-S30LB1	Runs on Windows95/98/NT4.0
Monochrome monitor		IV-09MT	Monochrome 9 inch monitor
LED lighting equipment		IV-60LD	Integrated light source and controller in one housing

- For details about the IV-S30SP, IV-S30LB1, IV-09MT, and IV-60LD, see the individual instruction manuals.

[2] When the IV-S33M controller is used



- A maximum of two cameras of the same type can be connected to the IV-S33M.
- Mixed use of different camera types (IV-S30C1/C2, IV-S30C3/C4, and EIA cameras) is not supported.
- The IV-S30KC7 camera cable cannot be used with the IV-S30C3/C4 high-speed camera.
- The IV-S20C1 camera for the IV-S20 can also be connected using a camera conversion cable (IV-S30HC).

■ Product lines

Item name	Model name	Specification or details	
Camera	Standard	IV-S30C1	Camera main housing (without lens or camera cable)
	Micro	IV-S30C2	Camera main housing (without lens or camera cable)
	High-speed	IV-S30C3	Camera main housing (without lens or camera cable)
	Micro, high-speed camera	IV-S30C4	Camera main housing (without lens or camera cable)
Camera converter	IV-S30EA1	Connect up to two EIA cameras (commercially available)	
Camera cable	IV-S30KC3	Cable for IV-S30C1/C2/C3/C4 camera, 3 m	
	IV-S30KC5	Cable for IV-S30C1/C2/C3/C4 camera, 5 m	
	IV-S30KC7	Cable for IV-S30C1/C2 camera, 7 m	
Camera lens	IV-S20L16	C mount lens with a 16 mm focal length	
Remote keypad	IV-S30RK1	Keys for remote entry	
Parameter setting support software	IV-S30SP	Runs on Windows95/98/NT4.0	
Image processing library	IV-S30LB1	Runs on Windows95/98/NT4.0	
Monochrome monitor	IV-09MT	Monochrome 9 inch monitor	
LED lighting equipment	IV-60LD	Integrated light source and controller in one housing	

- For details about the IV-S30SP, IV-S30LB1, IV-09MT, and IV-60LD, see the individual instruction manuals.

3-2 System configuration examples

This section outlines the system configurations for measurement using an external trigger, such as measurement using a photo sensor, measurement using CCD trigger, and measurement triggered by a command from a personal computer.

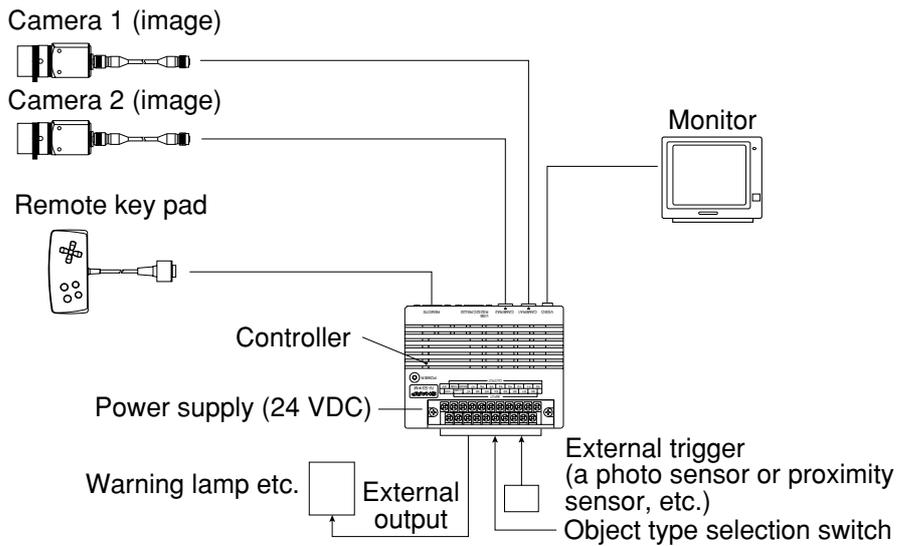
See "Setting the Input/Output Conditions" in the IV-S30 User's Manual (function and operation).

[1] System configuration example for measurement triggered by an external trigger, such as a photo sensor

(1) When IV-S30 is used in a stand-alone mode

- Purpose/application

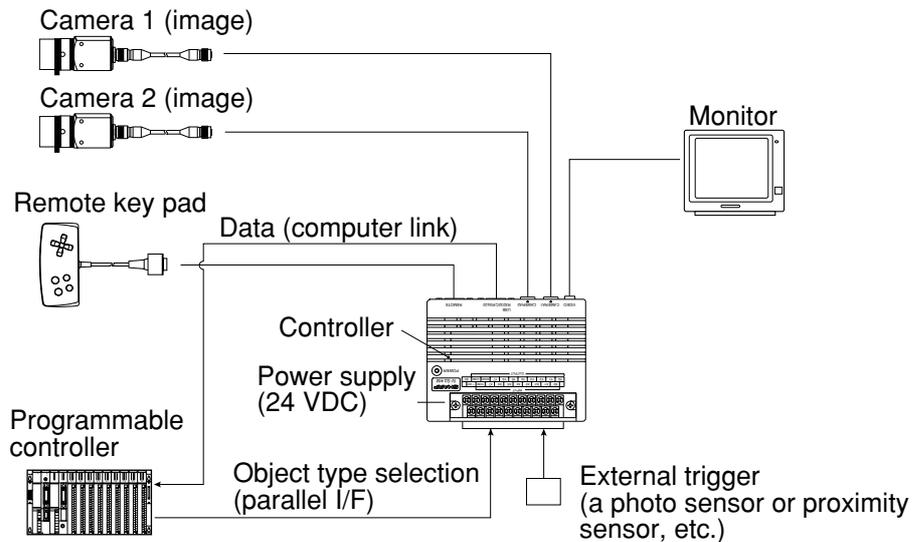
Measurement is started by an external trigger (a photo sensor or proximity sensor), and the measurement result is output externally (warning lamp). The object type number is selected by an external switch.



(2) When a programmable controller is connected

- Purpose/application

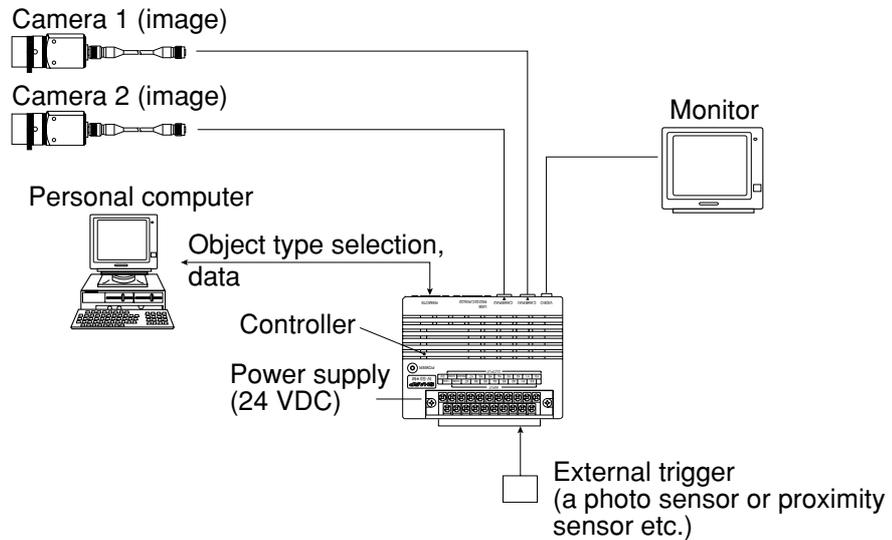
Measurement is started by an external trigger (a photo sensor or proximity sensor), and the measurement data is output to a programmable controller. The object type number is selected by the programmable controller.



(3) When a personal computer is connected

- Purpose/application

Measurement is started by an external trigger (a photo sensor or proximity sensor etc.), and the measurement data is output to a personal computer. The object type number is selected by the personal computer.



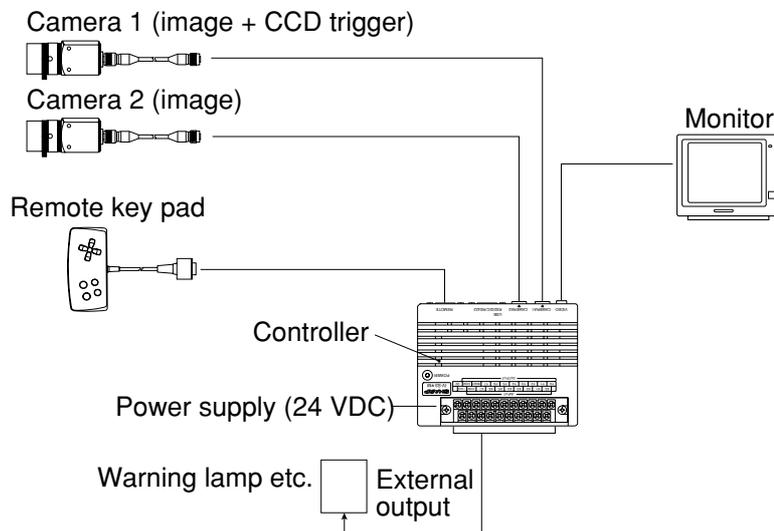
[2] System configuration example for measurement triggered by the internal CCD sensor trigger

The internal CCD trigger can be used with camera 1, but with camera 2.

(1) When IV-S30 is used in a stand-alone mode

- Purpose/application

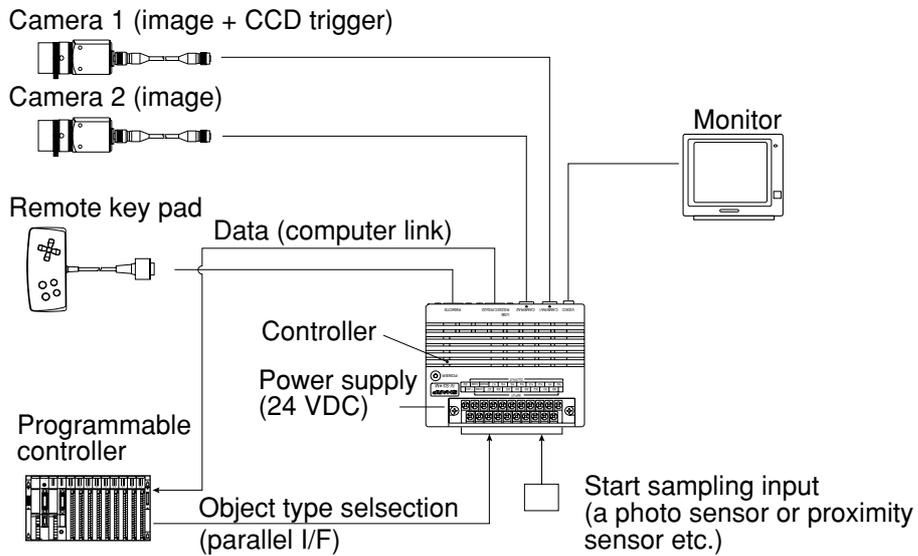
Measurement is started by a CCD trigger, and the measurement result is output externally (warning lamp etc.). In this case, sampling operation is automatically started.



(2) When a programmable controller is connected

- Purpose/application

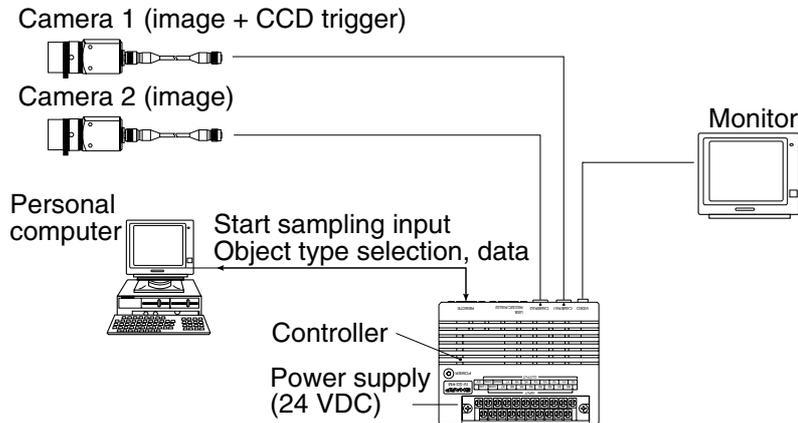
Measurement is started by a CCD trigger (sampling start input: a photo sensor etc.), and the measurement data is output to a programmable controller. The object type number is selected by the programmable controller.



(3) When a personal computer is connected

- Purpose/application

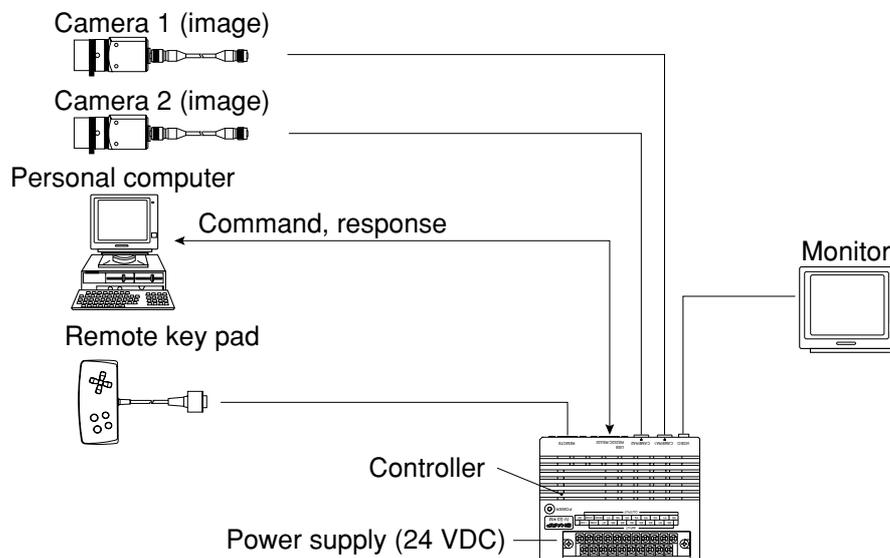
Measurement is started by a CCD trigger (sampling start input: personal computer), and the measurement data is output to a personal computer. The object type number is selected by the personal computer.



[3] System configuration example for measurement triggered by a command from a personal computer

- Purpose/application

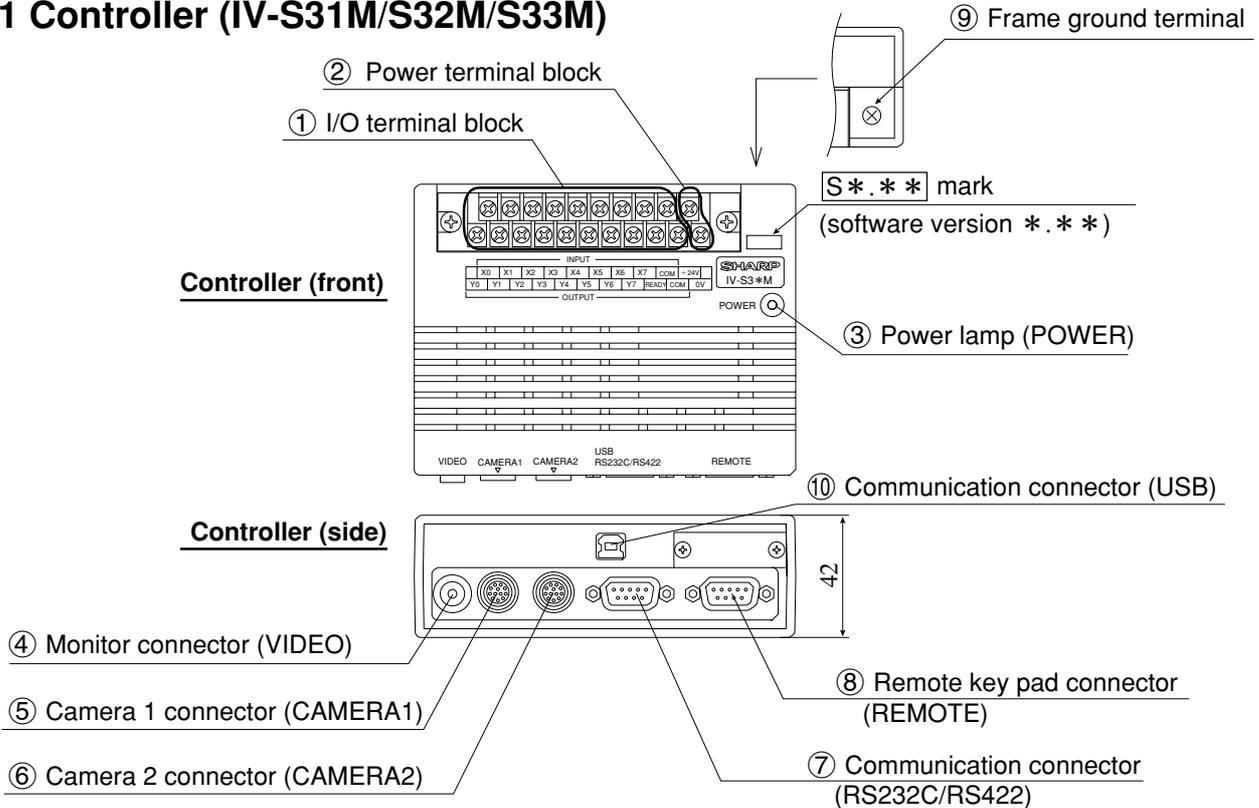
Measurement is started by a trigger from a personal computer, and the measurement data is output to the personal computer. The object type number is selected by the personal computer.



Chapter 4: Part Names and Functions

This section describes the names and functions of the controller, camera (camera lens, camera converter, camera body and camera cable), and the remote keypad which comprise the IV-S30 system. See section in Chapter 5 "Connection and Installation Methods" for details about the housing brackets, camera angle bracket and conversion connector.

4-1 Controller (IV-S31M/S32M/S33M)

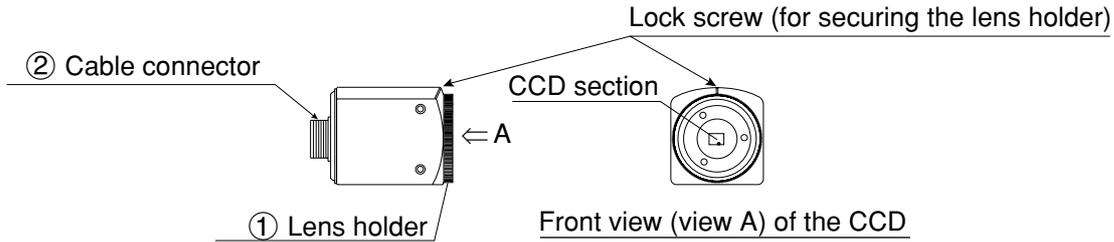


	Name	Function
①	I/O terminal block INPUT: X0 to X7, C (+) OUTPUT: Y0 to Y7, READY, C (-)	This block has 8 input terminals and 9 output terminals. - External devices are connected to these terminals for input and output (parallel I/F). ⇨ See page 5-17.
②	Power terminal block (+24V, 0V)	Commercially available constant-voltage power supply (24 V DC ± 10%, 500 mA or more) is connected here. ⇨ See page 5-15.
③	Power lamp (POWER)	When the power is applied to the controller, the green lamp will light.
④	Monitor connector (VIDEO)	A monitor is connected here. - The monitor connector is an RCA jack.
⑤	Camera 1 connector (CAMERA1)	The camera cable connector is connected here.
⑥	Camera 2 connector (CAMERA2)	- The camera connected to the CAMERA 1 position is camera 1, and the camera connected to the CAMERA 2 position is camera 2.
⑦	Communication connector (RS232C/RS422: 9-pin, D-sub, female, rock screw)	This connector is used to connect a personal computer for communications (general purpose serial I/F) or to connect a programmable controller for a computer link. ⇨ See page 5-20
⑧	Remote key pad connector (REMOTE)	The remote key pad connector is used to make selections from the menus on the screen (to set parameters). It is connected here.
⑨	Frame ground terminal	Be sure to ground the housing frame ground terminal together with the frame ground of the constant-voltage power supply in accordance with class 3 grounding procedures. ⇨ See page 5-15.
⑩	Communication connector (USB)	This connector is used to connect a cable to a USB port on a personal computer. - The USB port only functions with Windows 98.

4-2 Camera

[1] Camera

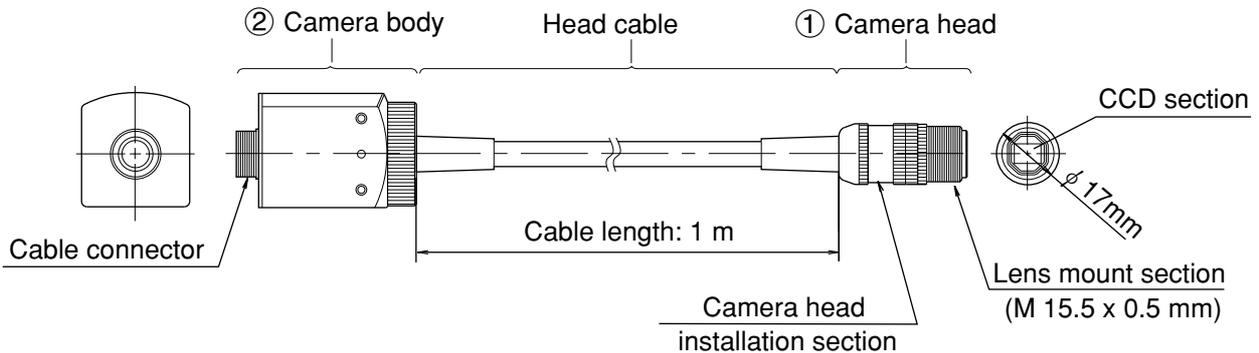
(1) Standard camera (IV-S30C1)



	Name	Function
①	Lens holder	The holder is used to make fine adjustment to the distance (back plane focus) between the CCD section and camera lens using a focus fixed lens. (The distance has been adjusted before shipment. Usually, it does not need to be adjusted.) - To adjust it, loosen the upper lock screw, and turn the lens holder counter-clockwise. The maximum allowable distance is 1.5 mm.
②	Cable connector	Connect this connector to the camera cable (IV-S30KC3/S30KC5/S30KC7).

- To connect an IV-S30C1 camera, use the IV-S31M/S32M/S33M controller and camera cable shown above.

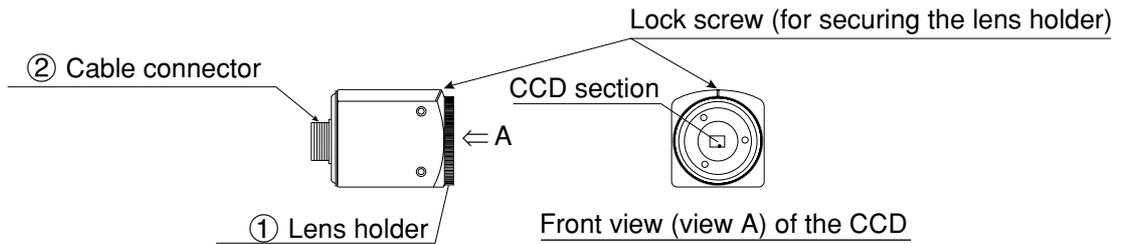
(2) Micro camera (IV-S30C2)



	Name	Function
①	Camera head	Install a (commercially available) lens. - The maximum external diameter of the camera head is ϕ 17 mm, and the one for lens mount is M 15.5 x 0.5 mm.
②	Camera body	Connect to the camera connector of the camera cable (IV-S30KC3/KC5/KC7).

- To connect an IV-S30C2 camera, use the IV-S31M/S32M/S33M controller and camera cable shown above.

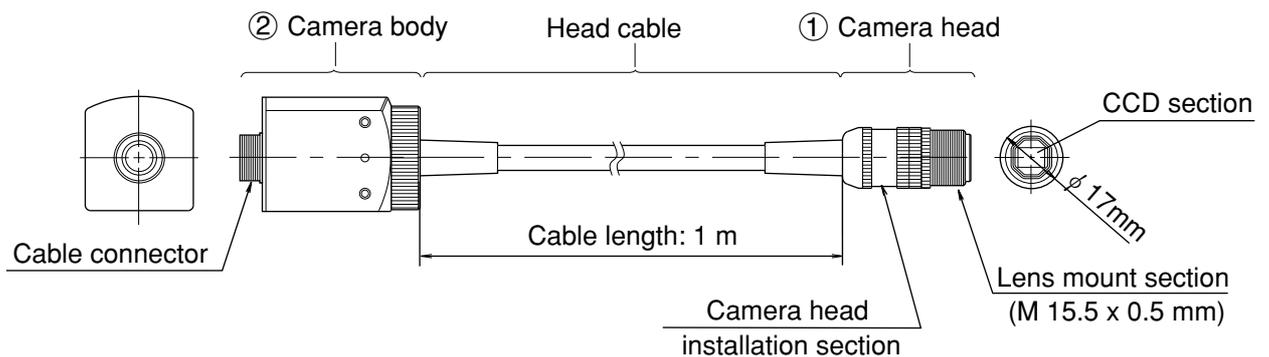
(3) High-speed camera (IV-S30C3)



	Name	Function
①	Lens holder	The holder is used to make fine adjustment to the distance (back plane focus) between the CCD section and camera lens using a focus fixed lens. (The distance has been adjusted before shipment. Usually, it does not need to be adjusted.) - To adjust it, loosen the upper lock screw, and turn the lens holder counter-clockwise. The maximum allowable distance is 1.5 mm.
②	Cable connector	Connect this connector to the camera cable (IV-S30KC3/S30KC5/S30KC7). Note: This cable cannot be used to connect the IV-S30KC7.

- To connect an IV-S30C3 camera, use the IV-S33M controller and camera cable shown above. Do not connect to the IV-S31M/S32M.

(4) Micro, high-speed camera (IV-S30C4)

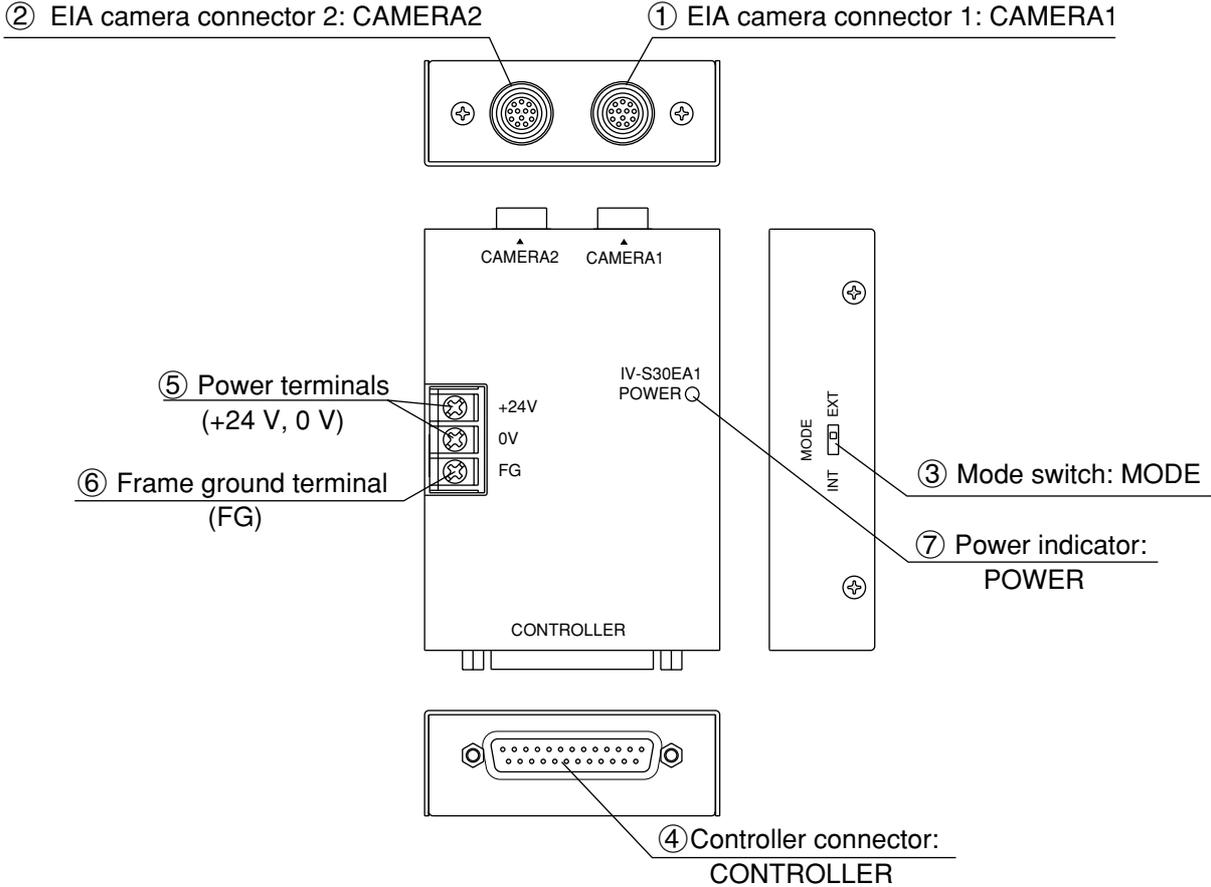


	Name	Function
①	Camera head	Install a (commercially available) lens. - The maximum external diameter of the camera head is $\phi 17$ mm, and the one for lens mount is M 15.5 x 0.5 mm.
②	Camera body	Connect to the camera connector of the camera cable (IV-S30KC3/KC5/KC7). Note: This cable cannot be used to connect the IV-S30KC7.

- To connect an IV-S30C4 camera, use the IV-S33M controller and camera cable shown above. Do not connect to the IV-S31M/S32M.

4

[2] IV-S30EA1 camera converter

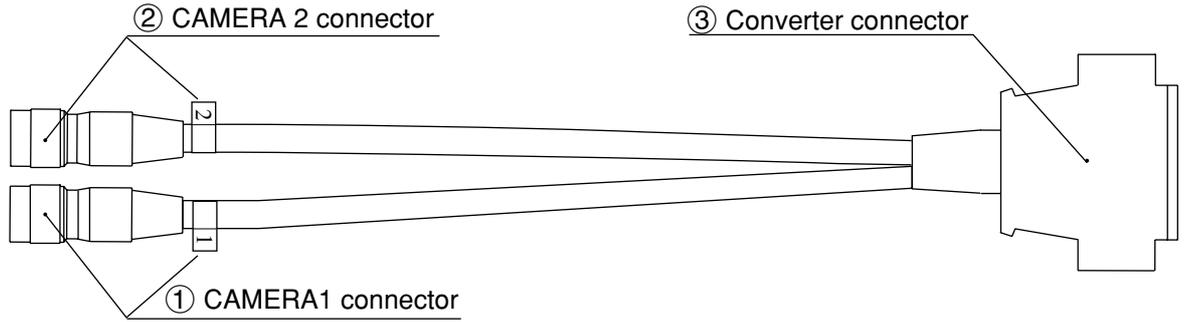


	Name	Function
①	EIA camera connector 1: CAMERA1	Connect an EIA camera (commercially available). Any camera connected to CAMERA1 will be camera 1, and any camera connected to CAMERA2 will be camera 2.
②	EIA camera connector 2: CAMERA2	Note: Do not connect SHARP's special IV-S30C1/C2/C3/C4 camera.
③	Mode switch: MODE	Select the camera synchronization mode from EXT and INT. Use a thin pointed object such as a ballpoint pen. - EXT = Lets you use an EIA camera with an externally synchronized mode (a synchronizing signal is sent from the IV-S33M to the EIA camera). - INT = Lets you use an EIA camera with an internally synchronized mode.
④	Controller connector: CONTROLLER	Connect to the main housing cable (supplied with the IV-S30EIA, see the next page)
⑤	Power terminals (+24 V, 0 V)	Connect to any commercially available constant voltage DC power supply (24 VDC±10%, 500 mA or more)
⑥	Frame ground terminal (FG)	This terminal is commoned with the enclosure. When the EIA camera is connected to the controller using a shielded cable, the EIA camera housing will be electrically connected to this terminal.
⑦	Power indicator: POWER	When power is supplied to the IV-S30EA1, this lamp will light green.

- To connect the IV-S30EA1 to the IV-S33M controller, use the cable supplied with the IV-S30 (see the next page).

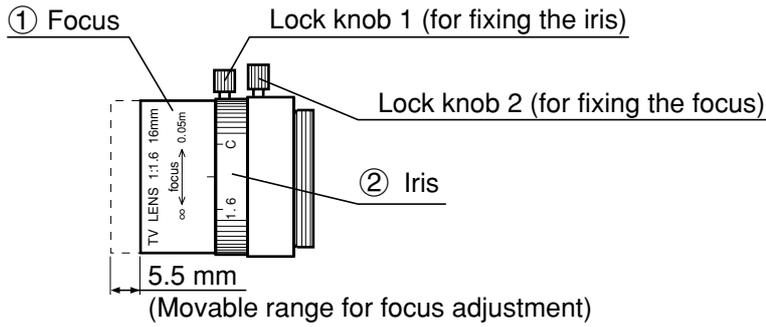
The IV-S30EA1 cannot be connected to the IV-S31M/S32M controller.

■ Cable to connect the converter to the controller (supplied with the IV-S30EA1)



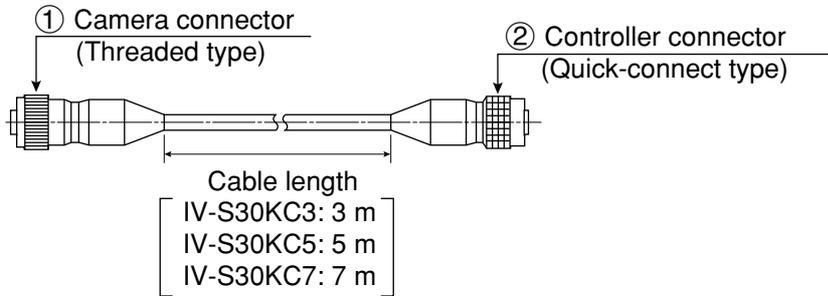
	Name	Function
①	Camera 1 connector	Connect to the CAMERA 1 and CAMERA 2 connectors on the IV-S33M controller.
②	Camera 2 connector	
③	Converter connection connector	Connect to the controller side connector on the IV-S30EA1.

[3] Camera lens (IV-S20L16)



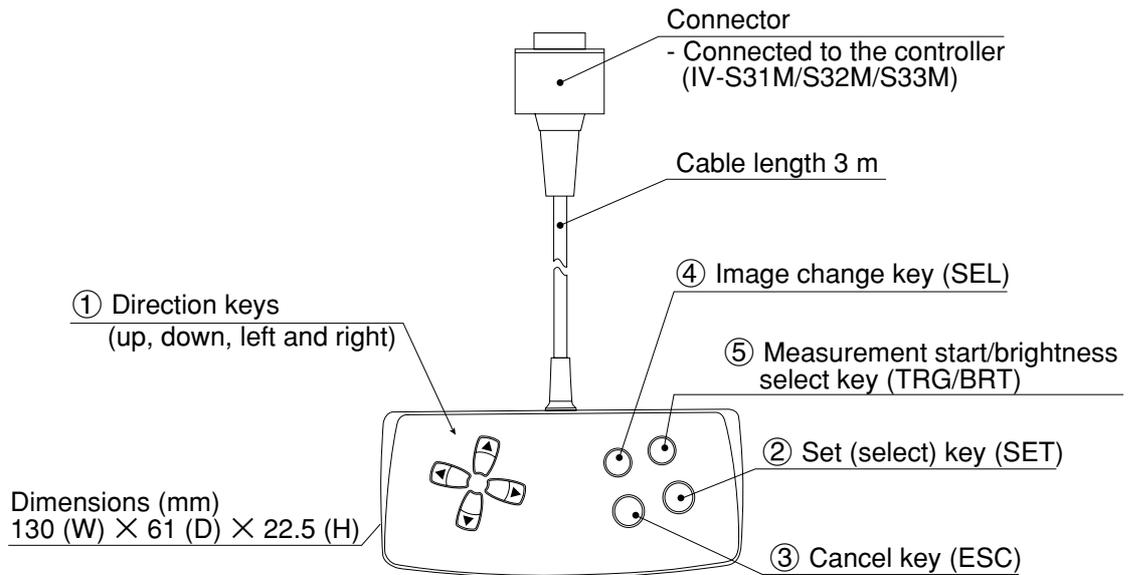
	Name	Function
①	Focus	To focus an image -The focal length (distance from an object) is 50 mm to infinity (from the front of lens).
②	Iris	To adjust the image brightness. -The iris aperture can be set from 1.6mm to closed.

[4] Camera cable (IV-S30KC3/KC5/KC7)



	Name	Function
①	Camera connector	Connect to a connector of camera cable (IV-S30C1/C2/C3/C4). Note: The IV-S30KC7 cannot be connected to the IV-S30C3/C4.
②	Controller connector	Connect to camera 1 connector or camera 2 connector of the controller (IV-S31M/S32M/S33M).

4-3 Remote keypad (IV-S30RK1)



	Key name	Function	Description
①	* Direction keys (up, down, left and right)	Selecting an item on a menu screen	Select an item with the up, down, left and right keys.
		Setting a window	Set each coordinate.
		Setting a value	- Select a digit or an item with the left and right keys, and then specify a value with the up and down keys. - Specify a value with the up, down, right and left keys.
②	Set (select) key (SET)	Determine a highlighted item	—
		Determine the setting value	
③	Cancel key (ESC)	Returning a setting to its original state before being changed	—
		Returning to the previous menu	
④	Image change key (SEL)	Switching the image mode between the through mode and freeze mode	Switch the image mode between through and freeze on a setting screen. (See the preceding page.) When the mode is switched from through to freeze, a new image is captured. Note: The run screen is only displayed in the freeze mode, and the "GAIN/OFFSET" screen is only displayed in the through mode.
⑤	Measurement start/brightness select key (TRG/BRT)	Start measurement input	Press this key on the run screen, and a new measurement is triggered.
		Switching the brightness level (H and L)	Change the displayed image brightness. - Use this key when the image is so bright that characters are difficult to see. - The brightness can be changed on any screen other than the run screen.

* The direction keys have an auto-repeat function.

Chapter 5: Connection and Installation Methods

5-1 Installation conditions

[1] Lighting equipment

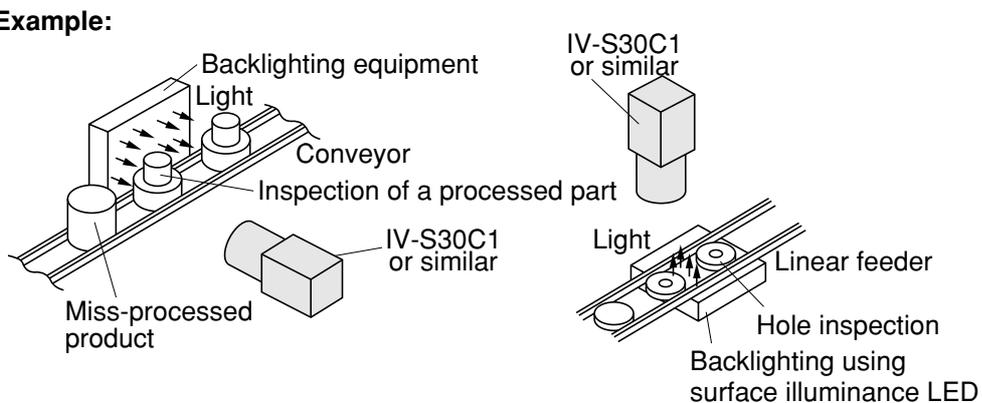
Lighting for the workpieces is an important factor in image processing. The lighting conditions affect the measurement results. Select the proper lighting equipment.

- Make sure there is uniform illumination of the whole measurement field where object images will be taken.
- Use flicker-free lighting equipment, such as a high frequency fluorescent lamps or halogen lamps.
- Consult us about the right lighting equipment for your application.

(1) Backlighting

Light should uniformly illuminate the field behind an object, so that the IV-S30 measure the object with it's shadow. Since the shadow picture will be converted to binary values, reliable measurements can be executed.

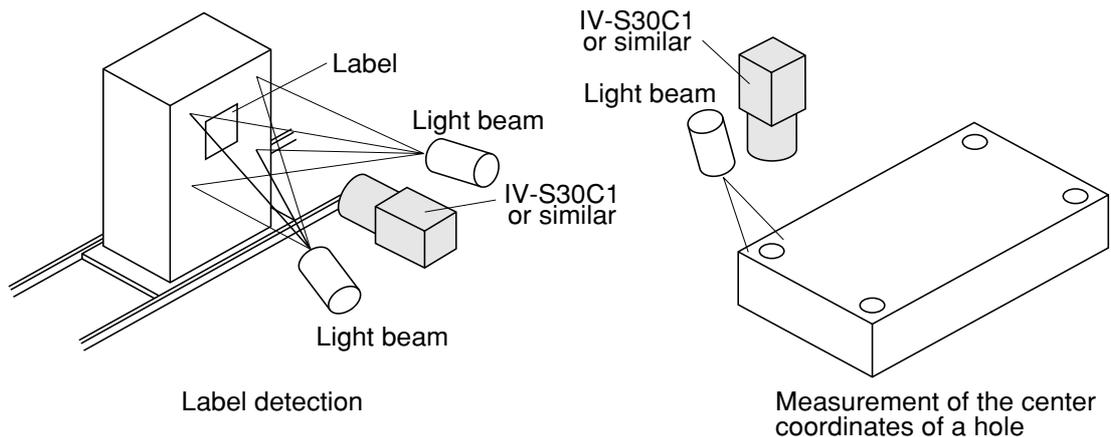
Example:



(2) Reflective lighting

A light shone on the front of an object with angle will be reflected, and the IV-S30 will pick up the reflected light. If too much light is reflected, such as from a metallic surface or similar materials, a proper image may not be obtained.

Example:

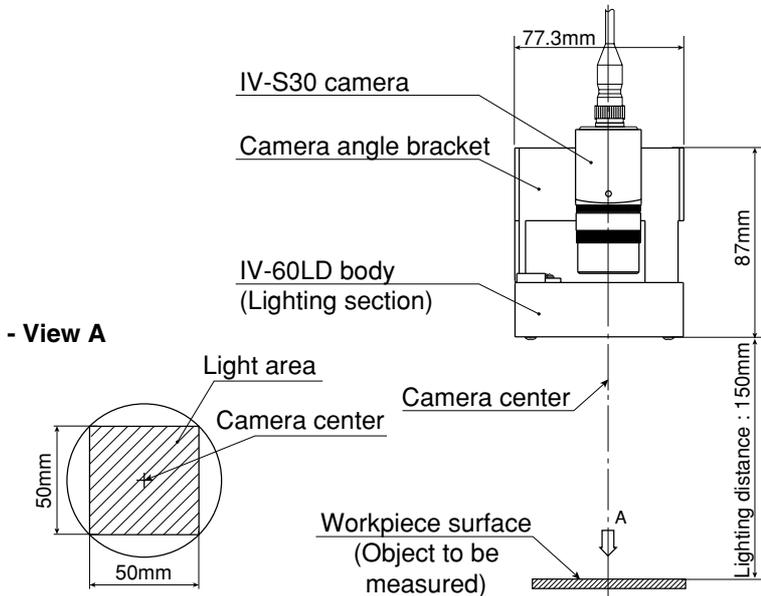


■ When using the IV-60LD

This paragraph describes how to use Sharp IV-60LD LED lighting equipment. For details about the installation and wiring of the IV-60LD, see the instruction manual.

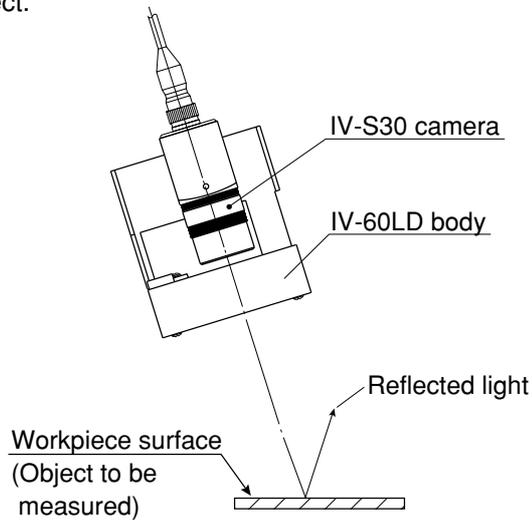
The distance between the IV-60LD and an object (distance at which to install lighting equipment) should be approximately 150 mm, and the lit area is approximately 50 mm ¥ 50 mm.

If the lighting distance is reduced approximately 60 mm, the lighting may be uneven.



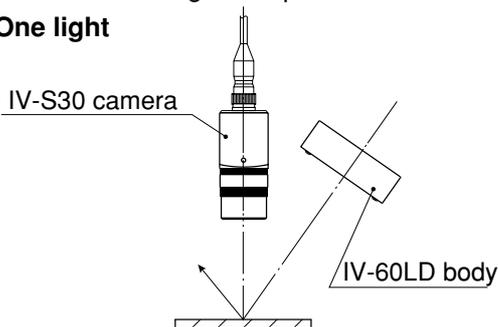
When the light is projected from above the object and if reflection off the object influences the image processing, try the following countermeasures.

- ① Tilt the camera center axis (within a range that does not affect the image processing) to move away from the light reflected from the object.

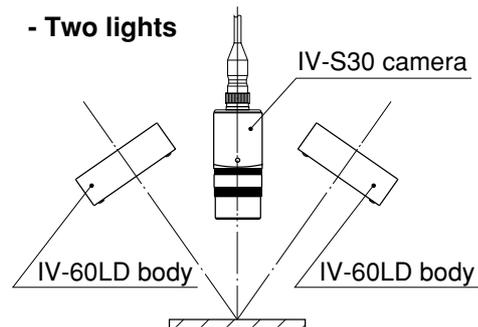


- ② Separate the camera from the lighting equipment. Install the IV-60LD lighting equipment so that it will shine from an angle that prevents creation of the reflection.

- One light



- Two lights

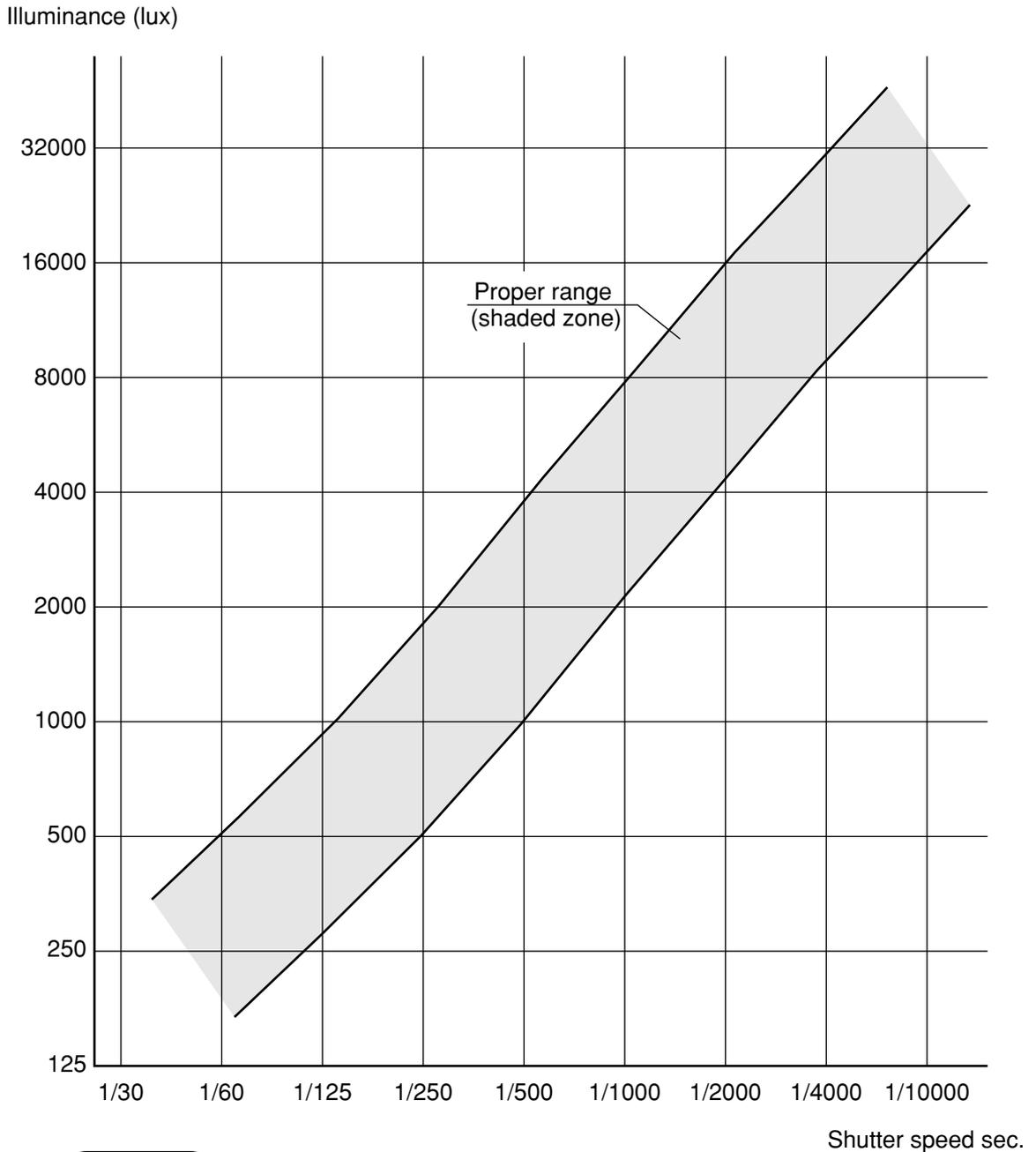


[2] Illuminance and shutter speed

The illuminance provided by the lighting equipment and the shutter speed must be set within the proper range.

- The following graph shows the relation between illuminance and shutter speed for the IV-S20L16 camera lens (focal length 16 mm) with an aperture setting of $f = 1.6$. Determine the proper amount of illuminance and the correct shutter speed, by referring to this graph. Adjust the aperture as necessary.
- To measure a moving object, or to increase the image processing speed, set the shutter speed to 1/1000 sec. or 1/2000 sec. or faster. However, an extremely high shutter speed will require intense lighting, thereby increasing the cost.

Relation between illuminance and shutter speed [IV-S20L16 camera lens (focal length 16 mm) with an aperture setting of $f = 1.6$]



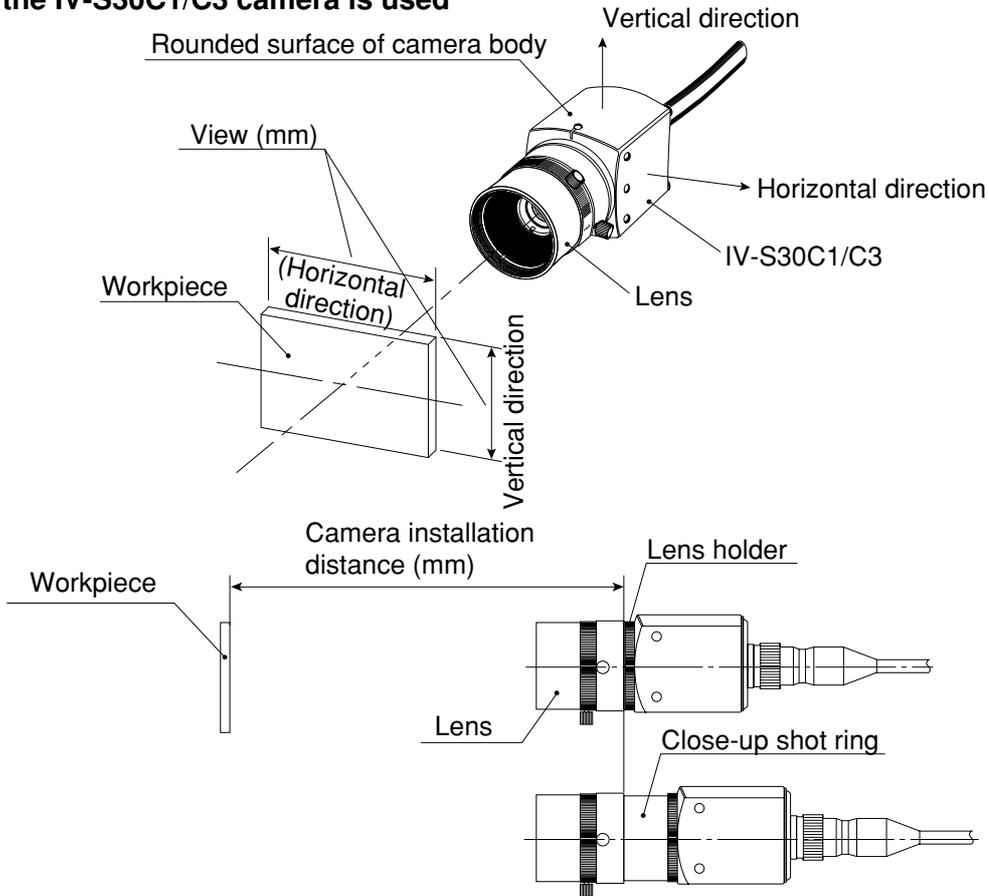
Note

- The standard relationship between illuminance and shutter speed is given above for reference. When actually installing the equipment, make sure the proper combination is used for the actual system.

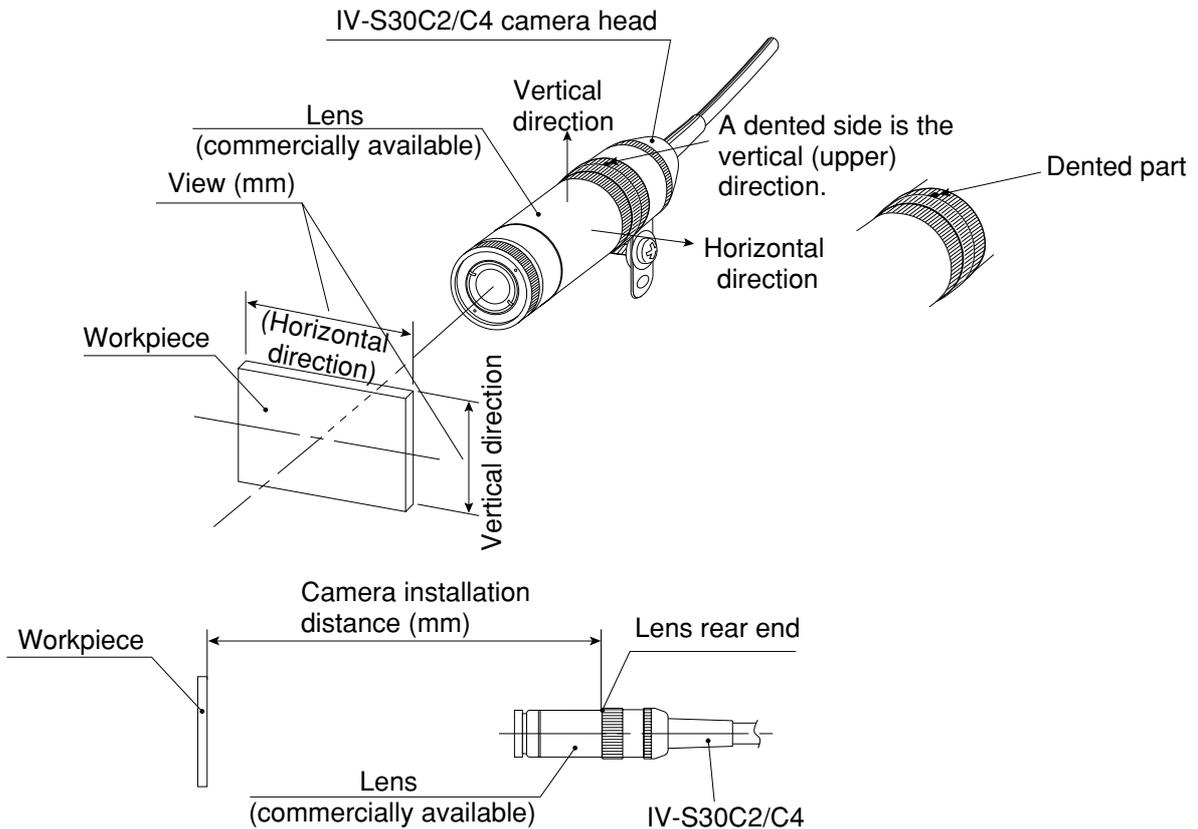
[3] Optimum lens and resolution

The optimum lens for your system can be selected, based on the camera installation distance and the field of view (workpiece size).

• **When the IV-S30C1/C3 camera is used**



• **When the IV-S30C2/C4 camera is used**



5

There is a relationships as shown on page 5-7 to page 5-9, among the camera installation distance, the field of view (in the vertical/horizontal direction), the lens focal length f , the aperture setting, the focal length, and the resolution.

[Example]

When the IV-S30C1/C3 camera is used, the camera installation distance is 500 mm, and the field of view (in the horizontal direction) is 110 mm, the optimum lens can be selected as described in the following procedure. The required information is taken from the table on page 5-7.

Camera installation distance (mm)	Lens focal length $f=16\text{mm}$			
	View (mm)		Focal length (mm)	Resolution (μm)
	Vertical	Horizontal		
450	96.3	102.8	16.6	200.7
500	107.4	114.6	16.5	223.9
600	129.6	138.3	16.4	270.1

① **Selecting the lens focal length f**

Follow the line for a camera installation distance of 500 mm for the view (in the horizontal direction) that is closest to 110 mm, which is 114.6 mm. A 114.6 mm field of view is shown in the column for a lens focal length f , of 16 mm. Therefore, a lens with focal length of 16 mm is considered to be optimum.

② **Considering the focal length**

The actual focal length, 16.5 mm, is longer than the lens focal length, $f = 16$ mm, by 0.5 mm. However, if the camera installation distance of 500 mm is within the focal range (distance from an object) of the actual lens ($f = 16$ mm), you can use it.

1. The focus range of the IV-S20L16 camera lens ($f = 16$ mm) built into the controller is from 50 mm to infinity. Therefore, the camera installation distance of 500 mm is within the focal range, and the IV-S20L16 lens can be used.
2. When another lens (with a focal range of 16 mm) is used, if its focal range exceeds 500 mm, install a commercially available C mount close-up shot ring. Use a ring that is 0.5 mm thick ($16.5 - 16 = 0.5$ mm).

③ **Resolution**

When the displayed image fills the whole monitor screen, and the view (in the horizontal direction) is 114.6 mm wide, the resolution is 223.9 μm .

$$\frac{114.6\text{mm}}{512(\text{pixelcount})} \doteq 223.9 \mu\text{m}$$

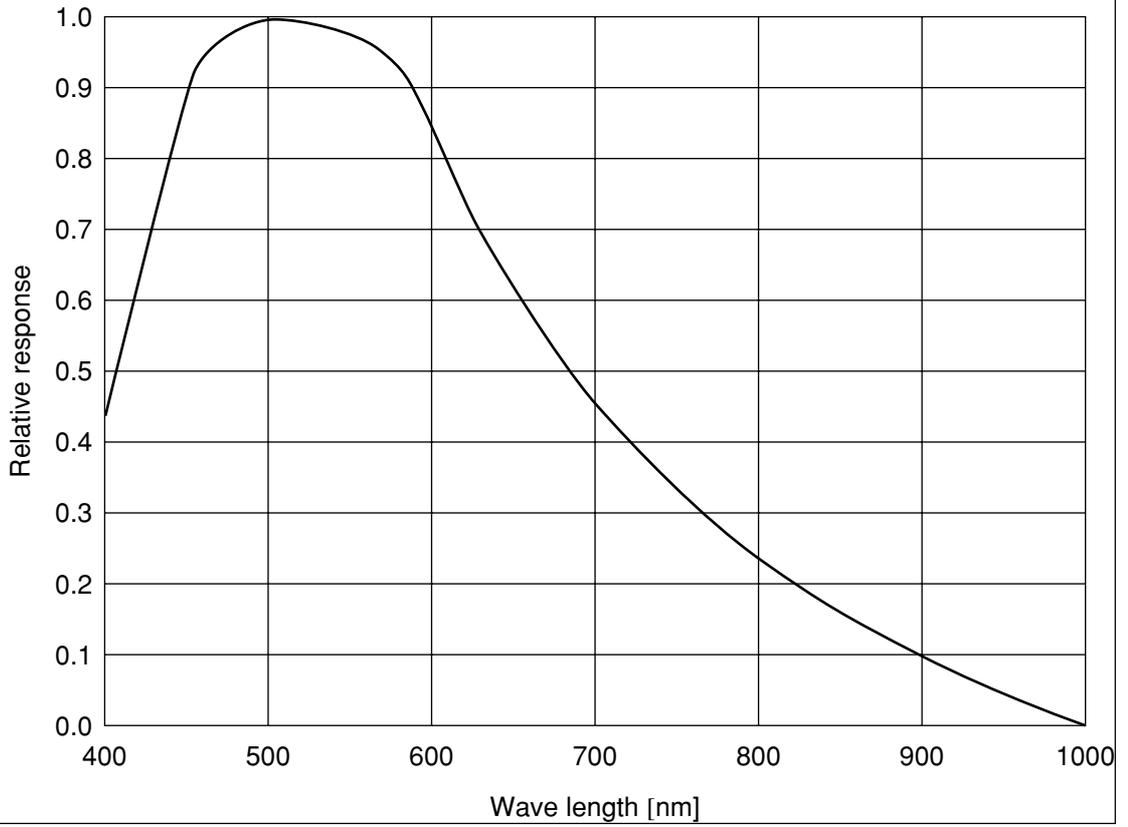
See "Glossary" for the definition of resolution.

Notes

- The values shown in the tables on page 5-7 to 5-9 are only reference data for installation. These values may vary, according to the characteristics of lenses you are using. When using any lens, check the data using the actual equipment.
- When the IV-S30C1/C3 camera is used.
 - If you want to use a camera lens other than the IV-S20L16, buy a lens with a C type lens base. (The IV-S20L16 has a C type lens base.)
 - A lens with too short focal length ($f = 4.2$ mm or 8 mm) will distort the edges of the field of view.
- When the IV-S30C2/C4 camera is used
 - Use a commercially available $\varnothing 17$ mm lens.
 - When a wide-angle lens is used, the distortion at the edges will be larger.

The spectral sensitivity characteristics of the CCD element used in the CCD camera are listed below.

- Spectral sensitivity characteristics of the CCD element



5

■ Relation among the camera installation distance, the field of view, and the focal length

• When the IV-S30C1/C3 camera is used

Camera installation distance (mm)	Lens focal length f=4.2mm				Lens focal length f=8mm				Lens focal length f=16mm				Lens focal length f=25mm			
	View (mm)		Focal length (mm)	Resolution (μm)	View (mm)		Focal length (mm)	Resolution (μm)	View (mm)		Focal length (mm)	Resolution (μm)	View (mm)		Focal length (mm)	Resolution (μm)
	Vertical	Horizontal			Vertical	Horizontal			Vertical	Horizontal			Vertical	Horizontal		
	Vertical	Horizontal	Vertical	Horizontal	Vertical	Horizontal	Vertical	Horizontal	Vertical	Horizontal	Vertical	Horizontal	Vertical	Horizontal		
55	39.7	42.4	4.9	82.8	14.2	15.2	10.0	29.6	—	—	—	—	—	—	—	—
60	44.0	46.9	4.8	91.6	16.4	17.5	9.7	34.2	9.8	10.4	21.8	20.4	5.0	5.3	42.9	10.4
70	52.4	55.9	4.7	109.2	20.9	22.3	9.4	43.5	12.0	12.8	20.7	25.0	6.4	6.8	38.9	13.3
80	60.9	65.0	4.7	126.9	25.3	27.0	9.1	52.7	14.2	15.2	20.0	29.6	7.8	8.3	36.4	16.3
90	69.3	74.0	4.6	144.5	29.7	31.7	9.0	62.0	16.4	17.5	19.5	34.2	9.2	9.9	34.6	19.2
100	77.8	83.0	4.6	162.1	34.2	36.5	8.8	71.2	18.6	19.9	19.0	38.9	10.7	11.4	33.3	22.2
120	94.7	101.0	4.5	197.3	43.1	45.9	8.7	89.7	23.1	24.6	18.5	48.1	13.5	14.4	31.6	28.1
140	111.6	119.1	4.5	232.6	51.9	55.4	8.5	108.2	27.5	29.4	18.1	57.4	16.3	17.4	30.4	34.0
160	128.5	137.1	4.4	267.8	60.8	64.9	8.5	126.7	32.0	34.1	17.8	66.6	19.2	20.5	29.6	40.0
180	145.5	155.2	4.4	303.1	69.7	74.4	8.4	145.2	36.4	38.8	17.6	75.9	22.0	23.5	29.0	45.9
200	162.4	173.2	4.4	338.3	78.6	83.8	8.4	163.7	40.8	43.6	17.4	85.1	24.9	26.5	28.6	51.8
250	204.7	218.3	4.3	426.4	100.8	107.5	8.3	210.0	51.9	55.4	17.1	108.2	32.0	34.1	27.8	66.6
300	246.9	263.4	4.3	514.5	123.0	131.2	8.2	256.2	63.0	67.3	16.9	131.4	39.1	41.7	27.3	81.4
350	289.2	308.5	4.3	602.6	145.2	154.9	8.2	302.5	74.1	79.1	16.8	154.5	46.2	49.3	26.9	96.2
400	331.5	353.6	4.3	690.7	167.4	178.6	8.2	348.7	85.2	90.9	16.7	177.6	53.3	56.8	26.7	111.0
450	373.8	398.7	4.3	778.8	189.6	202.2	8.1	395.0	96.3	102.8	16.6	200.7	60.4	64.4	26.5	125.8
500	416.1	443.9	4.3	866.9	211.8	225.9	8.1	441.2	107.4	114.6	16.5	223.9	67.5	72.0	26.3	140.6
600	500.7	534.1	4.3	1043.1	256.2	273.3	8.1	533.8	129.6	138.3	16.4	270.1	81.7	87.1	26.1	170.2
700	585.2	624.3	4.2	1219.3	300.6	320.6	8.1	626.3	151.8	162.0	16.4	316.4	95.9	102.3	25.9	199.8
800	669.8	714.5	4.2	1395.5	345.0	368.0	8.1	718.8	174.0	185.7	16.3	362.6	110.1	117.5	25.8	229.4
900	754.4	804.7	4.2	1571.7	389.4	415.4	8.1	811.3	196.2	209.3	16.3	408.9	124.3	132.6	25.7	259.0
1000	838.9	894.9	4.2	1747.9	433.8	462.7	8.1	903.8	218.4	233.0	16.3	455.1	138.5	147.8	25.6	288.6
1100	923.5	985.1	4.2	1924.1	478.2	510.1	8.1	996.3	240.6	256.7	16.2	501.4	152.7	162.9	25.6	318.2
1200	1008.1	1075.4	4.2	2100.3	522.6	557.5	8.1	1088.8	262.8	280.4	16.2	547.6	166.9	178.1	25.5	347.8
1300	1092.7	1165.6	4.2	2276.5	567.0	604.8	8.1	1181.3	285.0	304.1	16.2	593.9	181.2	193.2	25.5	377.4
1400	1177.2	1255.8	4.2	2452.7	611.4	652.2	8.0	1273.8	307.2	327.7	16.2	640.1	195.4	208.4	25.5	407.0
1500	1261.8	1346.0	4.2	2628.9	655.8	699.5	8.0	1366.3	329.4	351.4	16.2	686.4	209.6	223.6	25.4	436.6
1600	1346.4	1436.2	4.2	2805.1	700.2	746.9	8.0	1458.8	351.6	375.1	16.2	732.6	223.8	238.7	25.4	466.2
1700	1430.9	1526.4	4.2	2981.3	744.6	794.3	8.0	1551.3	373.8	398.8	16.2	778.9	238.0	253.9	25.4	495.8
1800	1515.5	1616.6	4.2	3157.5	789.0	841.6	8.0	1643.8	396.0	422.5	16.1	825.1	252.2	269.0	25.4	525.4
1900	1600.1	1706.9	4.2	3333.7	833.4	889.0	8.0	1736.3	418.2	446.2	16.1	871.4	266.4	284.2	25.3	555.0
2000	1684.7	1797.1	4.2	3509.9	877.8	936.4	8.0	1828.8	440.4	469.8	16.1	917.6	280.6	299.3	25.3	584.6
2500	2107.5	2248.1	4.2	4390.9	1099.8	1173.2	8.0	2291.3	551.4	588.2	16.1	1148.9	351.6	375.1	25.3	732.6
3000	2530.4	2699.2	4.2	5271.9	1321.8	1410.0	8.0	2753.9	662.4	706.6	16.1	1380.2	422.7	450.9	25.2	880.6
3500	2953.2	3150.3	4.2	6152.9	1543.8	1646.8	8.0	3216.4	773.4	825.1	16.1	1611.4	493.7	526.7	25.2	1028.7
4000	3376.1	3601.4	4.2	7033.9	1765.8	1883.6	8.0	3678.9	884.4	943.5	16.1	1842.7	564.8	602.5	25.2	1176.7
4500	3798.9	4052.4	4.2	7914.9	1987.8	2120.4	8.0	4141.4	995.4	1061.9	16.1	2074.0	635.8	678.2	25.1	1324.7
5000	4221.8	4503.5	4.2	8795.9	2209.8	2357.2	8.0	4604.0	1106.4	1180.3	16.1	2305.2	706.8	754.0	25.1	1472.7
5500	4644.7	4954.6	4.2	9676.9	2431.8	2594.0	8.0	5066.5	1217.4	1298.7	16.0	2536.5	777.9	829.8	25.1	1620.7
6000	5067.5	5405.6	4.2	10557.9	2653.8	2830.9	8.0	5529.0	1328.4	1417.1	16.0	2767.7	848.9	905.6	25.1	1768.7
6500	5490.4	5856.7	4.2	11438.9	2875.8	3067.7	8.0	5991.5	1439.4	1535.5	16.0	2999.0	920.0	981.4	25.1	1916.7
7000	5913.2	6307.8	4.2	12319.9	3097.8	3304.5	8.0	6454.1	1550.4	1653.9	16.0	3230.3	991.0	1057.1	25.1	2064.7
7500	6336.1	6758.9	4.2	13200.9	3319.8	3541.3	8.0	6916.6	1661.4	1772.3	16.0	3461.5	1062.0	1132.9	25.1	2212.7

Connection and Installation Methods

Camera installation distance (mm)	Lens focal length f=35mm				Lens focal length f=50mm				Lens focal length f=75mm			
	View (mm)		Focal length	Resolution	View (mm)		Focal length	Resolution	View (mm)		Focal length	Resolution
	Vertical	Horizontal	(mm)	(μm)	Vertical	Horizontal	(mm)	(μm)	Vertical	Horizontal	(mm)	(μm)
55												
60	—	—	—	—								
70												
80	4.6	4.9	62.2	9.5								
90	5.6	6.0	57.3	11.6								
100	6.6	7.0	53.8	13.7								
120	8.6	9.2	49.4	18.0	3.3	3.6	103.2	7.0				
140	10.7	11.4	46.7	22.2	4.8	5.1	87.3	9.9				
160	12.7	13.5	44.8	26.4	6.2	6.6	78.7	12.9				
180	14.7	15.7	43.4	30.7	7.6	8.1	73.4	15.8				
200	16.7	17.9	42.4	34.9	9.0	9.6	69.7	18.8				
250	21.8	23.3	40.7	45.5	12.6	13.4	64.1	26.2				
300	26.9	28.7	39.6	56.0	16.1	17.2	61.0	33.6	8.8	9.3	105.4	18.3
350	32.0	34.1	38.9	66.6	19.7	21.0	59.0	41.0	11.1	11.9	98.9	23.2
400	37.0	39.5	38.4	77.2	23.2	24.8	57.6	48.4	13.5	14.4	94.7	28.1
450	42.1	44.9	38.0	87.7	26.8	28.6	56.6	55.8	15.9	16.9	91.8	33.1
500	47.2	50.3	37.6	98.3	30.3	32.4	55.9	63.2	18.2	19.5	89.6	38.0
600	57.3	61.2	37.2	119.5	37.4	39.9	54.7	78.0	23.0	24.5	86.6	47.9
700	67.5	72.0	36.8	140.6	44.5	47.5	54.0	92.8	27.7	29.6	84.6	57.7
800	77.6	82.8	36.6	161.8	51.6	55.1	53.4	107.6	32.4	34.6	83.2	67.6
900	87.8	93.6	36.4	182.9	58.8	62.7	53.0	122.4	37.2	39.7	82.2	77.5
1000	97.9	104.5	36.3	204.0	65.9	70.2	52.7	137.2	41.9	44.7	81.4	87.3
1100	108.1	115.3	36.2	225.2	73.0	77.8	52.4	152.0	46.6	49.8	80.7	97.2
1200	118.2	126.1	36.1	246.3	80.1	85.4	52.2	166.8	51.4	54.8	80.2	107.1
1300	128.4	136.9	36.0	267.5	87.2	93.0	52.0	181.6	56.1	59.9	79.7	116.9
1400	138.5	147.8	35.9	288.6	94.3	100.6	51.9	196.4	60.9	64.9	79.4	126.8
1500	148.7	158.6	35.8	309.8	101.4	108.1	51.8	211.2	65.6	70.0	79.1	136.7
1600	158.8	169.4	35.8	330.9	108.5	115.7	51.6	226.0	70.3	75.0	78.8	146.5
1700	169.0	180.2	35.7	352.0	115.6	123.3	51.5	240.8	75.1	80.1	78.5	156.4
1800	179.1	191.1	35.7	373.2	122.7	130.9	51.4	255.6	79.8	85.1	78.3	166.3
1900	189.3	201.9	35.7	394.3	129.8	138.5	51.4	270.4	84.5	90.2	78.2	176.1
2000	199.4	212.7	35.6	415.5	136.9	146.0	51.3	285.2	89.3	95.2	78.0	186.0
2500	250.2	266.9	35.5	521.2	172.4	183.9	51.0	359.2	113.0	120.5	77.4	235.3
3000	300.9	321.0	35.4	626.9	207.9	221.8	50.9	433.2	136.6	145.8	76.9	284.7
3500	351.6	375.1	35.4	732.6	243.5	259.7	50.7	507.2	160.3	171.0	76.7	334.0
4000	402.4	429.2	35.3	838.4	279.0	297.6	50.6	581.2	184.0	196.3	76.4	383.3
4500	453.1	483.4	35.3	944.1	314.5	335.5	50.6	655.2	207.7	221.5	76.3	432.7
5000	503.9	537.5	35.2	1049.8	350.0	373.4	50.5	729.2	231.4	246.8	76.2	482.0
5500	554.6	591.6	35.2	1155.5	385.5	411.3	50.5	803.2	255.0	272.1	76.0	531.3
6000	605.4	645.8	35.2	1261.2	421.1	449.1	50.4	877.2	278.7	297.3	76.0	580.7
6500	656.1	699.9	35.2	1367.0	456.6	487.0	50.4	951.2	302.4	322.6	75.9	630.0
7000	706.8	754.0	35.2	1472.7	492.1	524.9	50.4	1025.3	326.1	347.8	75.8	679.4
7500	757.6	808.1	35.2	1578.4	527.6	562.8	50.3	1099.3	349.8	373.1	75.8	728.7

• When the IV-S30C2/C4 camera is used

Camera installation distance (mm)	Lens focal length f=7.2mm				Lens focal length f=15mm				Lens focal length f=24 mm			
	Vertical direction	Vertical direction 7.50			Vertical direction	Vertical direction 15.00			Vertical direction	Vertical direction 24.00		
	Workpiece size (Hmm)	Workpiece size (Hmm)	Focal length (mm)	Resolution (μm)	Workpiece size (Hmm)	Workpiece size (Hmm)	Focal length (mm)	Resolution (μm)	Workpiece size (Hmm)	Workpiece size (Hmm)	Focal length (mm)	Resolution (μm)
55	18.7	20.0	9.0	39.0	—	—	—	—	—	—	—	—
60	21.1	22.5	8.8	43.9	8.8	9.3	18.2	18.3	4.1	4.4	30.9	8.6
70	25.8	27.5	8.6	53.8	11.1	11.9	17.6	23.2	5.6	6.0	29.1	11.7
80	30.5	32.6	8.4	63.6	13.5	14.4	17.1	28.1	7.1	7.6	28.0	14.8
90	35.3	37.6	8.3	73.5	15.9	16.9	16.8	33.1	8.6	9.2	27.3	17.9
100	40.0	42.7	8.2	83.4	18.2	19.5	16.6	38.0	10.1	10.7	26.8	21.0
120	49.5	52.8	8.1	103.1	23.0	24.5	16.2	47.9	13.0	13.9	26.2	27.1
140	59.0	62.9	8.0	122.8	27.7	29.6	16.0	57.7	16.0	17.1	25.8	33.3
160	68.4	73.0	7.9	142.6	32.4	34.6	15.9	67.6	18.9	20.2	25.5	39.5
180	77.9	83.1	7.9	162.3	37.2	39.7	15.8	77.5	21.9	23.4	25.3	45.6
200	87.4	93.2	7.8	182.0	41.9	44.7	15.7	87.3	24.9	26.5	25.1	51.8
250	111.1	118.5	7.8	231.4	53.8	57.3	15.5	112.0	32.3	34.4	24.9	67.2
300	134.7	143.7	7.7	280.7	65.6	70.0	15.4	136.7	39.7	42.3	24.7	82.6
350	158.4	169.0	7.7	330.1	77.4	82.6	15.4	161.3	47.1	50.2	24.6	98.1
400	182.1	194.2	7.7	379.4	89.3	95.2	15.3	186.0	54.5	58.1	24.5	113.5
450	205.8	219.5	7.6	428.7	101.1	107.9	15.3	210.7	61.9	66.0	24.5	128.9
500	229.5	244.8	7.6	478.1	113.0	120.5	15.3	235.3	69.3	73.9	24.4	144.3
600	276.8	295.3	7.6	576.7	136.6	145.8	15.2	284.7	84.1	89.7	24.3	175.1
700	324.2	345.8	7.6	675.4	160.3	171.0	15.2	334.0	98.9	105.5	24.3	206.0
800	371.5	396.3	7.6	774.1	184.0	196.3	15.2	383.3	113.7	121.2	24.3	236.8
900	418.9	446.8	7.6	872.8	207.7	221.5	15.1	432.7	128.5	137.0	24.2	267.6
1000	466.3	497.4	7.6	971.4	231.4	246.8	15.1	482.0	143.3	152.8	24.2	298.5
1100	513.6	547.9	7.6	1070.1	255.0	272.1	15.1	531.3	158.1	168.6	24.2	329.3
1200	561.0	598.4	7.6	1168.8	278.7	297.3	15.1	580.7	172.9	184.4	24.2	360.2
1300	608.3	648.9	7.5	1267.4	302.4	322.6	15.1	630.0	187.7	200.2	24.2	391.0
1400	655.7	699.4	7.5	1366.1	326.1	347.8	15.1	679.4	202.5	216.0	24.1	421.8
1500	703.1	750.0	7.5	1464.8	349.8	373.1	15.1	728.7	217.3	231.8	24.1	452.7
1600	750.4	800.5	7.5	1563.5	373.4	398.4	15.1	778.0	232.1	247.5	24.1	483.5
1700	797.8	851.0	7.5	1662.1	397.1	423.6	15.1	827.4	246.9	263.3	24.1	514.3
1800	845.1	901.5	7.5	1760.8	420.8	448.9	15.1	876.7	261.7	279.1	24.1	545.2
1900	892.5	952.0	7.5	1859.5	444.5	474.1	15.1	926.0	276.5	294.9	24.1	576.0
2000	939.9	1002.6	7.5	1958.1	468.2	499.4	15.1	975.4	291.3	310.7	24.1	606.8
2500	1176.7	1255.2	7.5	2451.5	586.6	625.7	15.0	1222.1	365.3	389.6	24.1	761.0
3000	1413.5	1507.8	7.5	2944.9	705.0	752.0	15.0	1468.7	439.3	468.6	24.1	915.2
3500	1650.3	1760.4	7.5	3438.2	823.4	878.3	15.0	1715.4	513.3	547.5	24.1	1069.4
4000	1887.1	2013.0	7.5	3931.6	941.8	1004.6	15.0	1962.1	587.3	626.4	24.0	1223.5
4500	2123.9	2265.6	7.5	4424.9	1060.2	1130.9	15.0	2208.8	661.3	705.4	24.0	1377.7
5000	2360.7	2518.2	7.5	4918.3	1178.6	1257.2	15.0	2455.4	735.3	784.3	24.0	1531.9
5500	2597.5	2770.8	7.5	5411.7	1297.0	1383.5	15.0	2702.1	809.3	863.3	24.0	1686.1
6000	2834.3	3023.4	7.5	5905.0	1415.4	1509.8	15.0	2948.8	883.3	942.2	24.0	1840.2
6500	3071.1	3276.0	7.5	6398.4	1533.8	1636.1	15.0	3195.5	957.3	1021.1	24.0	1994.4
7000	3307.9	3528.6	7.5	6891.7	1652.2	1762.4	15.0	3442.2	1031.3	1100.1	24.0	2148.6
7500	3544.7	3781.2	7.5	7385.1	1770.6	1888.7	15.0	3688.8	1105.3	1179.0	24.0	2302.8

■ Table of magnifications and viewing size

(Vertical size x Horizontal size x Diagonal size) mm

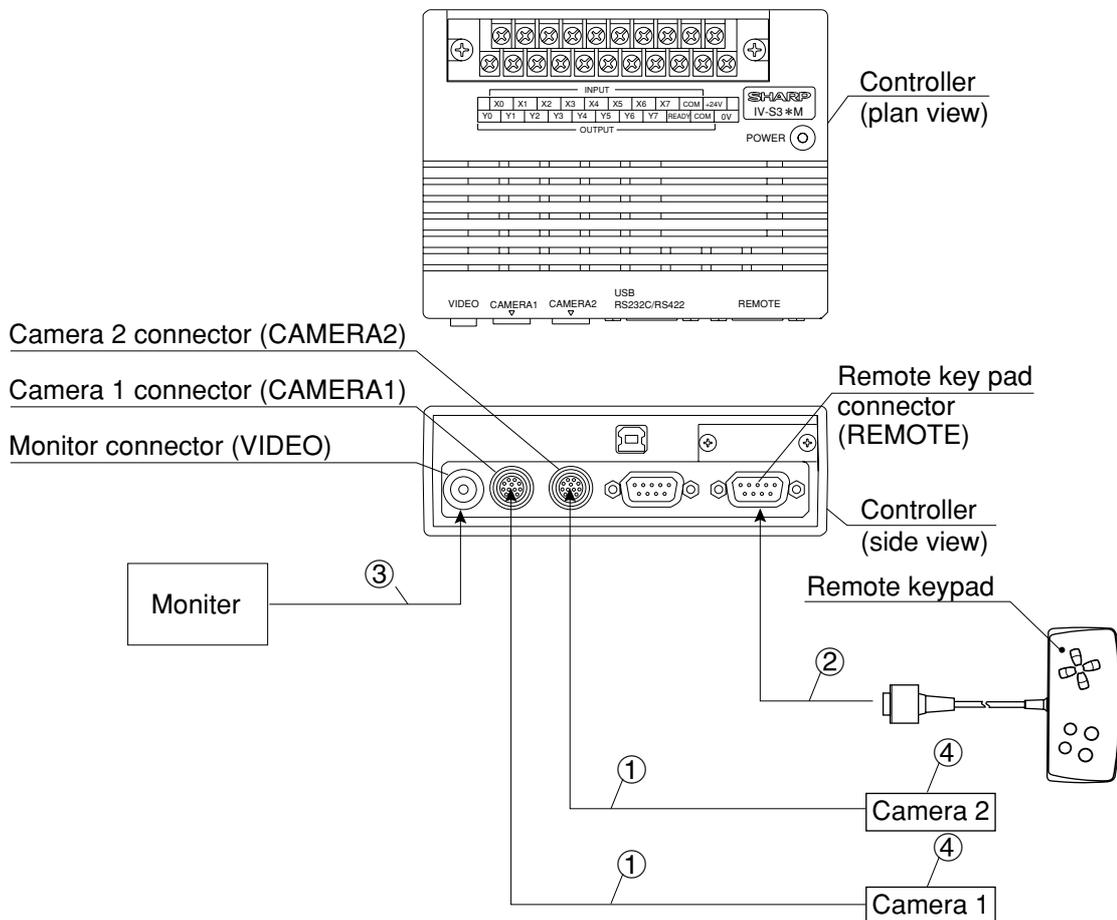
Magnification	1/3" viewing field	14" monitor magnification
×0.14	25×27×36.6	8.3
×0.16	22×23×32.2	9.4
×0.18	20×21×29.2	10.6
×0.2	18×19×26.3	11.8
×0.3	12×13×17.5	17.8
×0.5	7.2×7.7×10.53	29.6
×0.75	4.8×5.1×7.02	44.4
×0.8	4.5×4.8×6.58	47.4
×1	3.6×3.8×5.26	59.3
×2	1.8×1.9×2.63	118.6
×4	0.9×0.96×1.316	237.2
×4.5	0.8×0.85×1.170	266.8
×6	0.6×0.64×0.877	355.8
×8	0.45×0.48×0.658	474.4
×10	0.36×0.38×0.526	593
×12	0.3×0.32×0.439	711.6

5

5-2 Installing, connecting and wiring the IV-S31M/S32M/S33M controller

[1] Connecting equipment to the controller

Connect the cameras (up to 2 cameras), remote key pad, and monitor to the controller (IV-S31M/S32M/S33M).



- ① Connect the camera cable (IV-S30KC3/S30KC5/S30KC7) connector or a connector of the main housing connection cable (IV-S30EA1) to the camera 1 (CAMERA1) and camera 2 (CAMERA2) connectors on the controller.

Note: Only connect or disconnect the camera connectors while the power is OFF.

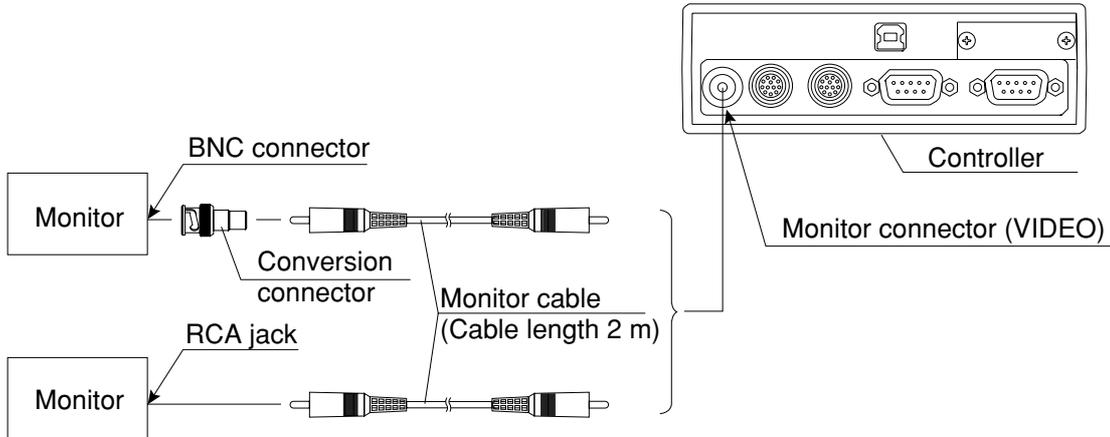
The main housing connection cable (IV-S30EA1) can be connected to the IV-S33M only.

- Push the convex side of the connector into the concave side of the mating connector. When the connector is all the way on, it clicks.
- To disconnect the connector, hold the plug of the connector, and pull it straight out.
- A camera connected to the camera 1 connector (CAMERA1) is treated as camera 1 by this system, and a camera connected to the camera 2 connector (CAMERA2) is treated as camera 2.
- You must have a camera connected to the camera 1 connector.

- ② Plug the remote key pad (IV-S30RK1) connector into the remote keypad connector (REMOTE) on the controller.

Connection and Installation Methods

- ③ Connect the monitor to the monitor connector (VIDEO: RCA jack) on the controller using the monitor cable (supplied with the controller) and a conversion connector (supplied with controller). If the monitor has an RCA jack, the conversion connector is not required.
- Use a monitor with either an EIA or NTSC compatible video input terminal.
 - Connect the cable to the monitor connector straight and treat it carefully.

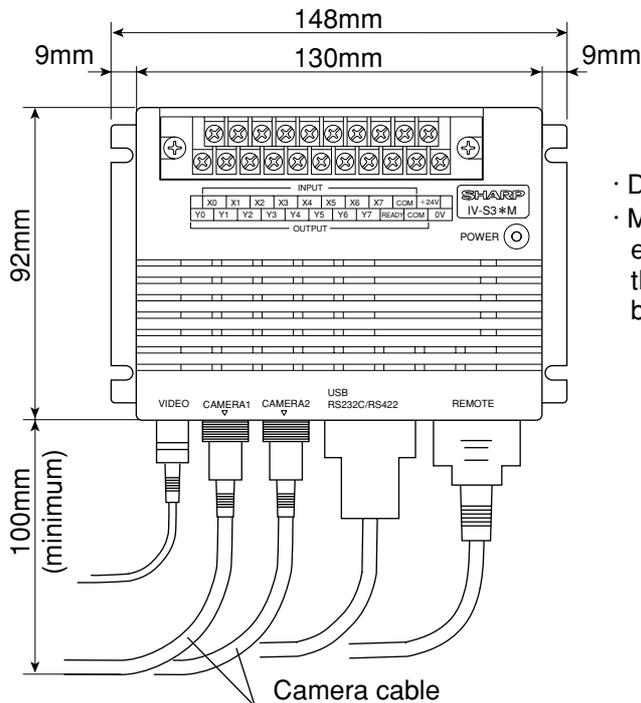


- If you need a monitor cable longer than 2 m, you can purchase a one at a video store.

- ④ For details about connecting and installing cameras, see page 5-23 in this manual.

■ Leave enough space around the controller (IV-S31M/S32M/S33M)

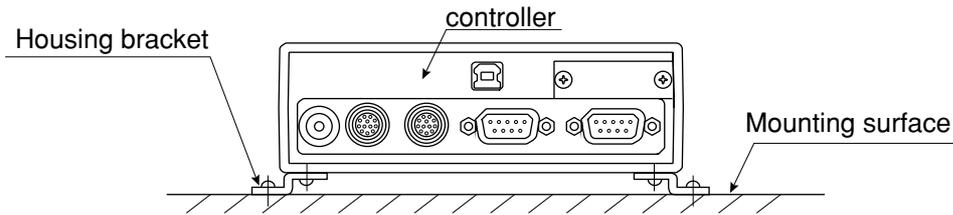
In order to connect camera cables, the remote key pad cable, monitor cable and D-sub connector to the controller, the following space (min.) is required.



- Do not bend the camera cables repeatedly.
- Make sure the installation location allows enough space for the input/output wires going to the I/O terminal block and the power terminal block on the controller.

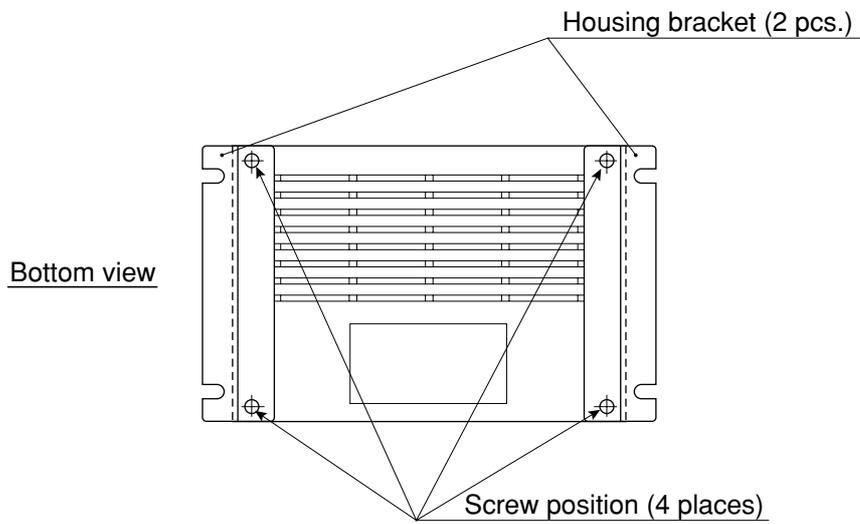
[2] Installation

To install the IV-S31M/S32M/S33M controller, secure the bottom of the housing on the mounting surface with the two main housing brackets (supplied with the controller.)

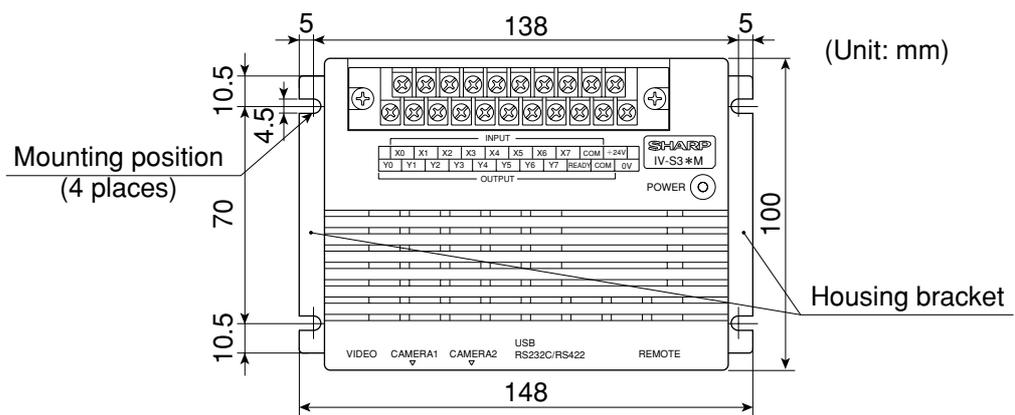


■ Mounting procedure

- ① Attach the two housing brackets on the bottom of the controller.
Four screws (M 3 x 6) are supplied to attach the brackets.



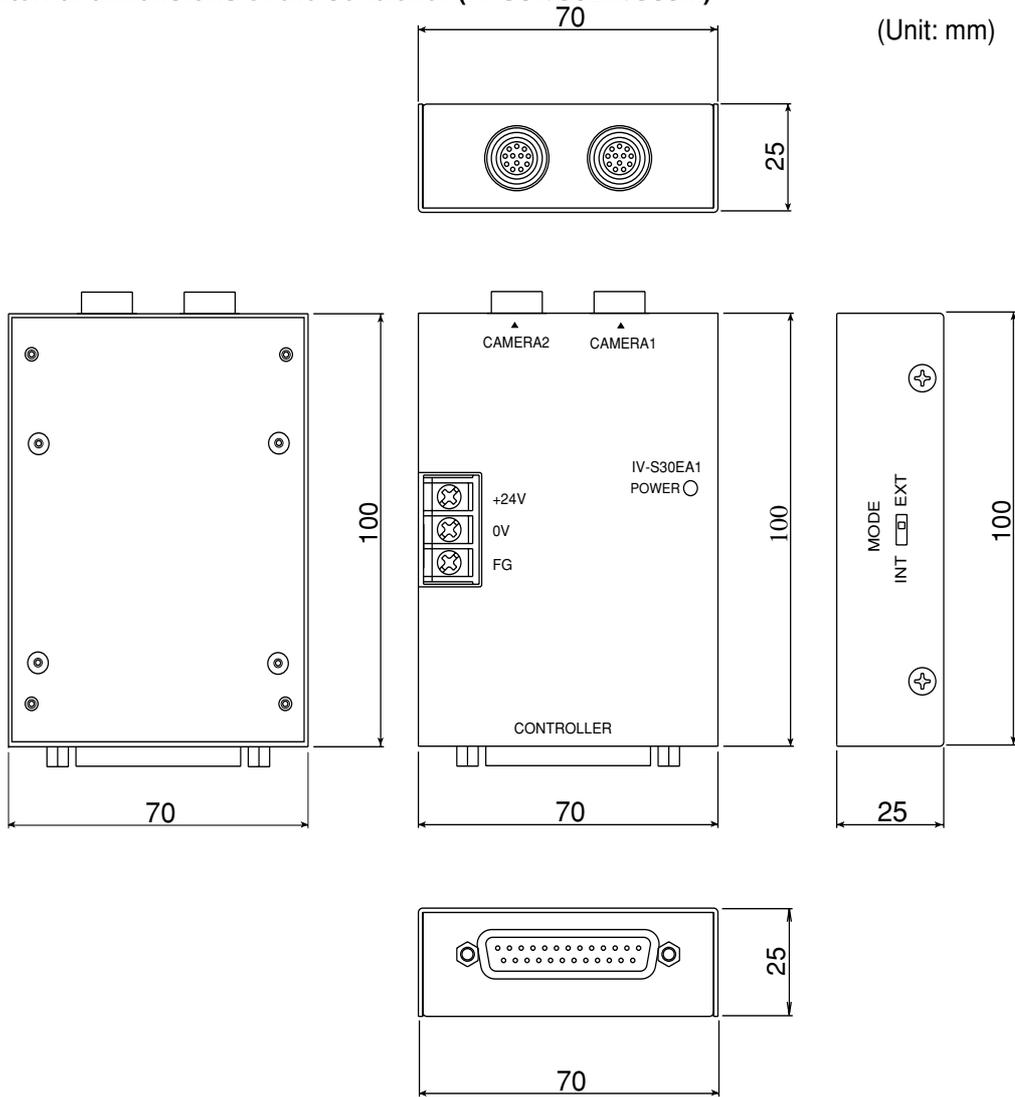
- ② Secure the housing on the mounting surface with the brackets.



The external dimensions of the housing brackets and the controller are shown on the following page.

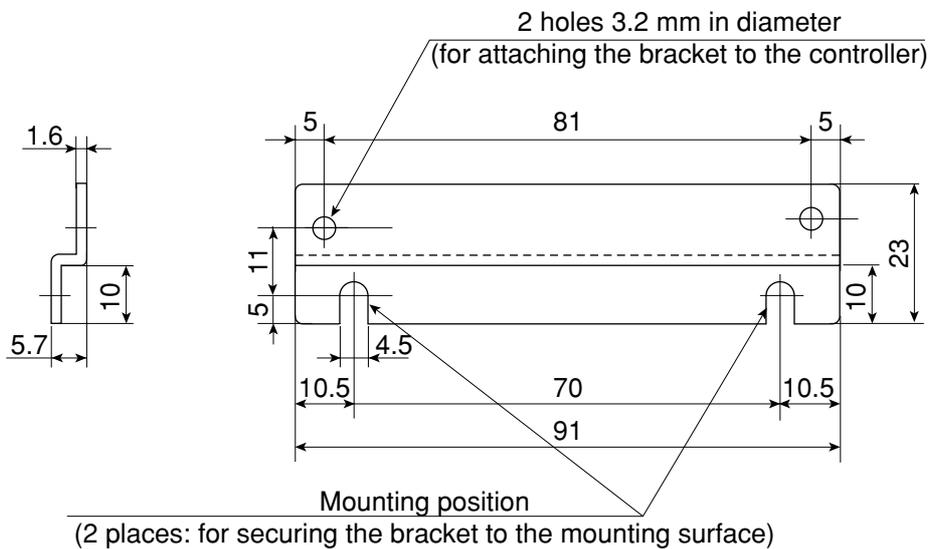
- External dimensions of the controller (IV-S31/S32M/S33M)

(Unit: mm)



- External dimensions of housing bracket

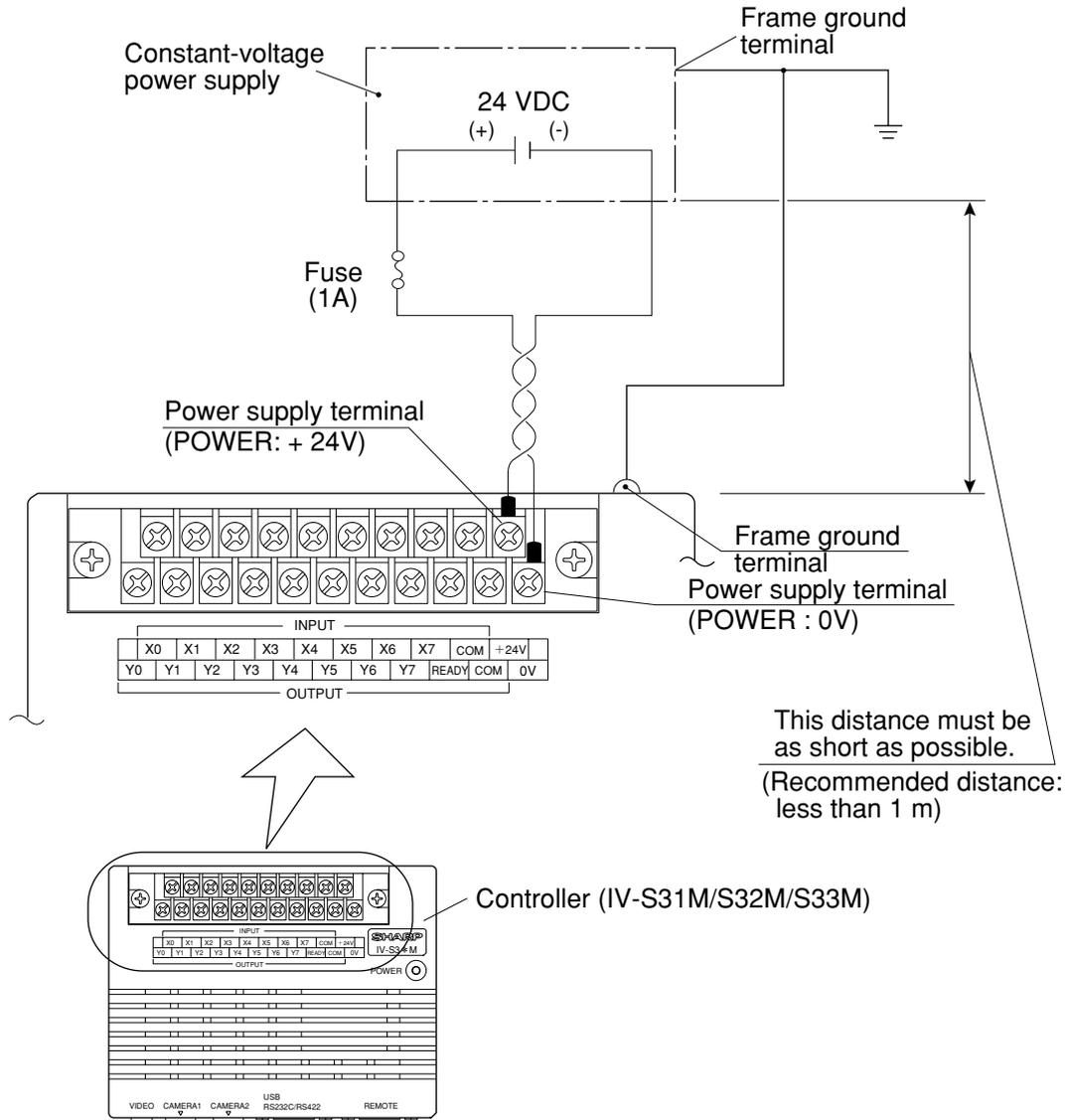
(Unit: mm)



[3] Connecting a power supply

Connect a commercially available constant-voltage power supply to the power terminals (POWER: +24 V, 0 V) on the controller (IV-S31M/S32M/S33M). Use a 24 VDC \pm 10%, 500 mA or more constant-voltage power supply.

- Use an individual power supply to supply power to the controller. If the power supply is used to power other equipment, measurement errors may occur.
- Check the polarity of the power supply terminals, +24 V and 0 V. If power is supplied with the polarity inverted, the controller may be damaged.
- Only connect or disconnect the camera cable and other equipment while the power is OFF.



5

Note

To improve the noise resistance of the constant-voltage power supply connected to the controller (IV-S31M/S32M/S33M), observe the following precautions.

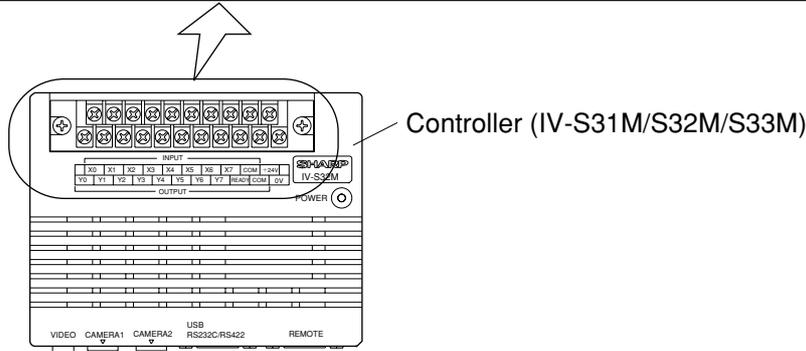
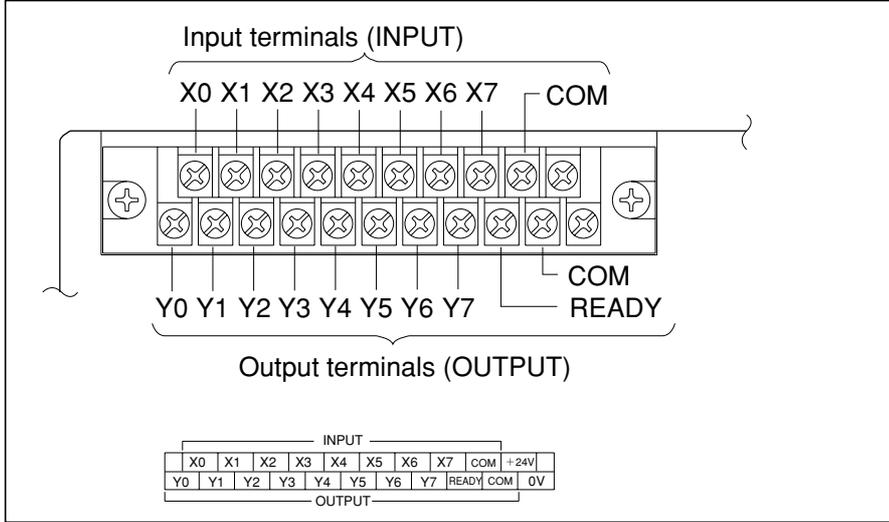
- Ground the FG terminal of the constant-voltage power supply according to the class 3 grounding.
- The power line between the controller and the constant-voltage power supply must be as short as possible. (Recommended distance: less than 1 m)
Do not run the power supply line near any noise generating sources, such as electric motor lines.
- Use twisted-pair wire for the power supply line.

[4] Connecting to the input/output terminals (parallel I/F)

8 input terminals and 9 output terminals are available on the input/output terminal block on the controller (IV-S31M/S32M/S33M).

The input terminal block has INPUT terminals X0 to X7 and COM , and the output terminal block has OUTPUT terminals Y0 to Y7, READY and COM .

[Input/output terminal block on the controller]



Terminal block	Interrupt processing input (1 terminal)	External trigger (X0)
	Input (7 terminals)	-IV-S33M Object type change (X1 to 6): 6 terminals External input (X7): 1 terminals -IV-S32M Object type change (X1 to 5): 5 terminals External input (X6 and 7): 2 terminals -IV-S31M Object type change (X1 to 4): 4 terminals External input (X5 to 7): 3 terminals
	Common for input (1 terminal)	(+) or (-) cocmmon
	Output (9 terminals)	READY: 1 terminal Logical output set by user (Y0 to 7): 8 terminals
	Common for output (1 terminal)	(+) or (-)
	Power supply (2 terminals)	24 VDC: 1 terminal, 0 V: 1 terminal

(1) Input terminals (INPUT) X0 to X7

① IV-S31M/S32M

Input terminal	Input/output condition setting *1	Input details
X0	Measurement start input I/F = CCD trigger CCD sampling start = General-purpose serial interface signal or auto detect (edge + level)	External input
	Measurement start input I/F = Parallel + General-purpose serial interface signal + USB	Measurement start input
	Measurement start input I/F = CCD trigger CCD sampling start = Parallel	
X1 to 5	Measurement start input I/F = CCD trigger CCD sampling start = General-purpose serial interface signal or auto detect (edge + level)	External input
	Measurement start input I/F = Parallel + General-purpose serial + USB	Object type numbers *2 IV-S32M:0 to 31 IV-S31M:0 to 15 - X5 is used for external input on the IV-S31M
	Measurement start input I/F = CCD trigger CCD sampling start = Parallel	
X6	Parallel input X6 is used for external input, a register reference image signal, or to correct a total area judgement.	
X7	Parallel input X7 is used for external input, a change in the output camera signal, measurements with each camera, and for overlapping images.	

*1: For details about the settings on the [I/O CONDITIONS] menu, see "Setting the Input/Output Conditions" in the IV-S30 (IV-S31M/S32M) User's Manual (Function and operation).

*2: Object type numbers and X1 to X5 have the following relationships.

• IV-S32M

Object type	X5	X4	X3	X2	X1	Object type	X5	X4	X3	X2	X1
00	OFF	OFF	OFF	OFF	OFF	16	ON	OFF	OFF	OFF	OFF
01	OFF	OFF	OFF	OFF	ON	17	ON	OFF	OFF	OFF	ON
02	OFF	OFF	OFF	ON	OFF	18	ON	OFF	OFF	ON	OFF
03	OFF	OFF	OFF	ON	ON	19	ON	OFF	OFF	ON	ON
04	OFF	OFF	ON	OFF	OFF	20	ON	OFF	ON	OFF	OFF
05	OFF	OFF	ON	OFF	ON	21	ON	OFF	ON	OFF	ON
06	OFF	OFF	ON	ON	OFF	22	ON	OFF	ON	ON	OFF
07	OFF	OFF	ON	ON	ON	23	ON	OFF	ON	ON	ON
08	OFF	ON	OFF	OFF	OFF	24	ON	ON	OFF	OFF	OFF
09	OFF	ON	OFF	OFF	ON	25	ON	ON	OFF	OFF	ON
10	OFF	ON	OFF	ON	OFF	26	ON	ON	OFF	ON	OFF
11	OFF	ON	OFF	ON	ON	27	ON	ON	OFF	ON	ON
12	OFF	ON	ON	OFF	OFF	28	ON	ON	ON	OFF	OFF
13	OFF	ON	ON	OFF	ON	29	ON	ON	ON	OFF	ON
14	OFF	ON	ON	ON	OFF	30	ON	ON	ON	ON	OFF
15	OFF	ON	ON	ON	ON	31	ON	ON	ON	ON	ON

• IV-S31M

Object type	X4	X3	X2	X1	Object type	X4	X3	X2	X1
0	OFF	OFF	OFF	OFF	8	ON	OFF	OFF	OFF
1	OFF	OFF	OFF	ON	9	ON	OFF	OFF	ON
2	OFF	OFF	ON	OFF	10	ON	OFF	ON	OFF
3	OFF	OFF	ON	ON	11	ON	OFF	ON	ON
4	OFF	ON	OFF	OFF	12	ON	ON	OFF	OFF
5	OFF	ON	OFF	ON	13	ON	ON	OFF	ON
6	OFF	ON	ON	OFF	14	ON	ON	ON	OFF
7	OFF	ON	ON	ON	15	ON	ON	ON	ON

Connection and Installation Methods

② IV-S33M

Input terminal	Input/output condition setting *1	Input details
X0	Measurement start input I/F = CCD trigger CCD sampling start = General-purpose serial interface signal or auto detect (edge + level)	External input
	Measurement start input I/F = Parallel + General-purpose serial interface signal + USB	Measurement start input
	Measurement start input I/F = CCD trigger CCD sampling start = Parallel	
X1 to 5	Measurement start input I/F = CCD trigger CCD sampling start = General-purpose serial interface signal or auto detect (edge + level)	External input
	Measurement start input I/F = Parallel + General-purpose serial + USB	Object type numbers *2 IV-S33M:0 to 63
	Measurement start input I/F = CCD trigger CCD sampling start = Parallel	
X6	Parallel input X6 is select one of 64 object types.	
	Parallel input X6 is used for external input, a register reference image signal, or to correct a total area judgement.	
X7	Parallel input X7 is used for external input, a change in the output camera signal, measurements with each camera, and for overlapping images.	

*1: For details about the settings on the [I/O CONDITIONS] menu, see "Setting the Input/Output Conditions" in the IV-S30 (IV-S31M/S32M/S33M) User's Manual, Function and Operation.

*2: Object type numbers and X1 to X6 have the following relationships.

Object type	X6	X5	X4	X3	X2	X1	Object type	X6	X5	X4	X3	X2	X1
00	OFF	OFF	OFF	OFF	OFF	OFF	32	ON	OFF	OFF	OFF	OFF	OFF
01	OFF	OFF	OFF	OFF	OFF	ON	33	ON	OFF	OFF	OFF	OFF	ON
02	OFF	OFF	OFF	OFF	ON	OFF	34	ON	OFF	OFF	OFF	ON	OFF
03	OFF	OFF	OFF	OFF	ON	ON	35	ON	OFF	OFF	OFF	ON	ON
04	OFF	OFF	OFF	ON	OFF	OFF	36	ON	OFF	OFF	ON	OFF	OFF
05	OFF	OFF	OFF	ON	OFF	ON	37	ON	OFF	OFF	ON	OFF	ON
06	OFF	OFF	OFF	ON	ON	OFF	38	ON	OFF	OFF	ON	ON	OFF
07	OFF	OFF	OFF	ON	ON	ON	39	ON	OFF	OFF	ON	ON	ON
08	OFF	OFF	ON	OFF	OFF	OFF	40	ON	OFF	ON	OFF	OFF	OFF
09	OFF	OFF	ON	OFF	OFF	ON	41	ON	OFF	ON	OFF	OFF	ON
10	OFF	OFF	ON	OFF	ON	OFF	42	ON	OFF	ON	OFF	ON	OFF
11	OFF	OFF	ON	OFF	ON	ON	43	ON	OFF	ON	OFF	ON	ON
12	OFF	OFF	ON	ON	OFF	OFF	44	ON	OFF	ON	ON	OFF	OFF
13	OFF	OFF	ON	ON	OFF	ON	45	ON	OFF	ON	ON	OFF	ON
14	OFF	OFF	ON	ON	ON	OFF	46	ON	OFF	ON	ON	ON	OFF
15	OFF	OFF	ON	ON	ON	ON	47	ON	OFF	ON	ON	ON	ON
16	OFF	ON	OFF	OFF	OFF	OFF	48	ON	ON	OFF	OFF	OFF	OFF
17	OFF	ON	OFF	OFF	OFF	ON	49	ON	ON	OFF	OFF	OFF	ON
18	OFF	ON	OFF	OFF	ON	OFF	50	ON	ON	OFF	OFF	ON	OFF
19	OFF	ON	OFF	OFF	ON	ON	51	ON	ON	OFF	OFF	ON	ON
20	OFF	ON	OFF	ON	OFF	OFF	52	ON	ON	OFF	ON	OFF	OFF
21	OFF	ON	OFF	ON	OFF	ON	53	ON	ON	OFF	ON	OFF	ON
22	OFF	ON	OFF	ON	ON	OFF	54	ON	ON	OFF	ON	ON	OFF
23	OFF	ON	OFF	ON	ON	ON	55	ON	ON	OFF	ON	ON	ON
24	OFF	ON	ON	OFF	OFF	OFF	56	ON	ON	ON	OFF	OFF	OFF
25	OFF	ON	ON	OFF	OFF	ON	57	ON	ON	ON	OFF	OFF	ON
26	OFF	ON	ON	OFF	ON	OFF	58	ON	ON	ON	OFF	ON	OFF
27	OFF	ON	ON	OFF	ON	ON	59	ON	ON	ON	OFF	ON	ON
28	OFF	ON	ON	ON	OFF	OFF	60	ON	ON	ON	ON	OFF	OFF
29	OFF	ON	ON	ON	OFF	ON	61	ON	ON	ON	ON	OFF	ON
30	OFF	ON	ON	ON	ON	OFF	62	ON	ON	ON	ON	ON	OFF
31	OFF	ON	ON	ON	ON	ON	63	ON	ON	ON	ON	ON	ON

- When the parallel input X6 is not set to "64OBJ-CHG (select from 64 object types)," only X1 to X5 are available to specify one of 32 object types.

(2) Output terminals (OUTPUT) Y0 to Y7 and READY

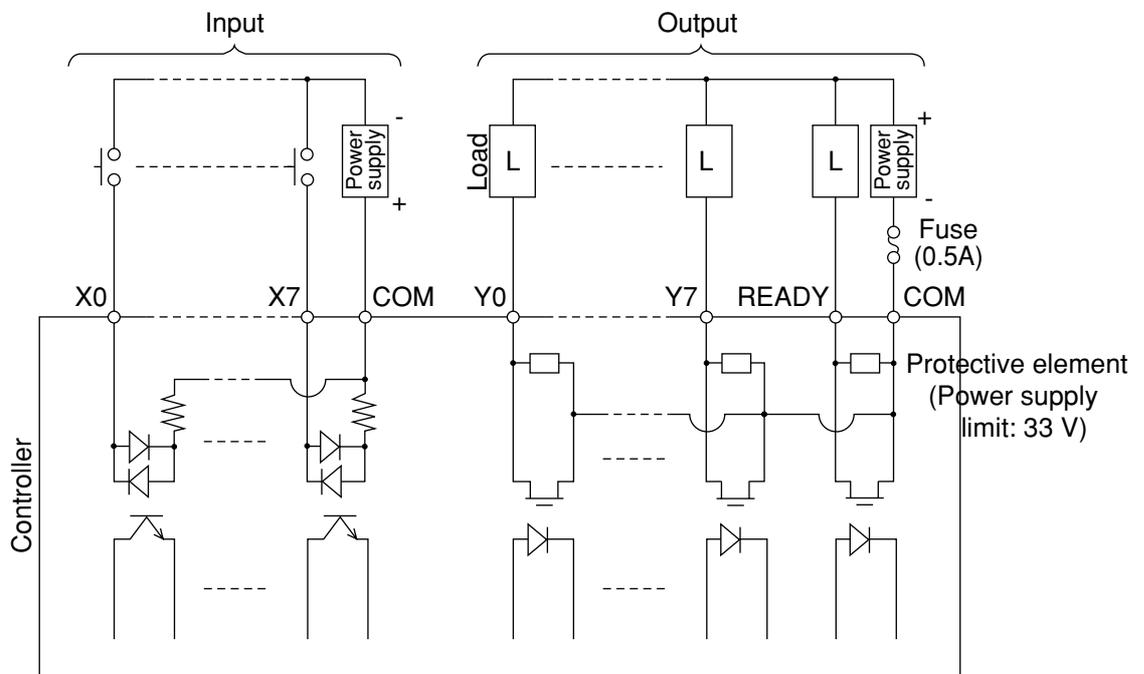
Y0 to Y7	Result of logical calculation output - Specify in the FINAL-OUTPUT on the [TYPE MEAS COND] menu.
READY	These signals will turn ON when the measurement start input is enabled. - For information about the timing chart and other details, see "Setting the Input/Output Conditions" in the IV-S30 User's Manual (Function and Operation).

(3) I/O port

The input/output terminals are isolated by photocouplers, to prevent malfunctions due to noise. Use them within the rated range. The specifications of the input/output ports are listed below.

Item		Rating
Input	Rated input voltage	12/24 VDC
	Input voltage range	10.5 to 26.4 VDC
	Input voltage level	ON: 10.5 V or less OFF: 3 V or more
	Input current level	ON: 3 mA or less OFF: 0.9 mA or more
	Input impedance	3.3 k ohm
Output	Rated output voltage	12/24 VDC
	Load voltage range	10.5 to 27 VDC
	Rated max. output current	100 mA DC
	Output type	Photo MOS open drain
	ON resistance	30 ohms or less
	Isolation method	Photo MOS isolation
Response time		3 ms or less (OFF to ON, ON to OFF)

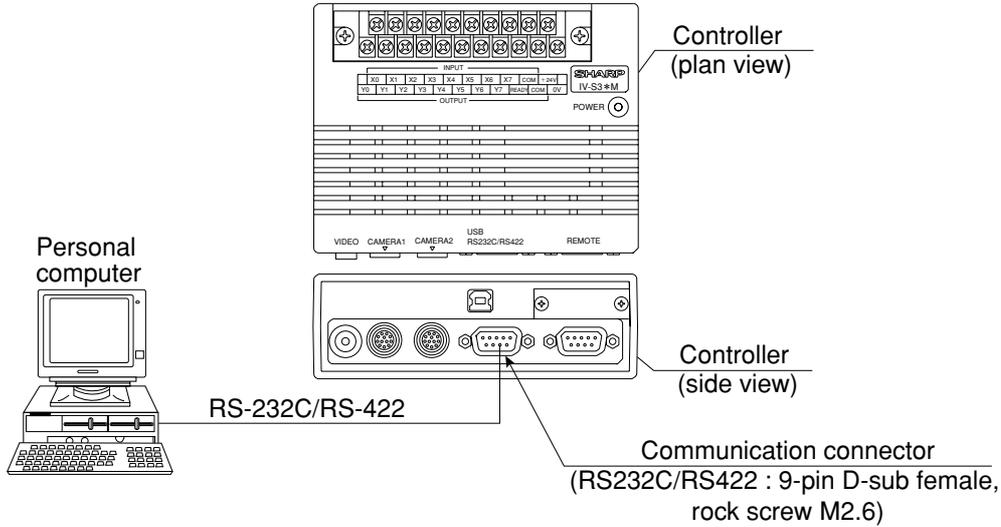
(4) Wiring to the controller (IV-S31M/S32M/S33M)



[5] Connection for communications with personal computer (general purpose serial I/F)

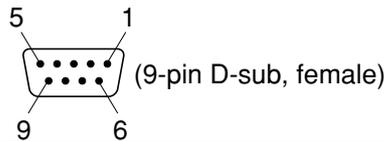
Connect a personal computer to the communication connector (RS232C/RS422) on the controller (IV-S31M/S32M/S33M).

A 9-pin D-sub, male connector is included with the controller.

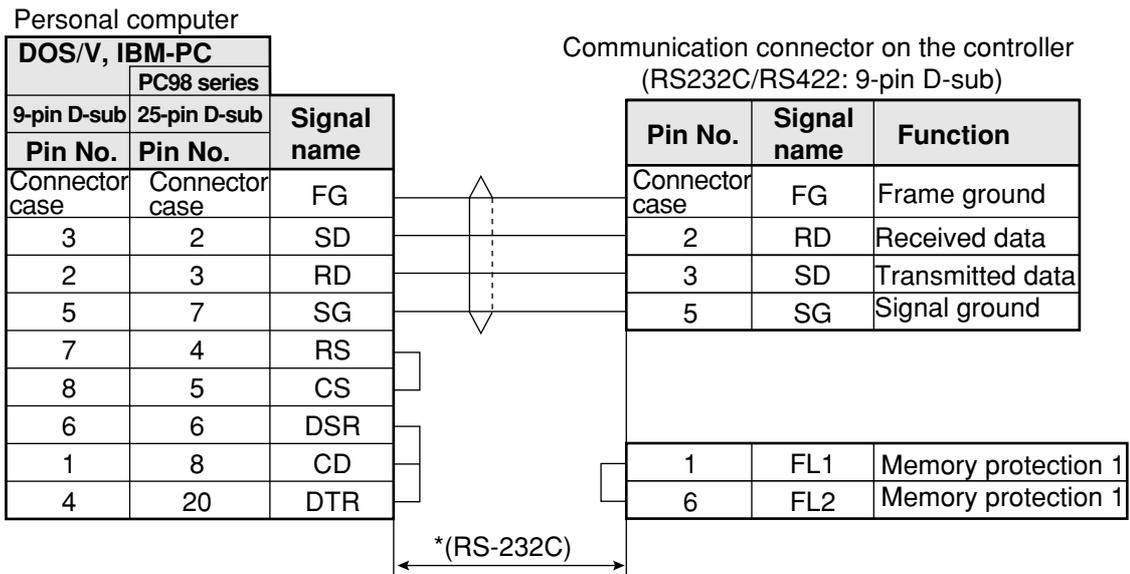


(1) When communicating through the RS-232C port

- The controller pin arrangement of the communication connector (for RS-232C)



Communication standard	Pin No.	Signal name	Details	Direction
RS-232C	2	RD	Received data (personal computer ⇄ IV-S30)	Input
	3	SD	Transmitted data (IV-S30 ⇄ personal computer)	Output
	5	SG	Signal ground	—
Connector shield		FG	Frame ground	—



*The maximum length of the communication cable depends on the communication speed.

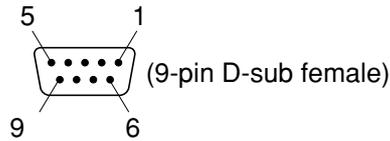
Communication speed (kbps)	Cable length
9.6, 19.2	15 m or less
38.4, 57.6, 115.2	2 to 3 m

- Conduct a communication test before using the devices for measurements.

(2) When communicating through the RS-422

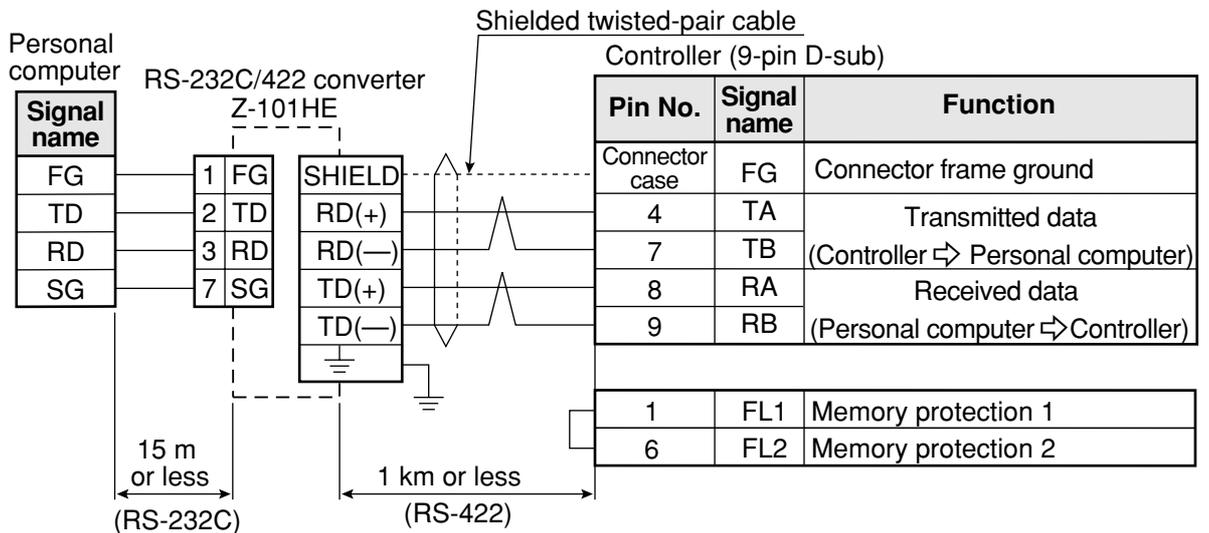
Specify the 4-wire or 2-wire RS-422 system on the [SET COMM PARMS] menu.

- The controller pin arrangement of the communication connector (for RS-422C)

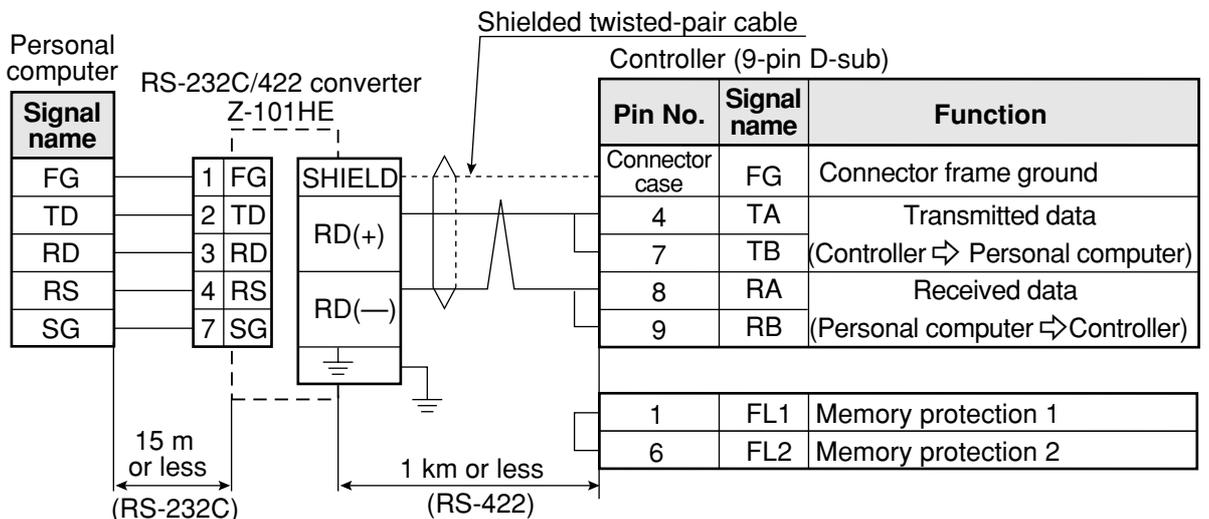


Communication standard	Pin No.	Signal name	Details	Direction
RS-422	4	TA	Transmitted data (Controller ⇄ Personal computer)	Output
	7	TB		
	8	RA	Received data (Personal computer ⇄ Controller)	Input
	9	RB		
Connector field		FG	Frame ground	—

① 4-wire system

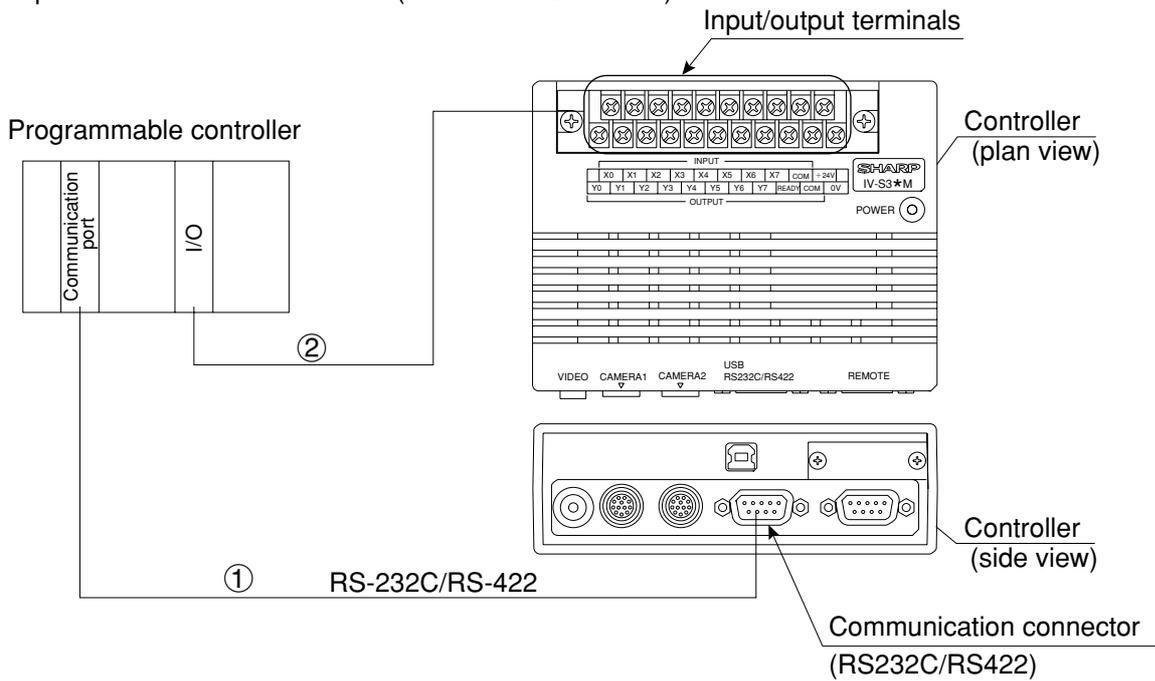


② 2-wire system



[6] Connecting a programmable controller using the computer link function

Connect a programmable controller to the communication connector (RS232C/RS422) and the input/output terminals on the controller (IV-S31M/S32M/S33M).



- ① Connect the computer link connector (RS-232C/RS-411) of a programmable controller to the communication connector (RS232C/RS422: 9-pin D-sub, female) on the controller.
 - See "Computer Link" in the IV-S30 User's Manual (Function and Operation). (The pin arrangement of the communication connector on the controller is shown on page 5-20 to 5-21.)
 - In the case of RS-232C, the maximum communication cable length depends on the communication speed.

Communication speed	Cable length
9.6, 19.2	15 m or less
38.4, 57.6, 115.2	2 to 3 m

Conduct a communication test before using the devices for measurements.

- ② Connect the input/output terminals of the programmable controller to the input/output terminals on the controller.
 - See item [4] "Connecting to the input/output terminals (parallel I/F)" for details about wiring procedure.

5-3 Installing and connecting the IV-S30C1/C2/C3/C4 camera

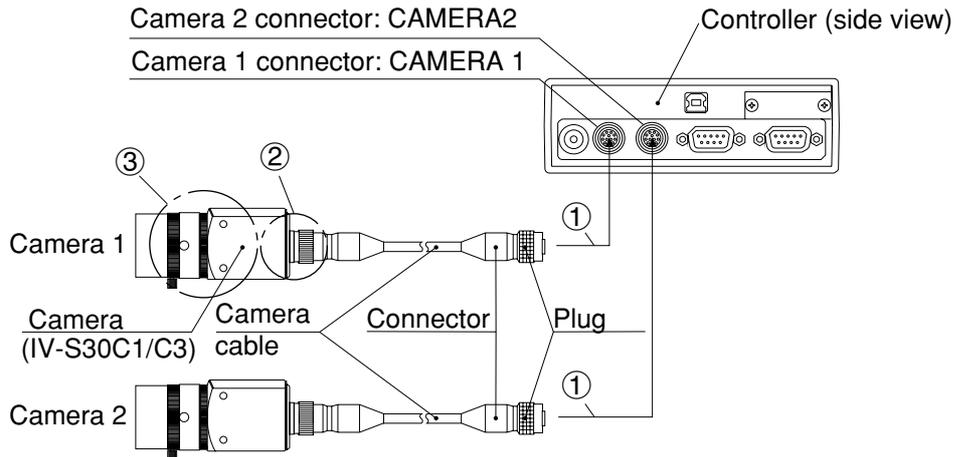
[1] Installing and connecting the IV-S30C1/C3

(1) Connections

Up to two IV-S30C1 standard cameras or IV-S30C3 high-speed cameras can be connected to the following controllers using camera cables.

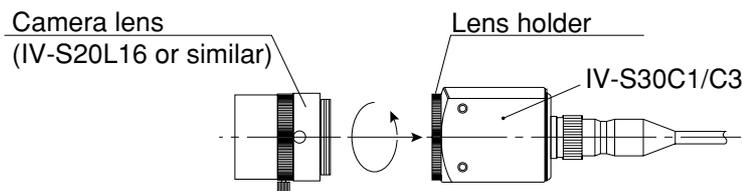
Camera	Controller to connect	Cables to be used
IV-S30C1	IV-S31M, IV-S32M, IV-S33M	IV-S30KC3 (3 m), IV-S30KC5 (5 m), IV-S30KC7 (7 m),
IV-S30C3	IV-S33M	IV-S30KC3 (3 m), IV-S30KC5 (5 m)

Note 1: Do not connect the IV-S30C3 to the IV-S31M/S32M. The IV-S30C3 cannot be used with the IV-S30KC7.



- ① Connect the camera cable(s) to the CAMERA 1 and CAMERA 2 connectors on the controller.
 - To connect them, match the keyed portion of the connectors and press in. When they are firmly connected, you will hear a click.
 - To unplug a connector, hold the plug housing and pull it straight out.
 - Any camera plugged into the CAMERA 1 connector will be system camera 1 and any camera plugged into the CAMERA 2 connector will be system camera 2 in the IV-S30 system.

Note 2: Make sure to turn OFF the power before connecting or disconnecting the cameras.
 Note 3: If there is only one camera, make sure to connect it as system camera 1.
- ② Plug the other end of the camera cable into the IV-S30C1/C3, and tighten the securing ring on the plug housing.
- ③ Screw the IV-S20L16 camera lens (or similar) into the lens holder on the IV-S30C1/C3 until it is secure.



Remarks

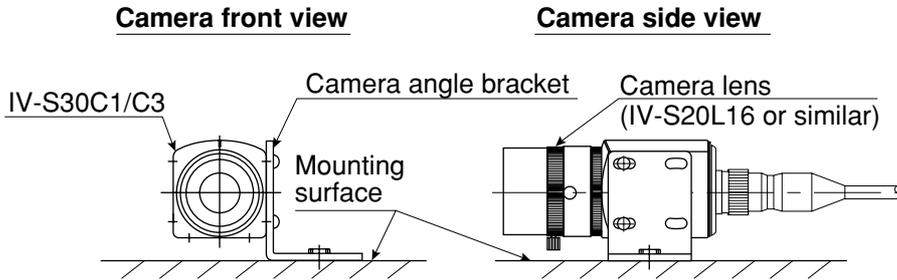
- You cannot use different types of cameras at the same time with the same controller (standard, high-speed and EIA cameras cannot be mixed). When an IV-S30C1 or IV-S30C3 is connected to the controller, the other cameras that can be connected to the controller are as follows:

Camera	Compatible second cameras
IV-S30C1	IV-S30C2 (Micro camera)
IV-S30C3	IV-S30C4 (Micro, high-speed camera)

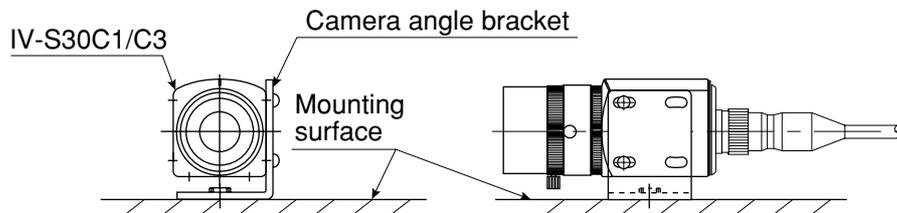
(2) Installing the camera body

Attach the camera (IV-S30C1/C3) on the mounting surface with the camera angle bracket (supplied with the camera).

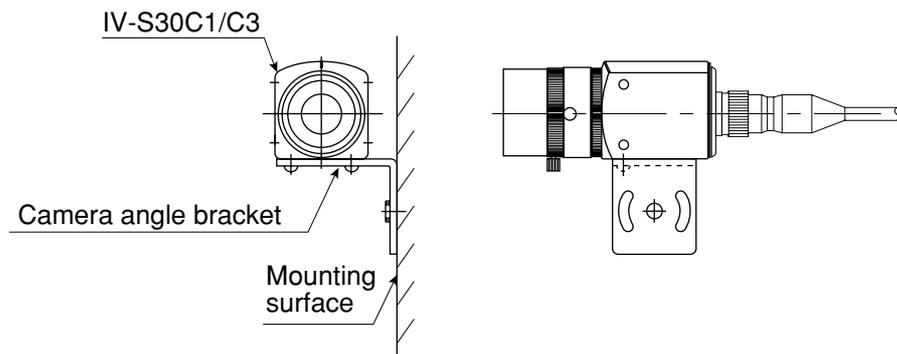
- Installation example 1



- Installation example 2



- Installation example 3

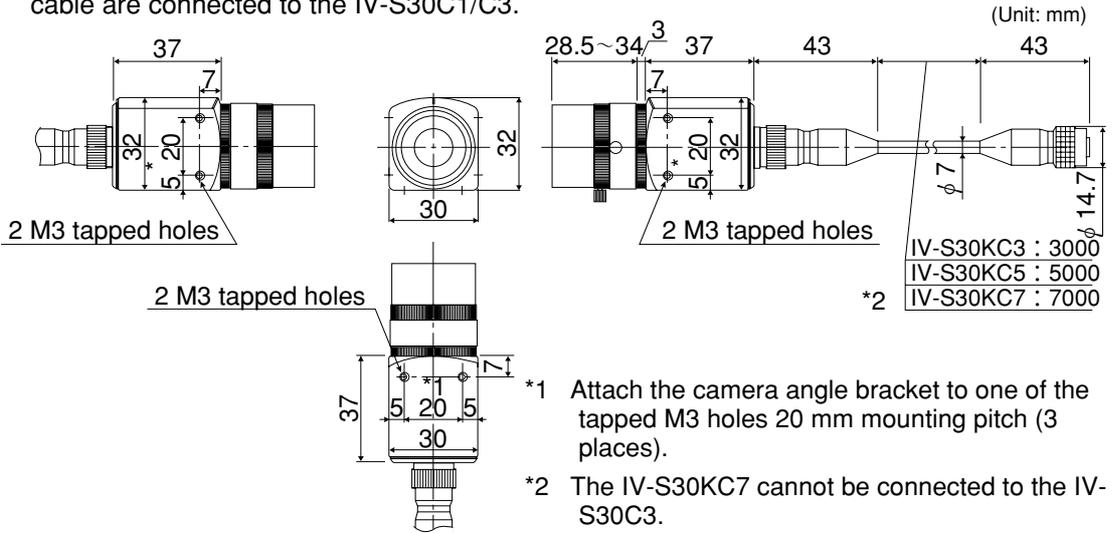


■ Installation procedure

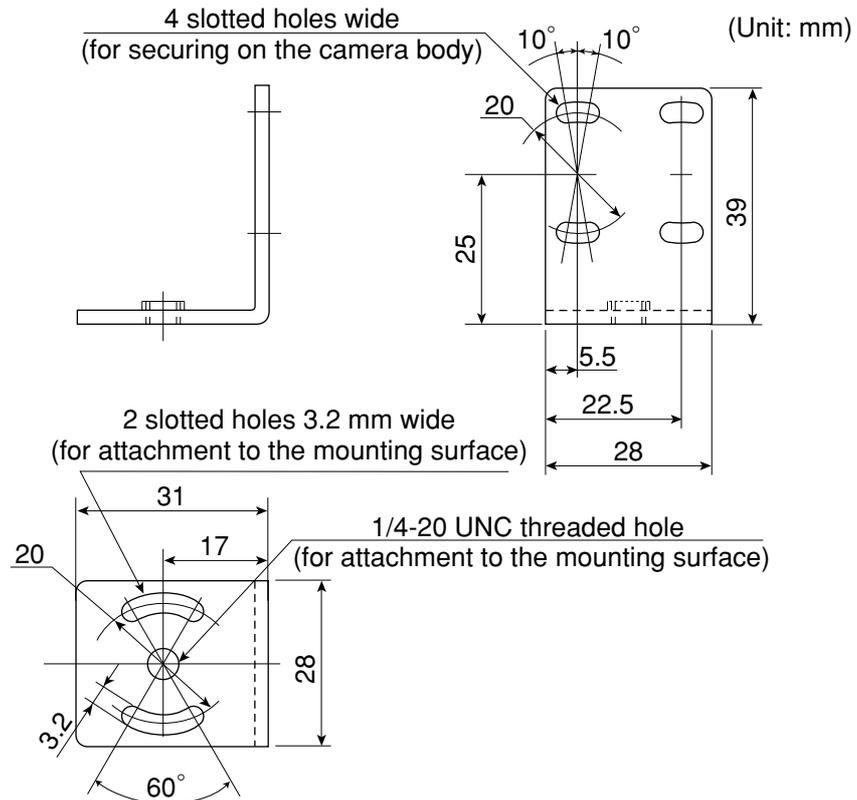
- ① Attach the camera angle bracket to the tapped M3 hole on the camera body (20 mm mounting pitch: one of three holes). Two screws (M 3 x 6) are supplied with the camera for attaching the angle.
- ② Attach the camera controller angle to the mounting surface with the slotted holes 3.2 mm wide (20 mm mounting pitch) or 1/4-20 UNC threaded hole.

The external dimensions of the camera angle bracket and camera body are shown on the following page.

- External dimensions when the IV-S20L16 camera lens and IV-S30KC3/KC5/KC7 camera cable are connected to the IV-S30C1/C3.

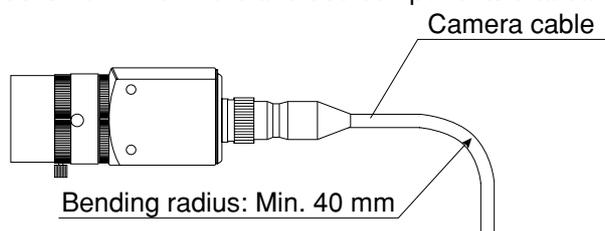


- External dimensions of camera angle bracket



Note

- When the camera cable (IV-S30KC3/S30KC5/S30KC7) is bent, its bending radius should be larger than 40 mm.
If the camera cable will be bent repeatedly during operation, design the cable layout so that the bending radius is 75 mm or more and use components that can be flexed up to 2 million times.



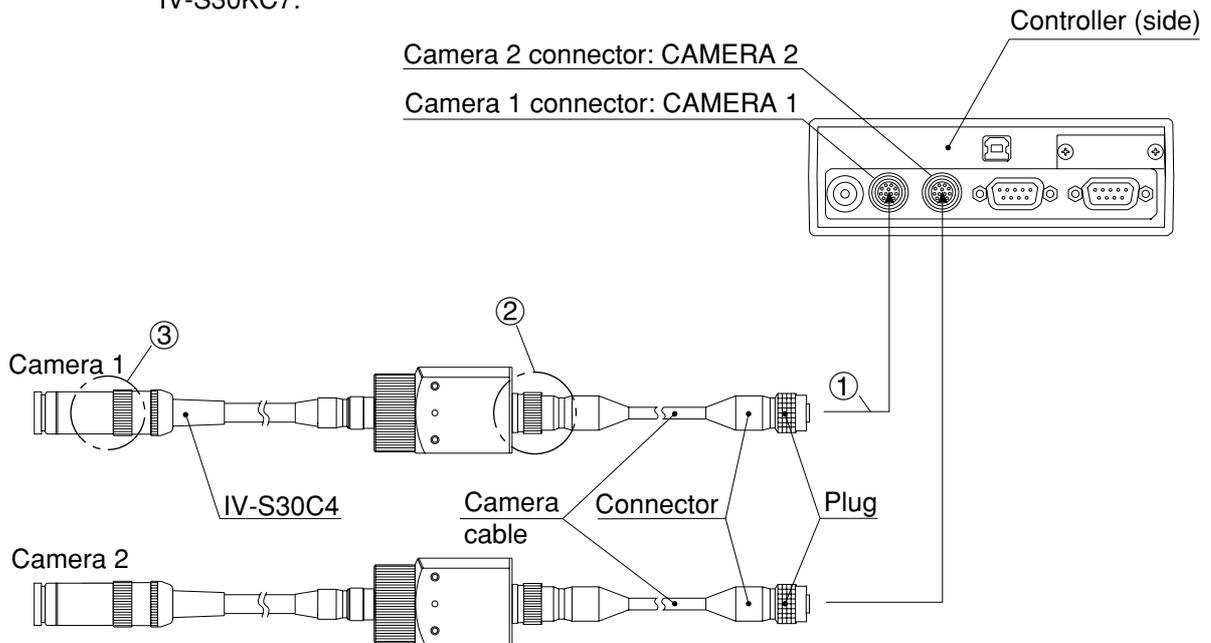
[2] Installing and connecting the IV-S30C2/C4

(1) Connections

Up to two IV-S30C2 micro cameras or IV-S30C4 micro, high-speed cameras can be connected to the following controllers using camera cables.

Camera	Controller to connect	Cables to be used
IV-S30C2	IV-S31M, IV-S32M, IV-S33M	IV-S30KC3 (3 m), IV-S30KC5 (5 m), IV-S30KC7 (7 m),
IV-S30C4	IV-S33M	IV-S30KC3 (3 m), IV-S30KC5 (5 m)

Note 1: Do not connect the IV-S30C4 to the IV-S31M/S32M. The IV-S30C4 cannot be used with the IV-S30KC7.



(Some parts of the external appearance of the IV-S30C2 are different from the IV-S30C4.)

- ① Connect the camera cable(s) to the CAMERA 1 and CAMERA 2 connectors on the controller.
 - To connect them, match the keyed portion of the connectors and press in. When they are firmly connected, you will hear a click.
 - To unplug a connector, hold the plug housing and pull it straight out.
 - Any camera plugged into the CAMERA 1 connector will be system camera 1 and any camera plugged into the CAMERA 2 connector will be system camera 2 in the IV-S30 system.

Note 2: Make sure to turn OFF the power before connecting or disconnecting the cameras.

Note 3: If there is only one camera, make sure to connect it as system camera 1.

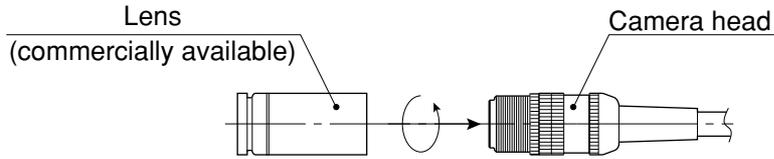
Remarks

- You cannot use different types of cameras at the same time with the same controller (standard, high-speed and EIA cameras cannot be mixed). When an IV-S30C2 or IV-S30C4 is connected to the controller, the other cameras that can be connected to the controller are as follows:

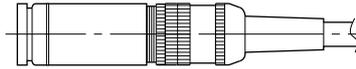
Camera	Compatible second cameras
IV-S30C2	IV-S30C1 (standard camera)
IV-S30C4	IV-S30C3 (high-speed camera)

Connection and Installation Methods

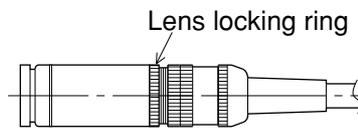
- ② Plug the camera connector on the camera cable (camera conversion cable) into the cable connector on the IV-S30C2/C4 camera and screw it down to secure the connection.
- ③ Screw a commercially available lens into the camera head of the IV-S30C2/C4.



1. Screw the lens in until the camera image is focused.

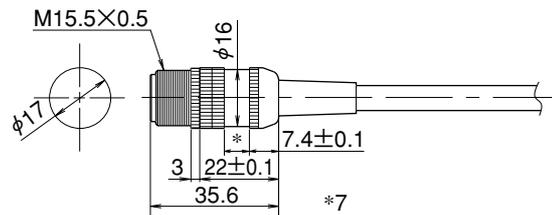


2. Secure the lens using the lens locking ring on the camera head

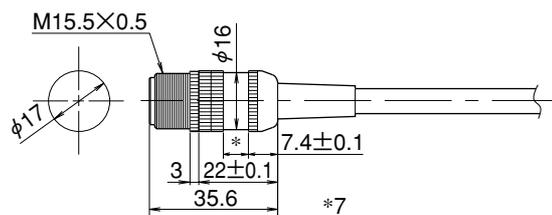


- External dimensions of the IV-S30C2 camera head

(Unit: mm)

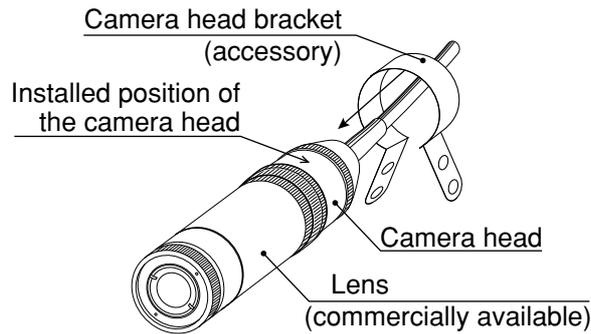


- External dimensions of the IV-S30C4 camera head

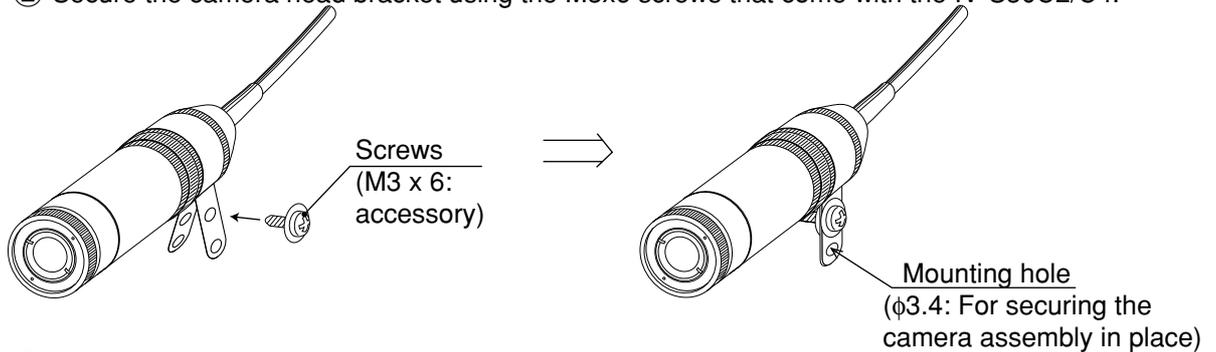


(2) Installation of the camera head

- ① Put the camera head through the bracket (supplied with the IV-S30C2/C4) from the cable side and slide the camera head into position.



- ② Secure the camera head bracket using the M3x6 screws that come with the IV-S30C2/C4.

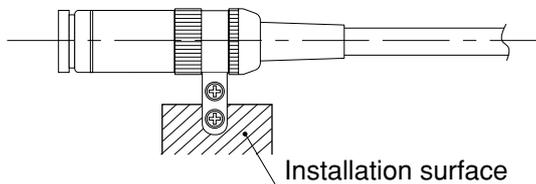


- ③ Secure the camera head assembly in place using the mounting hole (φ3.4) on the camera head bracket.

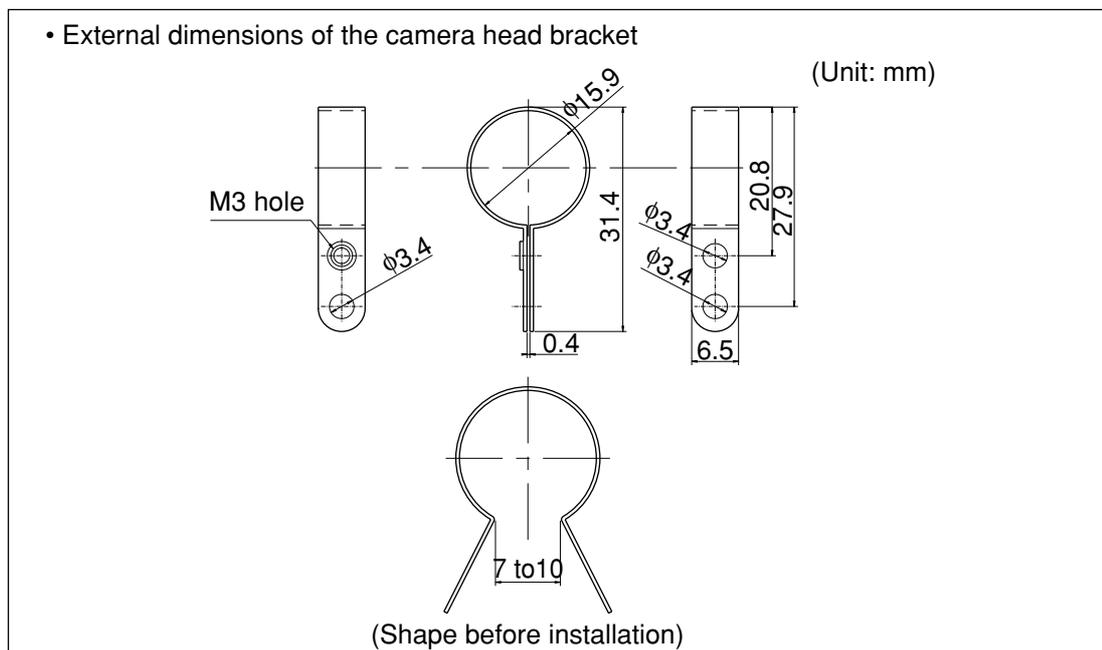
Front view



Side view



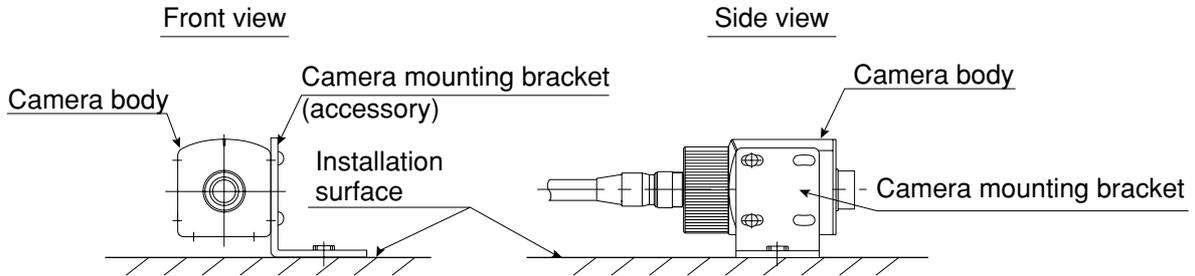
Note: The camera head bracket supplied with the camera is for simple installations and is not vibration-damping. To meet specific needs, the user may have to make a specialized bracket.



(3) Installation of the camera body

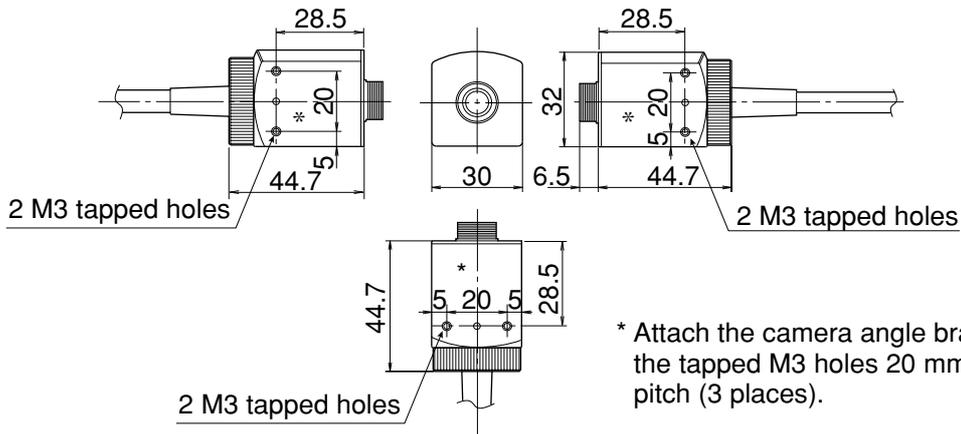
1. Attach the camera mounting bracket (comes with the IV-S30C2/C4) to the three M3 tapped holes (spacing: 20 mm) on the camera body using the M3×6 installation screws that come with the IV-S30C2/C4.
2. Secure the camera mounting bracket on the installation surface using a 3.2mm long, 20 mm difference screw or a 1/4-20 UNC screw hole.

[Installation example]

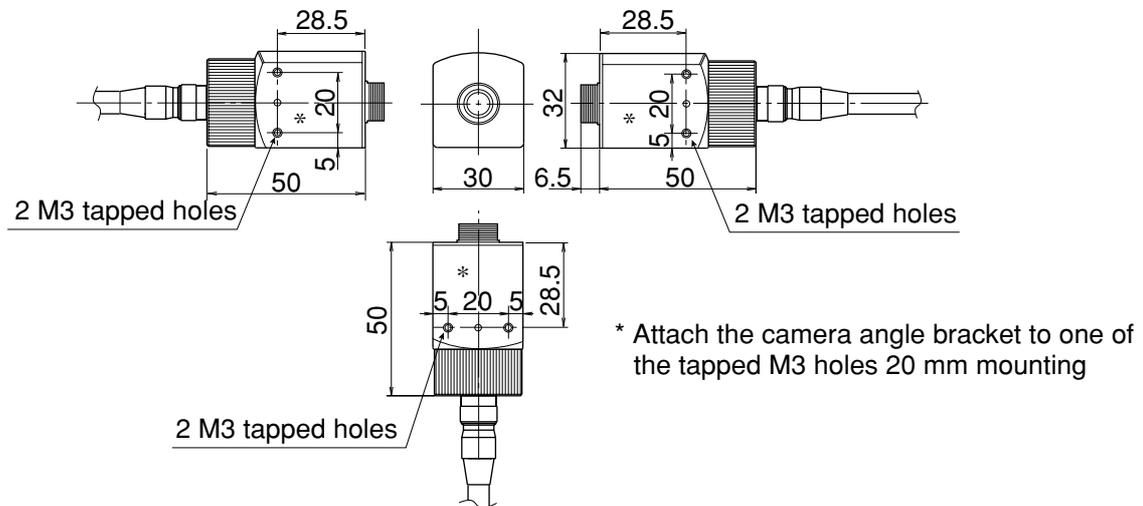


- External dimensions of the controller (IV-S30C2)

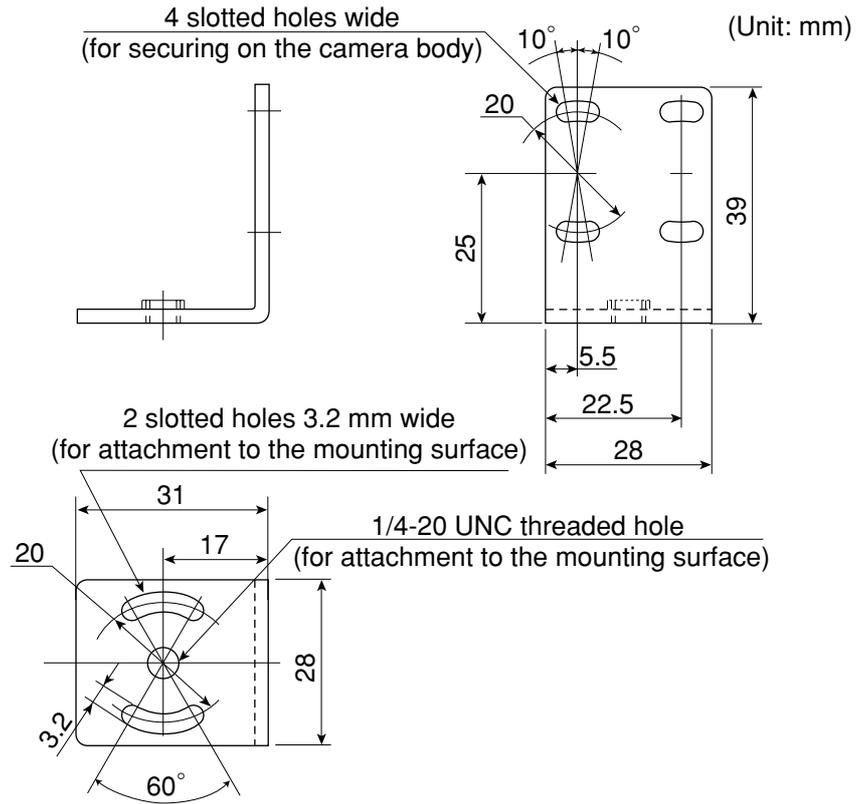
(Unit: mm)



- External dimensions of the controller (IV-S30C4)



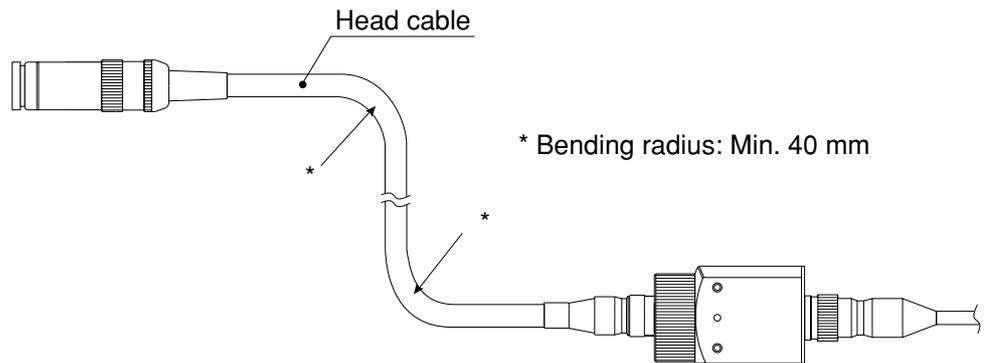
- External dimensions of camera angle bracket



5

Note

- When the camera head cable is bent, its bending radius should be larger than 40 mm. If the camera cable will be bent repeatedly during operation, design the cable layout so that the bending radius is 75 mm or more and use components that can be flexed up to 2 million times.

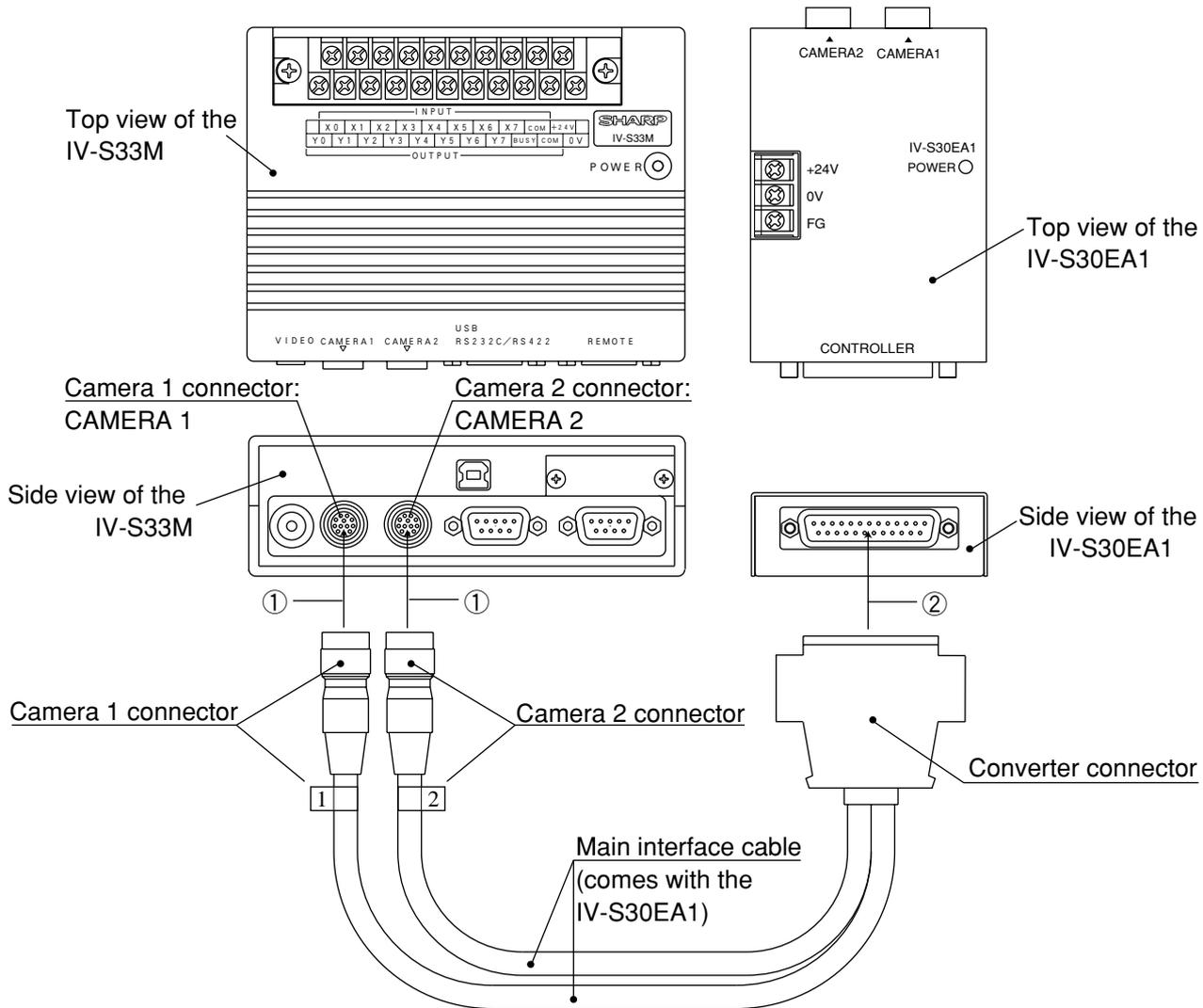


5-4 Installing, connecting, and wiring the IV-S30EA1 camera converter

[1] Connection to the IV-S33M controller

Connect the IV-S30EA1 camera converter to the IV-S33M controller using the main interface cable that comes with the camera converter.

Note: Do not connect the IV-S30EA1 to an IV-S31M/S32M controller.



- ① Connect the camera 1 and 2 connectors on the main interface cable to the CAMERA 1 and CAMERA 2 connectors on the IV-S33M. Make sure the connector numbers match.

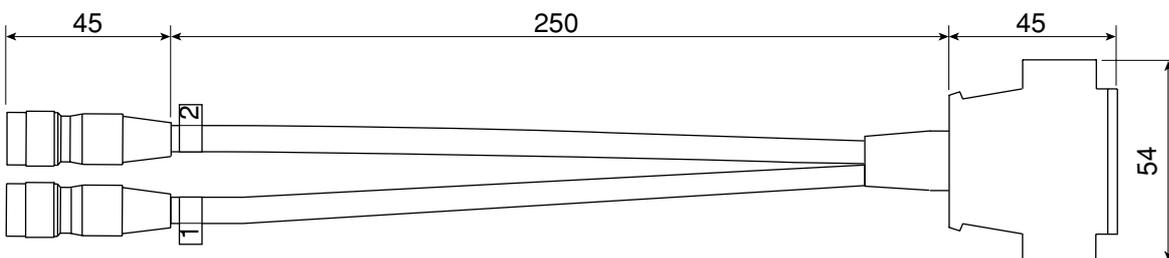
Note: Make sure to turn OFF the power before connecting or disconnecting the cameras or connector.

- To unplug a connector, hold the plug housing and pull it straight out.
- Any camera plugged into the CAMERA 1 connector will be system camera 1 and any camera plugged into the CAMERA 2 connector will be system camera 2 in the IV-S30 system.

- ② Connect the converter connector on the main interface cable to the controller connector on the IV-S30EA1.

• External dimensions of the main interface cable.

(Unit: mm)



[2] Connection to an EIA camera

This section describes how to connect a commercially available camera that conforms to the EIA standards to the IV-S30EA1.

(1) Cameras that can be connected

The specifications of the EIA cameras that can be connected to the IV-S30EA1 and the cameras we recommend are as follows:

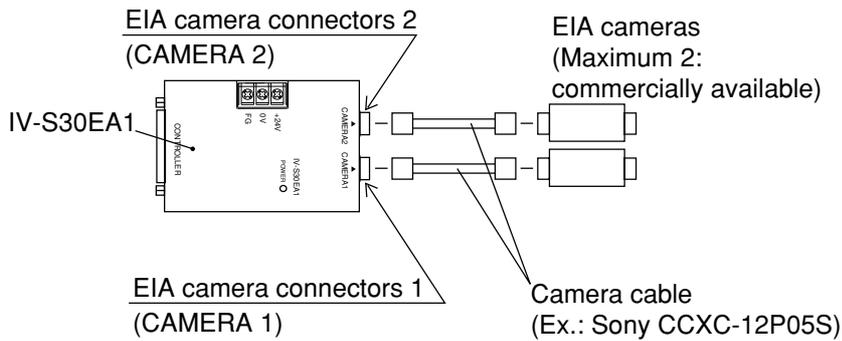
Item	Specifications
Number of scan lines	525
Scan method	2:1 interlace
Frequency	Horizontal 15.734 kHz, vertical 59.94 Hz
Image output	1.0 Vp-p (with a 75 ohm load)
Power supply	+12 VDC ±10%
Current consumption	300 mA maximum

• Recommended cameras

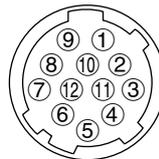
Model	Manufacturer
XC-75	Sony
CS8320B	Tokyo Electronics Industries

(2) Connecting between the IV-S30EA1 and an EIA camera

Connect the IV-S30EA1 to an EIA camera using the EIA camera cable. Check the signals (pin assignment) against the figures below.



• EIA camera connector pin assignments for connectors 1 and 2 on the IV-S30EA1



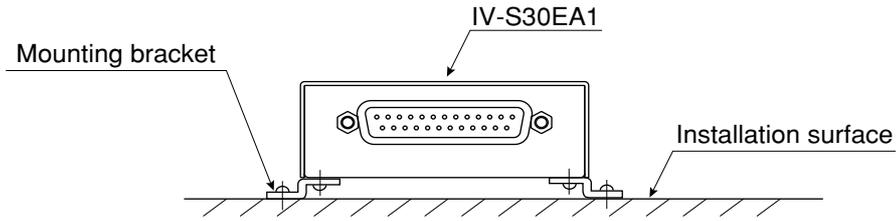
12-pin round connector (female): Made by Hirose Electric

Pin No.	Signal name	Signal type (input/output)	
		INT (internally synchronized mode)	EXT (externally synchronized mode)
1	GND		
2	+12 V	-	-
3	Image GND		
4	Image signal	Input	Input
5	HD GND	-	-
6	HD	Input	Output
7	VD	Input	Output
8	TRIG GND	-	-
9	TRG signal	High impedance state	Output
10	GND	-	-
11	-	Not connected	Not connected
12	VD GND	-	-

- When only one EIA camera is used, make sure to connect it to connector 1 (CAMERA1).

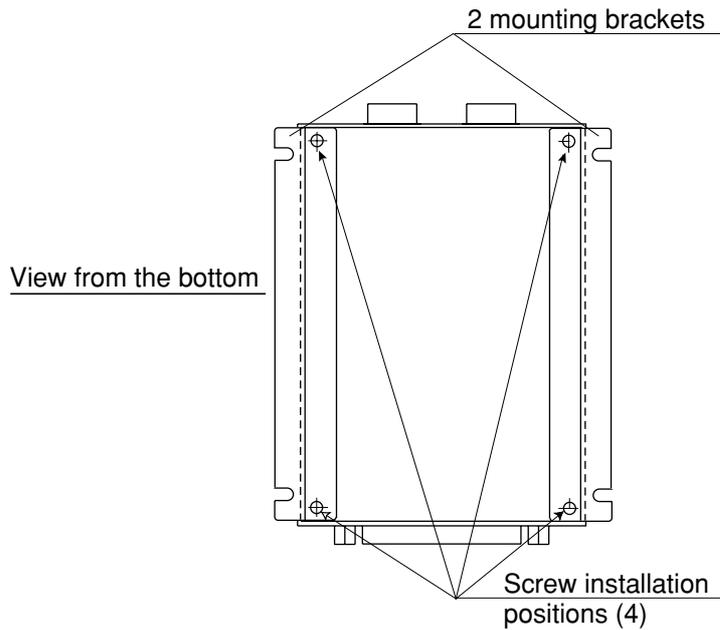
[3] Installing the IV-S30EA1

The bottom of the IV-S30EA1 camera converter should be installed by securing it on another surface with the two mounting brackets that come with the IV-S30EA1.

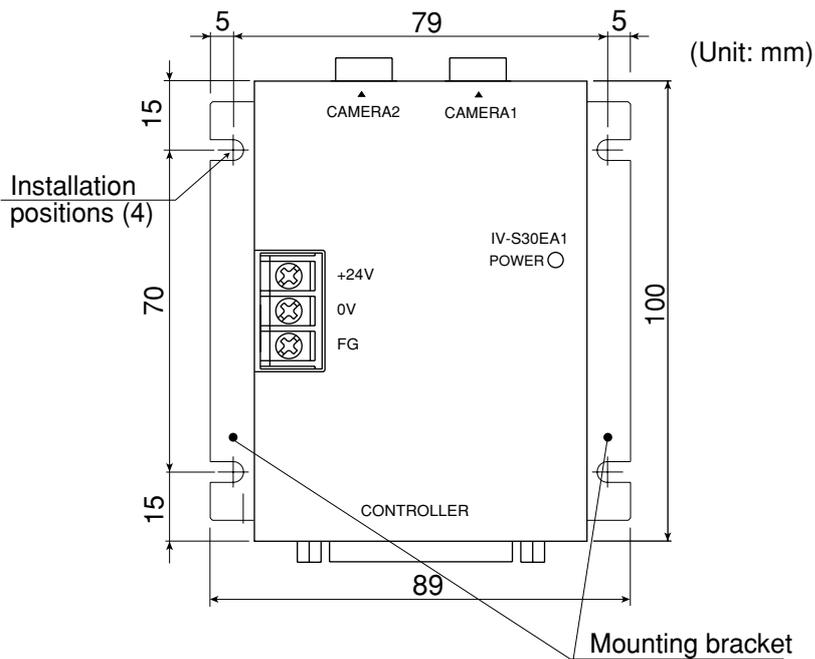


(1) Installation procedures

- ① Install the two mounting brackets on the bottom of the IV-S30EA1. Use the 4 screws (M3 x 6) that come with the IV-S30EA1.

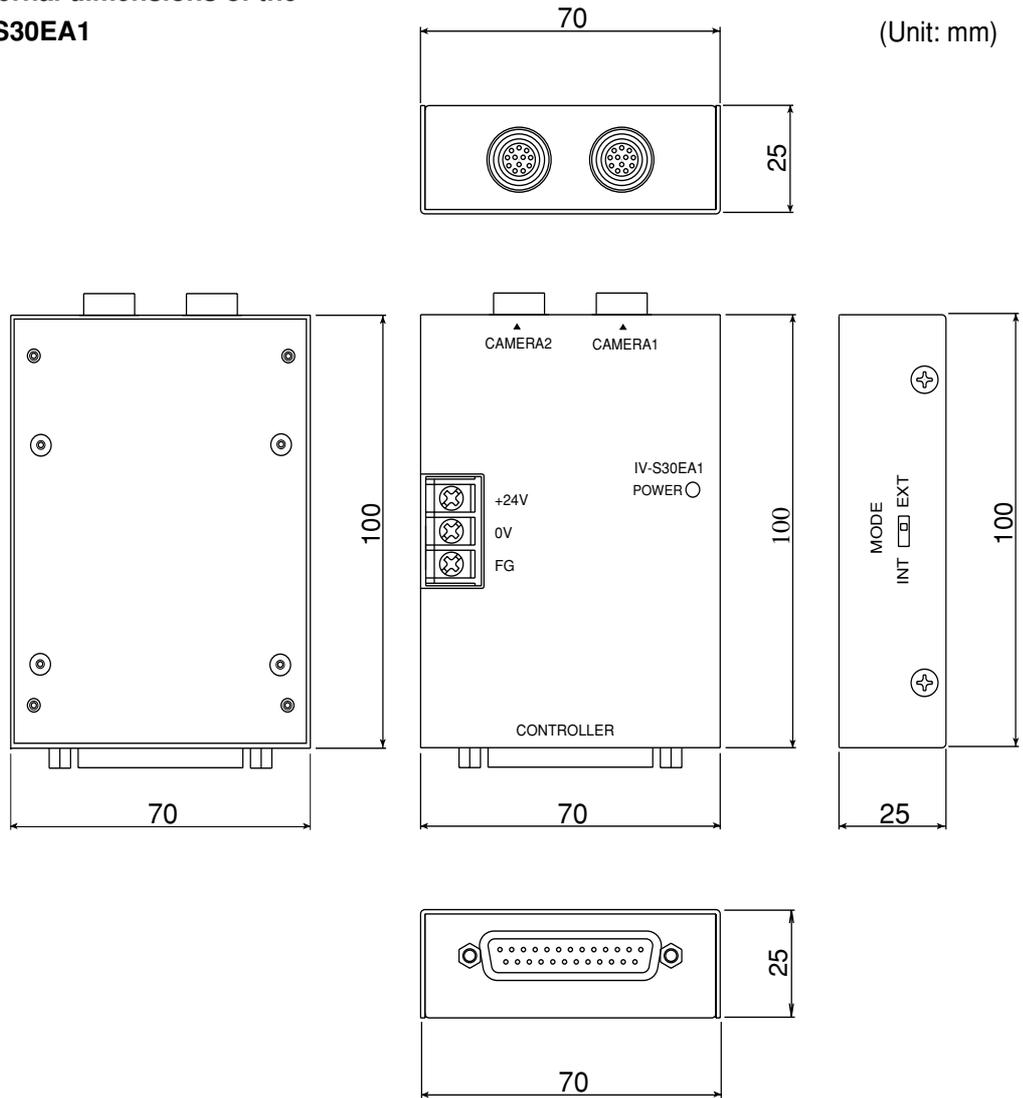


- ② Secure the unit on the installation surface using the mounting brackets.

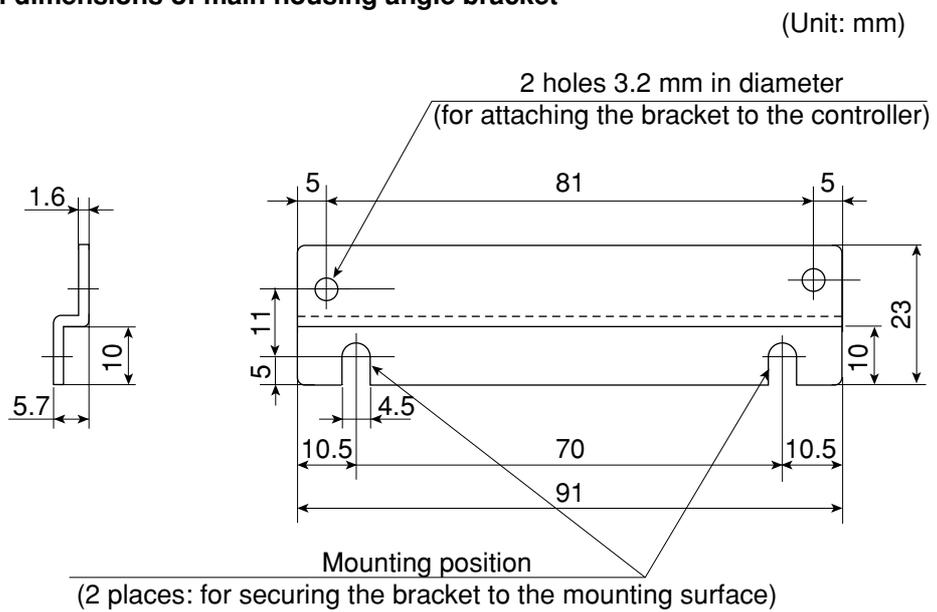


The external dimensions of the IV-S30EA1 and mounting brackets are shown on the next page.

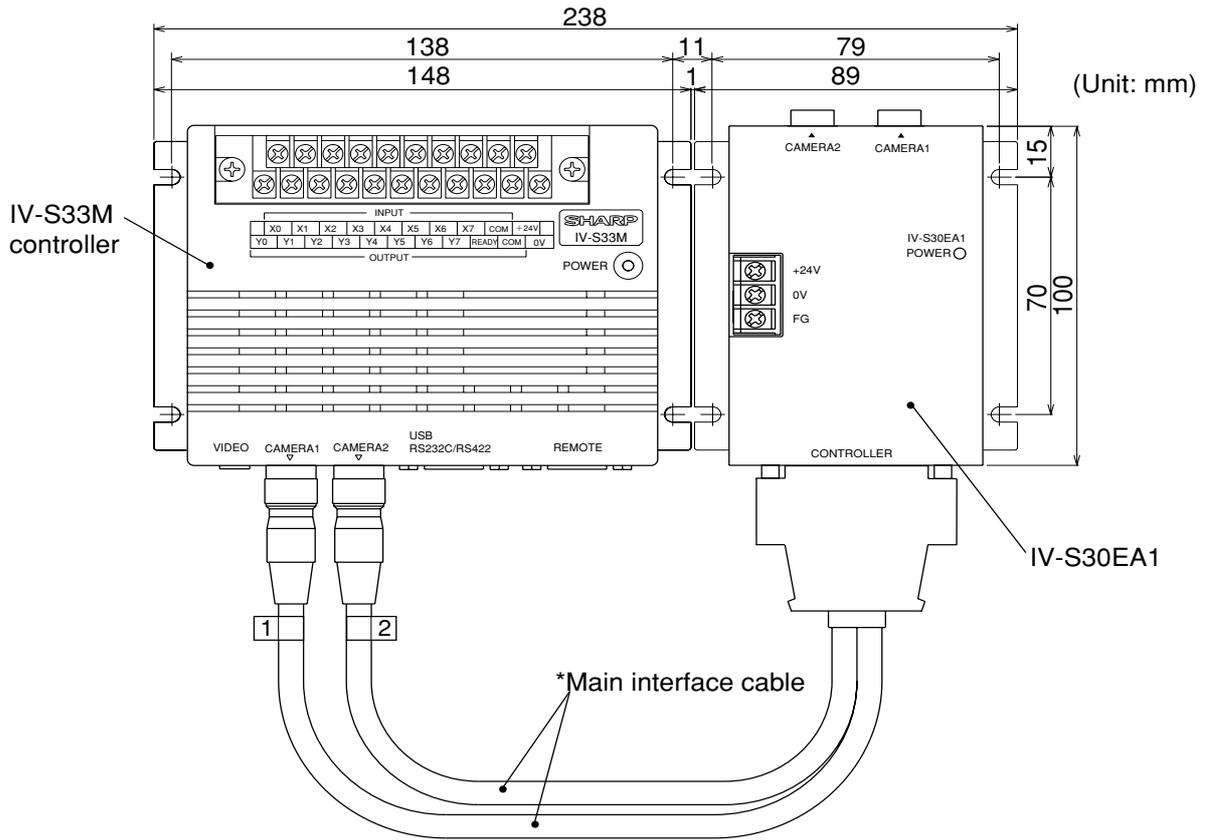
External dimensions of the IV-S30EA1



- External dimensions of main housing angle bracket



(2) Installation example

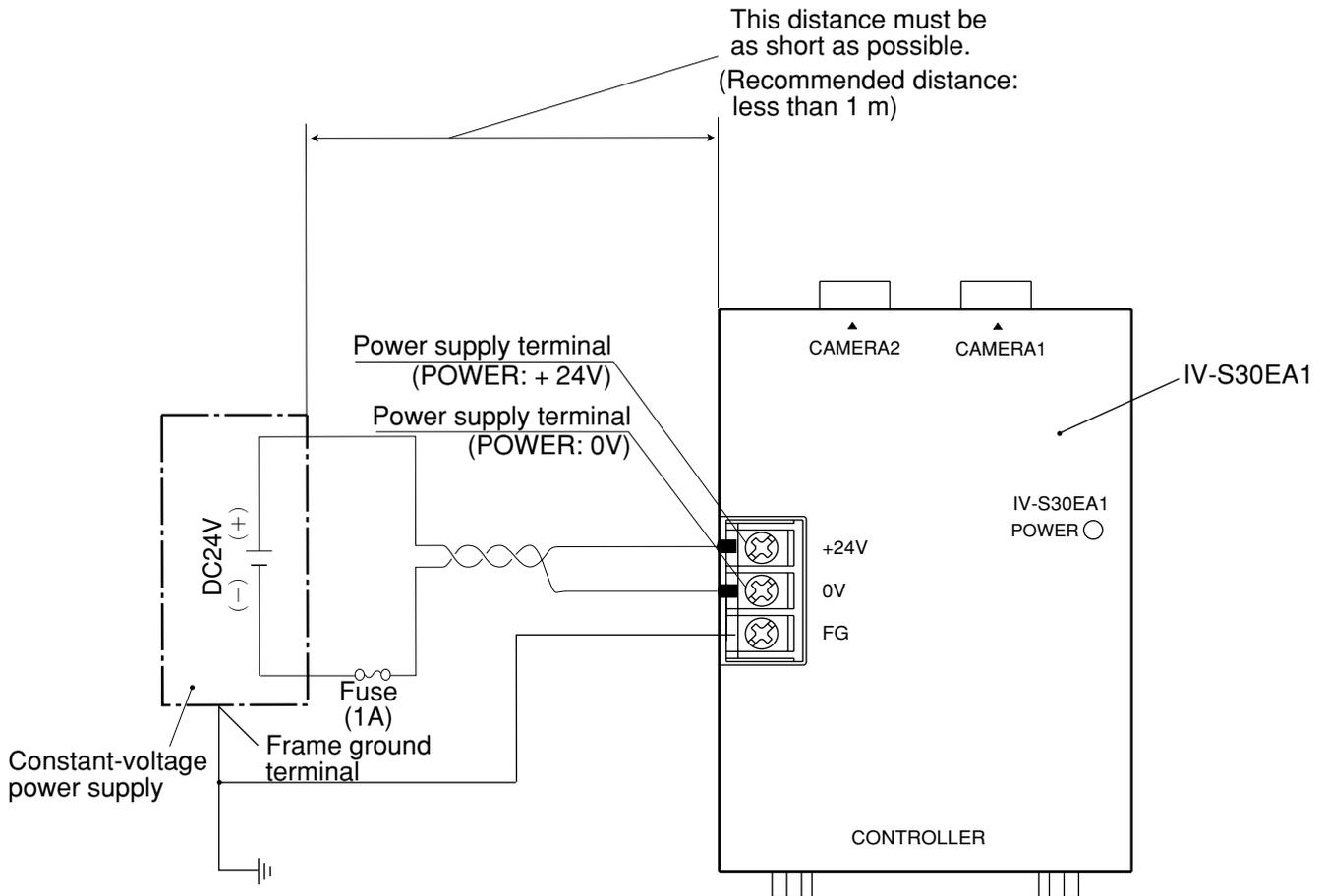


* The main interface cable should not be bent to a radius smaller than 40 mm.
(External dimensions of the main interface cable ⇨ See page 5-32.)

[4] Wiring of the IV-S30EA1

■ Connecting a power supply

- Connect a commercially available constant-voltage power supply to the power terminals (POWER: +24 V, 0 V) on the IV-S30EA1. Use a 24 VDC \pm 10%, 500 mA or more constant-voltage power supply.
- Use an individual and dedicated power supply to supply power to the IV-S30EA1. If the power supply is used to power other equipment, measurement errors may occur.
 - Check the polarity of the power supply terminals, +24 V and 0 V. If power is supplied with the polarity inverted, the controller may be damaged.
 - Only connect or disconnect the camera cable and other equipment while the power is OFF.

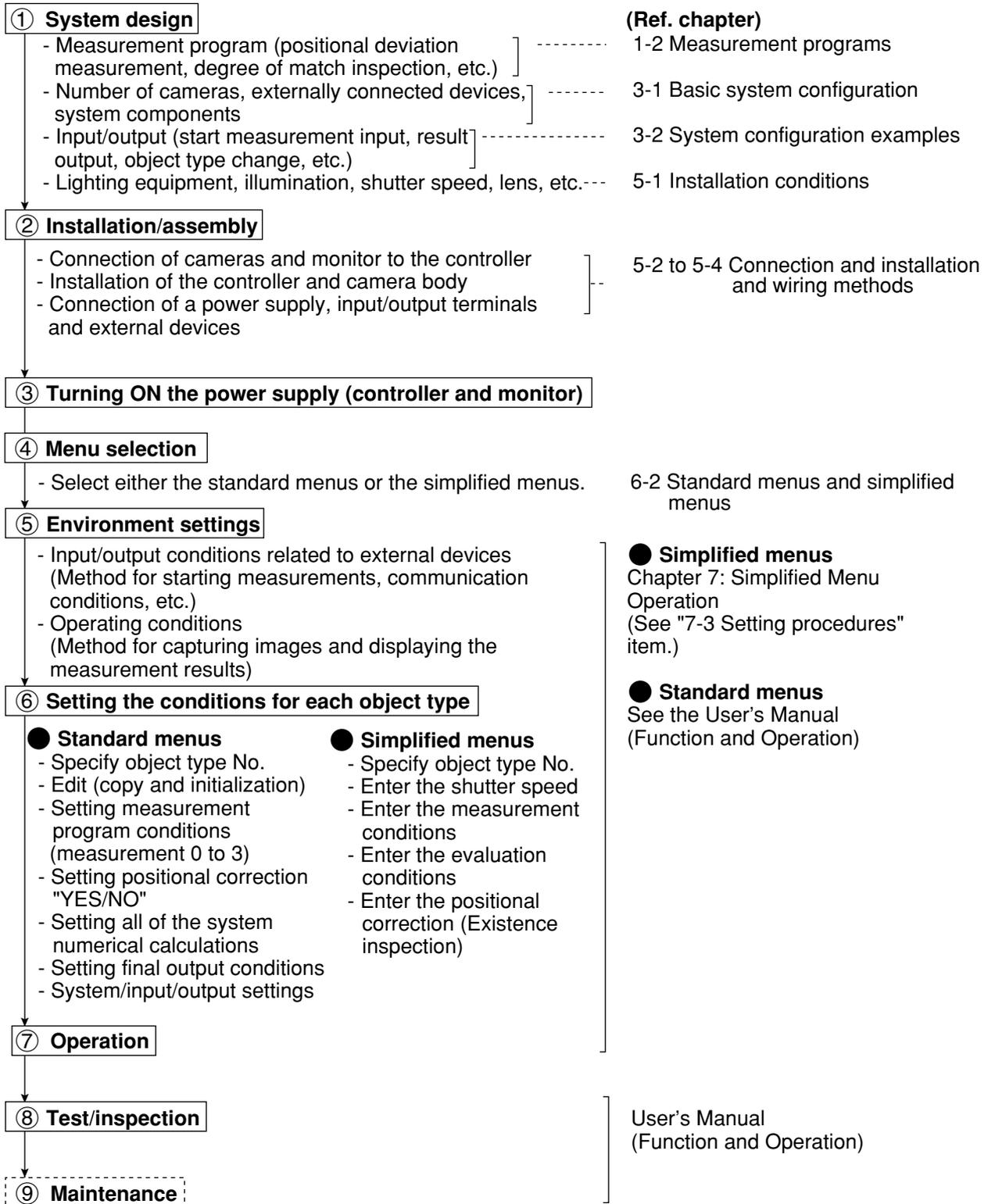


- Note: To improve the noise resistance of the constant-voltage power supply connected to the IV-S30EA1, observe the following precautions.
- Ground the FG terminal of the constant-voltage power supply according to the class 3 grounding.
 - The power line between the IV-S30EA1 and the constant-voltage power supply must be as short as possible. (Recommended distance: less than 1 m)
Do not run the power supply line near any noise generating sources, such as electric motor lines.
 - Use twisted-pair wire for the power supply line.

Chapter 6: Setting and Operating Outlines

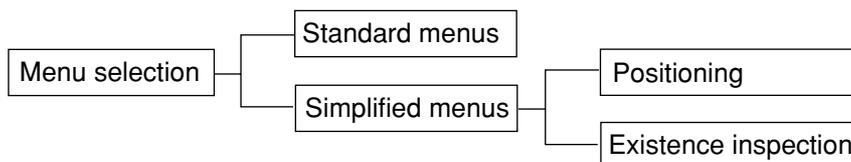
6-1 Setting and operating procedures

The setting and operating procedures are outlined below.



6-2 Standard menus and simplified menus

The IV-S30 has two types of main menu configurations: standard menus and simplified menu. The standard menus have all of the functions available which are presented to the operator. The simplified menus make it easy to set up position and existence inspections



Major differences between the standard menus and the simplified menus

Item	Standard menus	Simplified menus	
Number of menu layers	Three layers	Two layers	
Measurement program	Positional deviation measurement (Positioning) Number of registers: 8 1-point search, 2-point search, 1-point edge, 2-point edge 1-point search + 1-point edge	Number of registers: 1 1-point search, 2-point search	
	Area measurement by binary conversion (Existence inspection) Number of registers: 16 Definable rectangular, circular, and elliptical areas. Enable mask window and noise filter.	Number of registers: 8 Only rectangular area is definable. Mask window and noise filter setting not possible.	
	Degree of match inspection	Yes	No
	Lead inspection	Yes	No
	BGA/CSP inspection	Yes (IV-S32M/S33M)	No
	Object counting by binary conversion	Yes	No
	Object identification (labeling) by binary conversion	Yes	No
	Point measurement	Yes	No
	Multiple position measurement	Yes	No
	Multiple degree of match inspection	Yes	No
Distance and angle measurement	Yes	No	
Positional correction	XY correction, angular correction	XY correction (existence inspection)	
Register/display NG images	Yes (IV-S32M/S33M)	No	
PC function	Yes	No	
Numerical calculation function	Yes	No	

Relationship of the data between the standard menus and the simplified menus

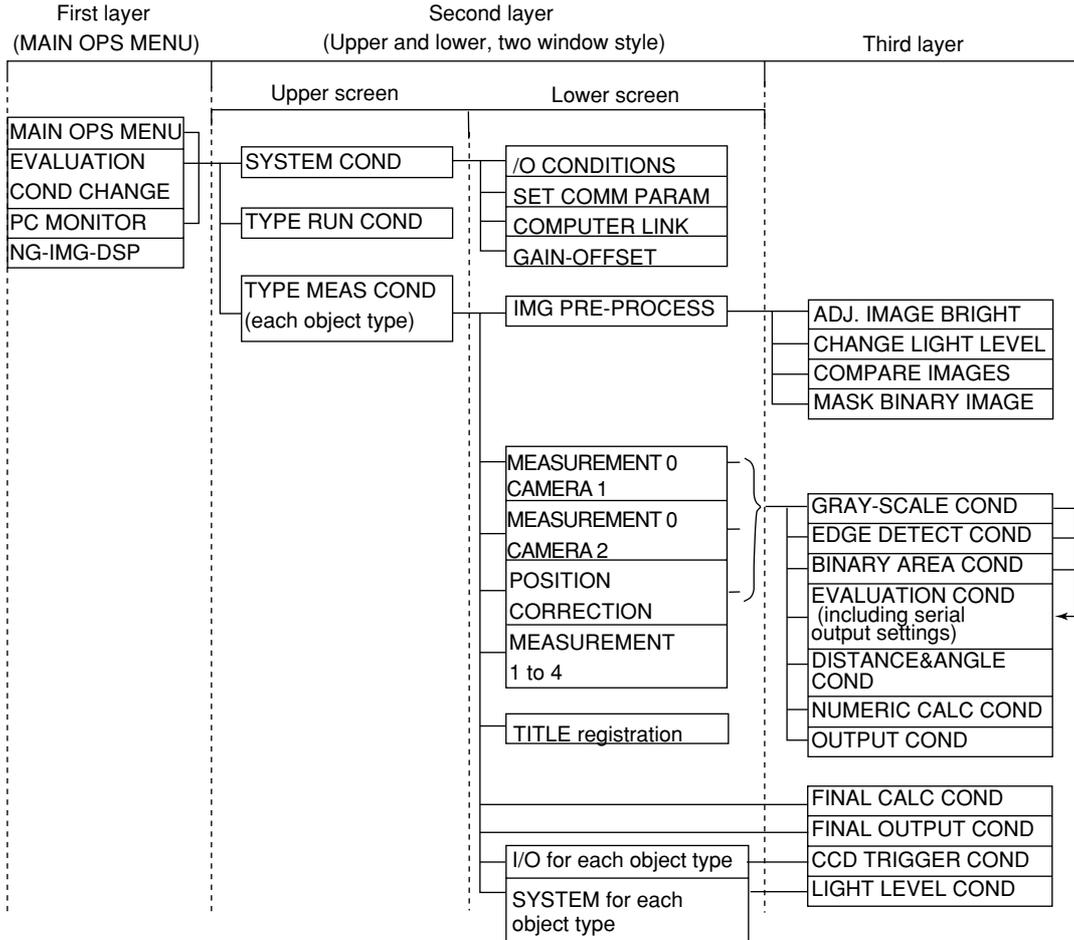
The data entered in the simplified menu will be saved when the screen is changed to the standard menu. The data set up in the standard menu will be initialized when the screen is changed to the simplified menu (the settings will be lost). The table below describes the relation between the data entered in the standard menu and in the simplified menu.

Measurement details	Simplified menus			Standard menu		
	Camera selection	Camera	Register number	Measurement number	Measuring program	Register number
Positioning	Camera 1	Camera 1	-	MEASUREMENT 0 CAMERA 1	Positional deviation measurement	0
	Camera 1 & 2	Camera 1	-	MEASUREMENT 0 CAMERA 1		
		Camera 2	-	MEASUREMENT 0 CAMERA 2		
Existence inspection (Deviation amount for XY correction)	Camera 1	Camera 1	-	MEASUREMENT 0 CAMERA 1	Positional deviation measurement (XY correction)	0
	Camera 1 & 2	Camera 1	-	MEASUREMENT 0 CAMERA 1		
		Camera 2	-	MEASUREMENT 0 CAMERA 2		
Existence inspection (Binary area)	Camera 1	Camera 1	0 to 7	MEASUREMENT 1 CAMERA 1	Area measurement after binary conversion	0 to 7
	Camera 1 & 2	Camera 1	0 to 7	MEASUREMENT 1 CAMERA 1		
		Camera 2	0 to 7	MEASUREMENT 1 CAMERA 2		

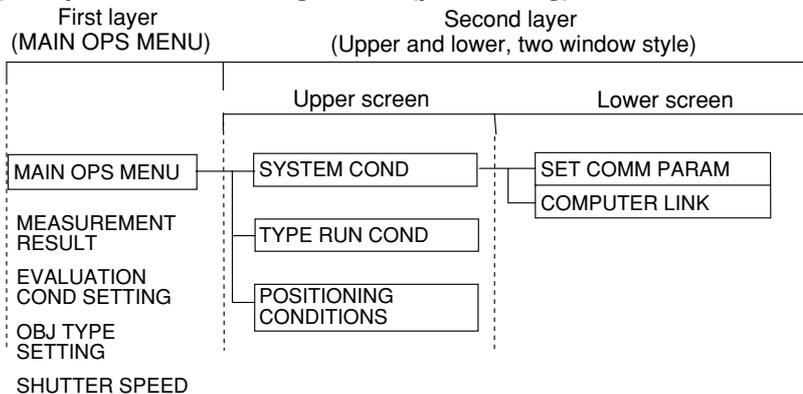
The object type numbers (IV-S31M: 0 to 15, IV-S32M: 0 to 31, IV-S33M: 0 to 63) are also shared by both types of menu configurations.

[1] Menu configuration

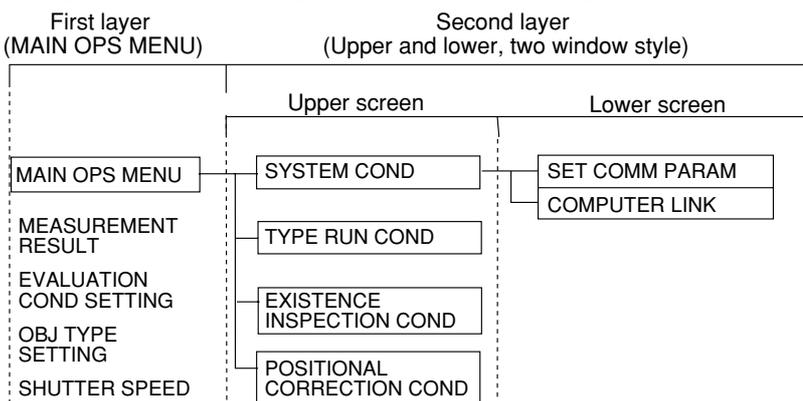
(1) Standard menu configuration



(2) Simplified menu configuration (positioning)



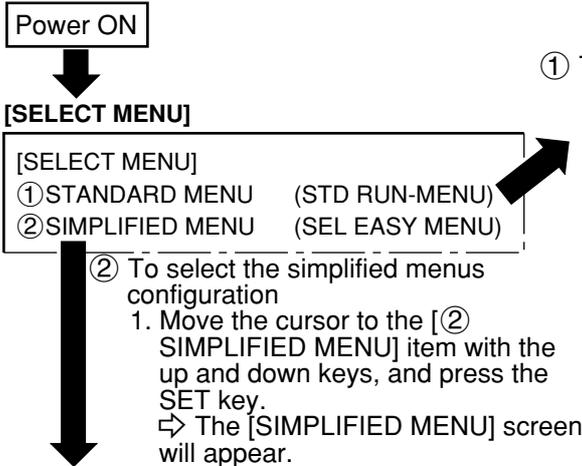
(3) Simplified menu configuration (existence inspection)



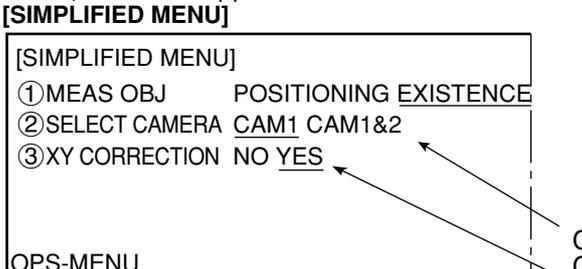
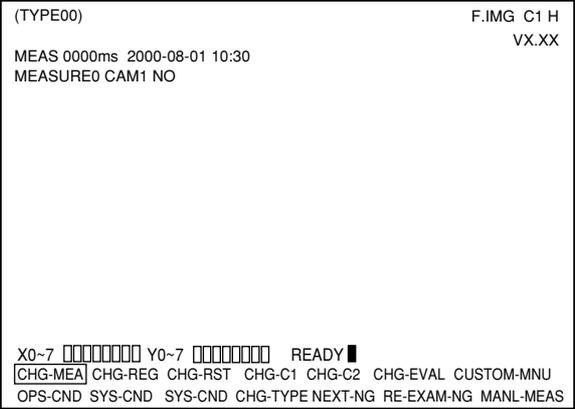
[2] Method for selecting the menu configuration

(1) When power is first turned ON after the machine is delivered

When power is first turned ON after the machine is delivered, the [SELECT MENU] screen will appear.



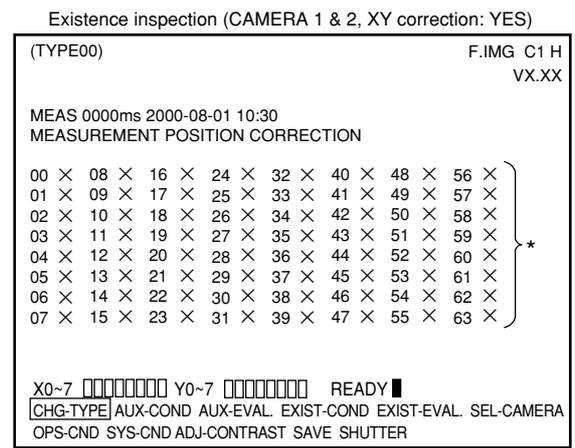
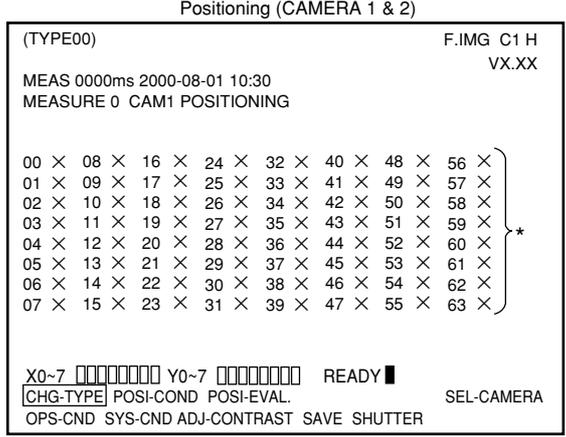
① To select the standard menu configuration
 1. Move the cursor to the [①STANDARD MENU] item with the up and down keys, and press the SET key.
 ⇨ The standard mode [MAIN OPS MENU] screen will appear.



Camera 1: Use only CAMERA 1
 Camera 1 & 2: Use both CAMERA 1 and CAMERA 2

1. Move the cursor to the item you want to set with the up and down keys, and press the SET key.
 2. Move the cursor to the item you want to specify with the left and right keys, and press the SET key.
 3. Move the cursor to the OPS-MENU item with the up and down keys, and press the SET key.
 ⇨ The [MAIN OPS MENU] screen will appear.

When the [①MEAS OBJ] is set to [EXISTENCE], [③ XY CORRECTION] item is displayed. Select "YES" to execute an XY correction.



* For the IV-S33M

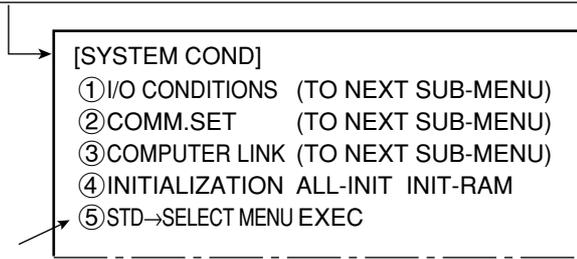
- For details about the method for using the simplified menus, see Chapter 7, "Simplified Menu Operation."
- For details about the method for using the standard menus, see the User's Manual (Function and Operation).

Notes

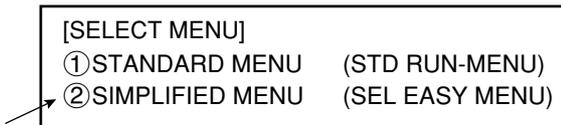
- If you have saved the configuration data in flash memory by selecting the "SAVE" item, the next time you turn ON the power, the menu configuration you selected will be displayed automatically.

(2) Changing the screen from the standard menus to the simplified menu configuration

Move the cursor to the "SYS-CND" item on the MAIN OPS MENU screen, and press the SET key.



1. Move the cursor to the "⑤ STD → SELECT MENU" item on the [SYSTEM COND] menu, and press the SET key.
2. Select the "EXEC" item, and press the SET key. The [SELECT MENU] screen will appear.



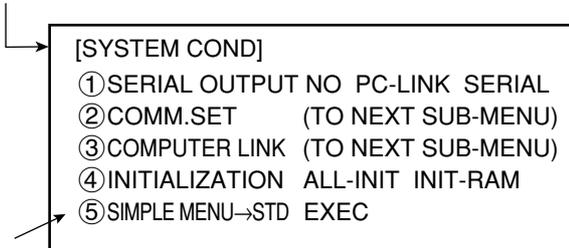
1. Move the cursor to the "② SIMPLIFIED MENU" item with the up and down keys, and press the SET key.
⇒ The [SIMPLIFIED MENU] screen will appear.
2. As described on the previous page, select each item that you want to specify, and press the SET key.

Notes

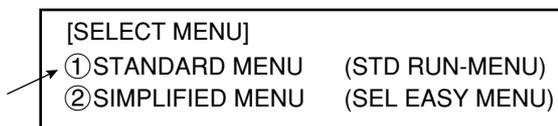
- Make sure to SAVE the system configuration data after you change from the standard menus to the simplified menu configuration. Otherwise, your selection of the simplified menu configuration will be ignored the next time you turn ON the power.
- When you change the IV-S30 configuration from the standard menus to the simplified menus, the data will be saved into the RAM.

(3) Changing from the simplified menus to the standard menu configuration

Move the cursor to the "SYS-CND" item on the MAIN OPS MENU screen, and press the SET key.



1. Move the cursor to the "⑤ SIMPLE MENU → STD" item on the [SYSTEM COND] menu, and press the SET key.
2. Select the "EXEC" item, and press the SET key. The [SELECT MENU] screen will appear.



1. Move the cursor to the "① STANDARD MENU" item with the up and down keys, and press the SET key.
⇒ The [MAIN OPS MENU] screen with the standard menus will appear.

To select whether "POSITIONING" or "EXISTENCE" is displayed on the simplified menus, select the [② SIMPLIFIED MENU] item on the [SELECT MENU] screen, and specify each item you want to appear on the simplified menus.

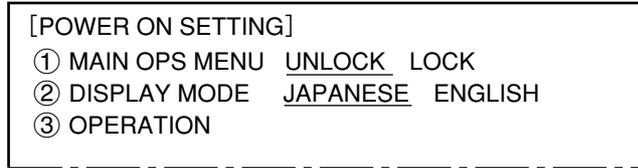
Notes

- Make sure to SAVE the system configuration data after you change from the simplified menus to standard menu configuration. Otherwise, your selection of the standard menu configuration will be ignored the next time you turn ON the power.
- The items that you selected for display on the simplified menus will be saved when the screen configuration is changed to the standard menus. (See page 6-2.)

6-3 Power on setting menu

Follow the procedure described below when turning ON the power to the IV-S31M/S32M/S33M controller, and the [POWER ON SETTING] menu will be displayed on the monitor.

1. Turn ON the power to the controller, while holding down the ESC key.
2. Keep pressing the ESC key down for approx. 9 sec., after turning ON the power and the menu will be displayed.



[1] Operations menu lock

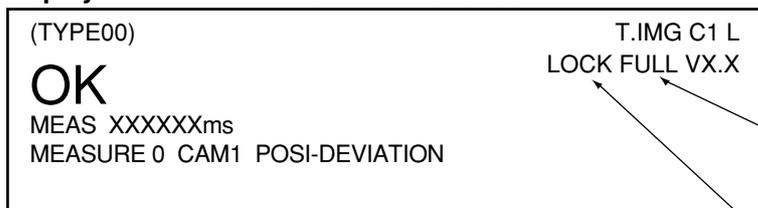
To prevent accidental changes to conditions you have set, the MAIN OPS MENU can be locked so that the screen cannot be changed to SET-SCRN. The operation can only be carried out on the [POWER ON SETTING] menu.

■ Operation procedure

1. On the [POWER ON SETTING] menu, move the cursor to item ① MAIN OPS MENU with the up and down keys, and press the SET key.
 2. Move the cursor to UNLOCK or LOCK with the left and right keys, and press the SET key.
 3. Move the cursor to item ③ OPERATION with the up and down keys, and press the SET key. Press the SET key once more.
- ⇒ The IV-S30 saves the settings in the flash memory and the screen will return to the SELECT MENU.

① MAIN OPS MENU	Description
UNLOCK	All of the operating conditions for the IV-S30 can be changed.
LOCK	The MAIN OPS MENU is locked and no change can be made.

■ Display when the MAIN OPS MENU is locked



This is only displayed when using the IV-S33M

"LOCK" will be displayed on the MAIN OPS MENU

[2] Change the Japanese or English display mode

The language used on the screen can be set to Japanese or English. Select the [POWER ON SETTING] menu.

■ Operation procedure

1. Move the cursor to item ② DISPLAY MODE with the up and down keys, and press the SET key.
 2. Move the cursor to JAPANESE or ENGLISH with the left and right keys.
 3. Move the cursor to item ③ OPERATION with the up and down keys, and press the SET key. Press the SET key once more.
- ⇒ The screen will return to the MAIN OPS MENU.

6-4 Camera setting

The cameras that can be connected to IV-S31M/S32M/S33M controllers are as follows:

Controller	Connectable cameras
IV-S31M	IV-S30C1 Standard camera
IV-S32M	IV-S30C2 Micro camera
IV-S33M * 1	IV-S30C1 Standard camera
	IV-S30C2 Micro camera
	IV-S30C3 High-speed camera
	IV-S30C4 Micro, high-speed camera
	EIA camera (commercially available)

* You cannot use different types of cameras at the same time with the same controller (standard, high-speed and EIA cameras cannot be mixed).

[1] For the IV-S31M/S32M

Only IV-S30C1/C2 standard cameras can be connected to the IV-S31M/S32M controllers. These controllers do not have settings for the type of camera connected to it.

[2] For the IV-S33M

An IV-S30C1/C2 standard camera, IV-S30C3/C4 high-speed camera, or commercially available EIA cameras can be connected to the IV-S33M. Select the camera type (camera synchronization, image capture mode) in the "CAMERA TYPE" item on the [SYSTEM COND] menu to match the type of camera you have connected.

Camera connected		IV-S30C1 (standard) IV-S30C2 (micro)	IV-S30C3 (high-speed) IV-S30C4 (micro and high-speed)	EIA camera (commercially available)
CAMERA TYPE (SYSTEM COND)	Camera selection	Standard	High-speed	EIA
	Camera synchronization ⇒ See (2) below	---	---	Externally or internally synchronized
	Image capture mode ⇒ See (1) below	---	Full or half, full + half	Full or half

- For details about finding the setting screens above, see page 7-31 for the simple menu and read the "Camera settings" section of the IV-S30 (IV-S31M/S32M/S33M) User's Manual, Function and Operation for details about the standard menu.

(1) Image capture mode

When you are using the IV-S30C3/C4 high-speed camera or an EIA camera, you have to select an image capture mode.

Image capture mode	Details
Full	Capture all of the lines in the image
Half	Capture the odds lines in the image
Full + half * 2	In the partial image mode, the measurement target lines are in full mode and the others are in half mode

* 2 "Full + half" mode can only be selected when it is a high-speed camera.

- For a comparison of the image capture times, see page 7-32.

(2) Camera synchronization

When an EIA camera is used, you have to set the camera synchronization mode (internal or external synchronization).

① Internal and external synchronization details

1. Internal synchronization

This mode uses the CCD image capture timing inside the camera, and captures images automatically.

- To send a captured image to the IV-S33M, first the IV-S33M must send a trigger to the camera. Then the camera will wait until the first line from its CCD is being read to begin the capture and image transmission. Due to this process (camera synchronization time + monitor output synchronization time), the shutter time may fluctuate (maximum: 33.3 + 16.6 ms).
- When two cameras are connected, camera 1 and camera 2 cannot both open their shutters at the same time. Therefore, there will be a difference in shutter timing as described above.

2. External synchronization

The IV-S33M controls the shutter speed and trigger timing in order to capture images. See the next page for the internal/external synchronization timing charts.

• External synchronization and internal synchronization processing

	Internal synchronization	External synchronization
Shutter time	Fixed by the camera design	Settable from the IV-S33M
Shutter speed	- Fluctuates with the camera synchronization time and the monitor output synchronization time (maximum 49.9 ms for each camera)	Fixed value (depends on the shutter speed) - When the shutter speed is 1/120, this value is 8.3 ms - Setting range varies with the camera connected.

• Shutter speeds of the recommended cameras

Cameras recommended		Sony XC-75	Tokyo Electronics Industry CS8320B
Shutter speeds	Internal synchronization (selected on the camera)	1/125, 1/250, 1/500, 1/1000 1/2000, 1/4000, 1/10000	1/125, 1/250, 1/500, 1/1000 1/2000, 1/4000, 1/10000
	External synchronization	1/100 to 1/1600	1/125 to 1/1500

② Setting the IV-S30EA1 and IV-S33M for use with an EIA camera

Set the IV-S30EA1 camera converter, and the IV-S33M controller to internal or external synchronization, to match the EIA camera you have.

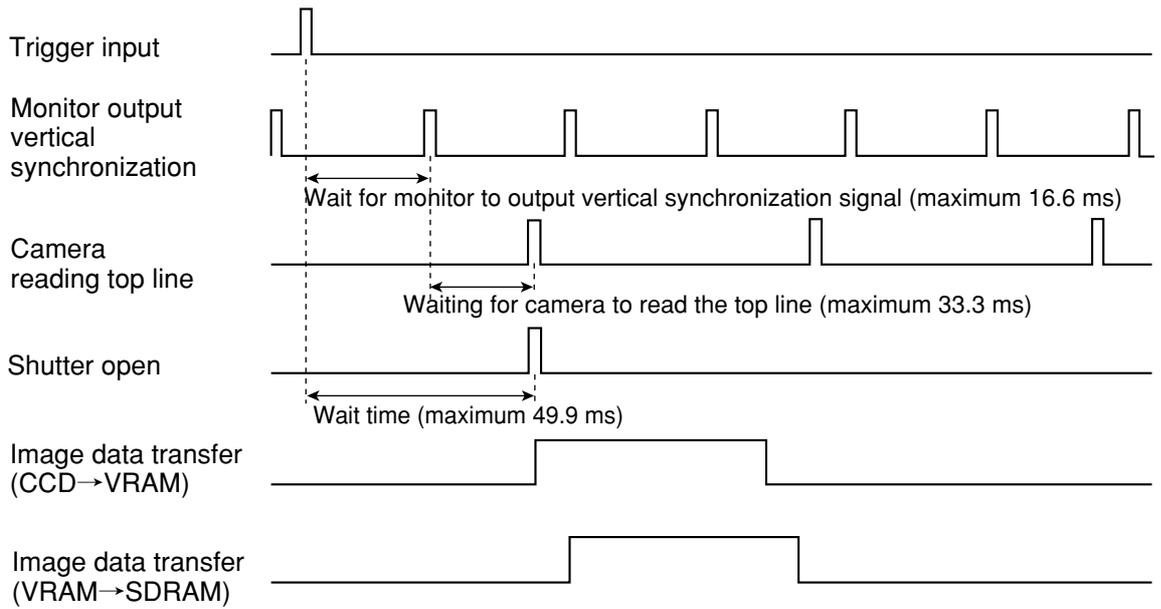
Item	Setting details		Reference
	For internal synchronization	For external synchronization	
EIA camera	Set to "Internal Synchronization" mode	Set to "External Synchronization" mode	*
IV-S30EA1 mode switch (MODE)	INT	EXT	Page 4-4
IV-S33M camera setting (system condition)	Camera Selection: EIA Camera Synchronization: Internal Synchronization	Camera Selection: EIA Camera Synchronization: External Synchronization	Page 7-31

*For example, set the Tokyo Electronics Industries CS8320B camera dip switches as follows:

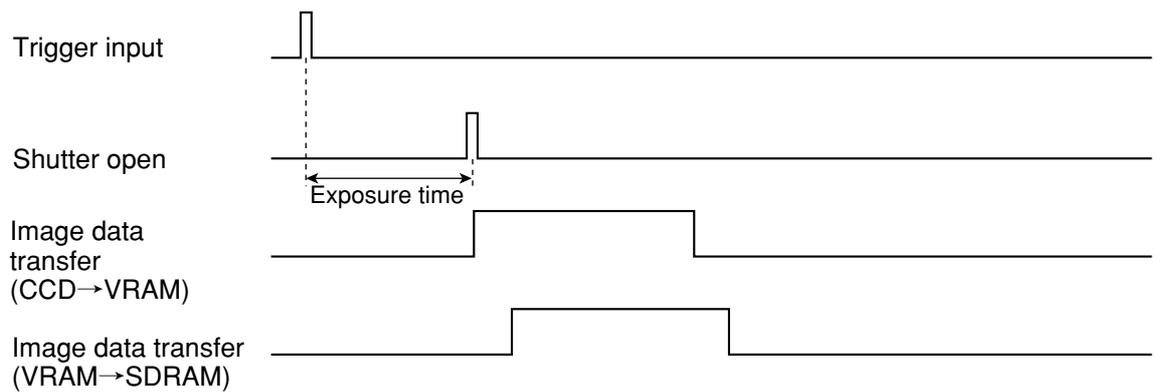
Function [Dip switch SW4]	Use Internal Synchronization	Use External Synchronization
γ correction [1]	OFF	OFF
CCD storage mode [2]	OFF (frame storage)	ON (field storage)
Restart and reset [3]	OFF	ON
Special shutter [4]	OFF	ON
VD output/FLD output [6]	OFF (VD output)	OFF (VD output)

③ Timing chart

■ Internal synchronization



■ External synchronization



Note: When an EIA camera is used, the last (lowest) line (line 479) may not be captured successfully due to some camera's characteristics.

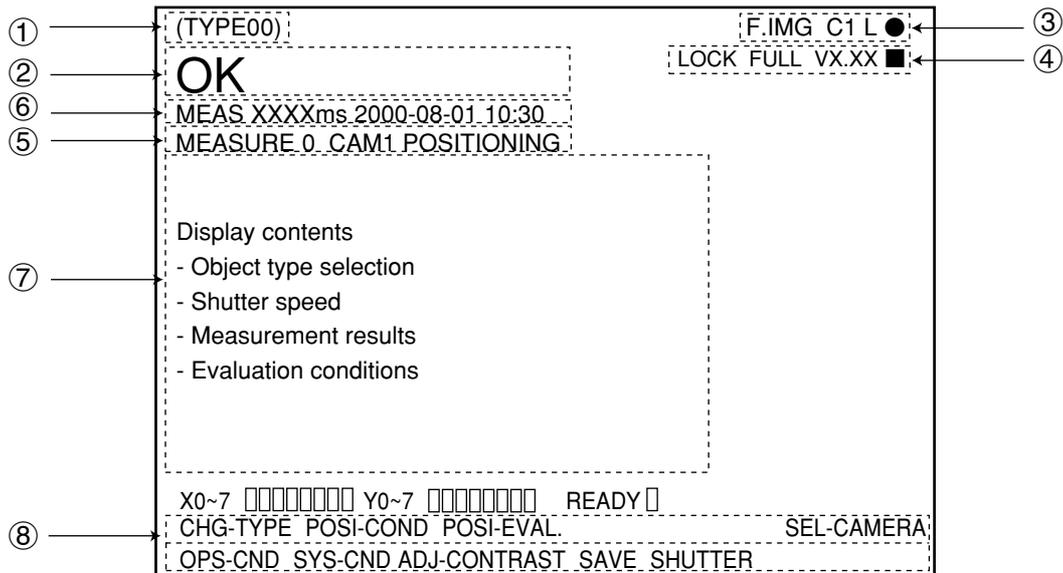
Chapter 7: Simplified Menu Operation

7-1 Operation screen

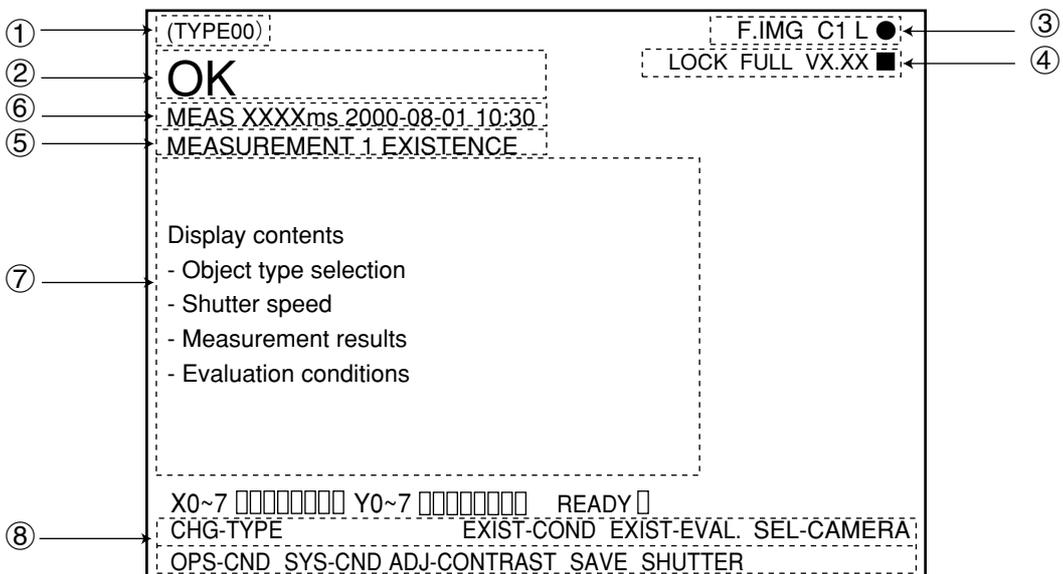
When the simplified menus are selected, supply power to the controller (IV-S31M/S32M/S33M), and the MAIN OPS MENU (startup screen) will be displayed on the monitor. (For details about the settings on the simplified menus, see page 6-4.)

- Before applying the power, make sure that the power cable, monitor cable, camera cables, and remote key pad have been connected to the controller.

■ The operation screen for "Positioning"



■ The operation screen for an "Existence inspection"



Simplified Menu Operation

① Object type No. (00 to 15: IV-S31M, 00 to 31: IV-S32M, 00 to 63 : IV-S33M)

② Final evaluation result

Display	Description
OK	"OK" is displayed when all of the individual evaluation results are acceptable.
NG	"NG" is displayed if any single evaluation result is unacceptable.
(Error message)	An error code and the measurement number that caused the error are displayed on the upper line. The error message is displayed on the lower line.

③ F C1 L ●

Actively operating: Flashing
 Image brightness: H = Original brightness of captured image
 L = Brightness reduced to half that in the captured image
 Output monitor status: C1 = Camera 1, C2 = Camera 2
 Image display mode: F = Freeze mode
 T = Through mode (raw image)

④ LOCK FULL VX.X ■

Flashes during communications
 System program version number
 Image scanning mode (this is only displayed on the IV-S33M)
 : FULL = full mode, HALF = half mode, F + H = full and half mode
 Lock the MAIN OPS MENU (operation screen)
 ("LOCK" is not displayed while the screen is unlocked. See page 6-6.)

⑤ Measurement No. (0 to 2), Camera No. (1 or 2), and the measurement to be carried out

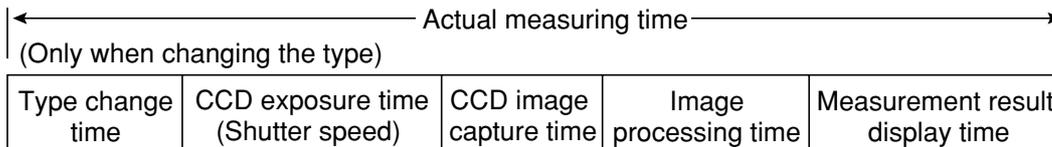
POSITIONING: MEAS 0 CAM 1 or MEAS 0 CAM 2

POS-CORRECT: MEAS 0 CAM 1 or MEAS 0 CAM 2

EXISTENCE: MEAS 1 CAM 1 or MEAS 2 CAM 2

⑥ Measuring time

- The screen shows the measuring time determined by the following (from measurement start to measurement end).



- The measuring time does not include the serial communication time.

- To decrease the measuring time:

1. Increase the shutter speed (page 7-12),
2. Change the CCD image capture mode (CAPTURE AN IMAGE) to PARTIAL-IMG (see page 7-7), and
3. Set the result displays (MESSAGE DISPLAY, PATTERN DISPLAY, SHOW BINARY IMG) to "NO" (see page 7-8 to 7-10).

⑦ Measurement result

- After you save* the specified conditions, the settings for the "Measured result screen" and "Image brightness: H/L" on the MAIN OPS MENU (operation screen) will be kept in memory, even when the power is turned OFF and ON again.

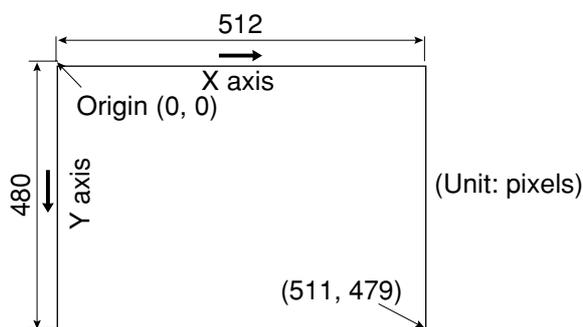
* To store the data, select "SAVE" on the menu bar.

⑧ Menu bar

Menu bar	Description	Positioning	Existence inspection (with correction)	Existence inspection (without correction)	Reference pages
CHG-TYPE	Change or register an object type.	●	●	●	7-11
POSI-COND	Go to the positioning condition setting screen.	●			7-14 to 7-16
POSI-EVAL	Set the positioning evaluation conditions	●			7-17
AUX-COND	Go to the position correction condition setting screen used in the existence inspection mode.			●	7-23
AUX-EVAL.	Specify the position correction evaluation conditions used in the existence inspection mode.			●	7-24
EXIST-COND	Go to the setting screen for specifying the existence inspection conditions.		●	●	7-18 to 7-22
EXIST-EVAL.	Specify the existence inspection evaluation conditions.		●	●	7-22
SEL-CAMERA	Switch the setting and the monitor display image between Camera1 and Camera 2 by pressing the SET key.	●	●	●	7-5
OPS-CND	Go to the OPS SET MENU setup screen.	●	●	●	7-7 to 7-10
SYS-CND	Go to the SYSTEM COND setup screen.	●	●	●	7-27 to 7-30
ADJ-CONTRAST	Change the image brightness between "L" and "H," by pressing the SET key.	●	●	●	7-4
SAVE	Store the evaluation and measurement conditions, such as reference images, in the flash memory.	●	●	●	7-26
SHUTTER	Specify the shutter speed.	●	●	●	7-12

[Image display area]

The size of the area where the image is displayed on the monitor is 512 (horizontal) pixels × 480 (vertical) pixels.



7-2 Image display

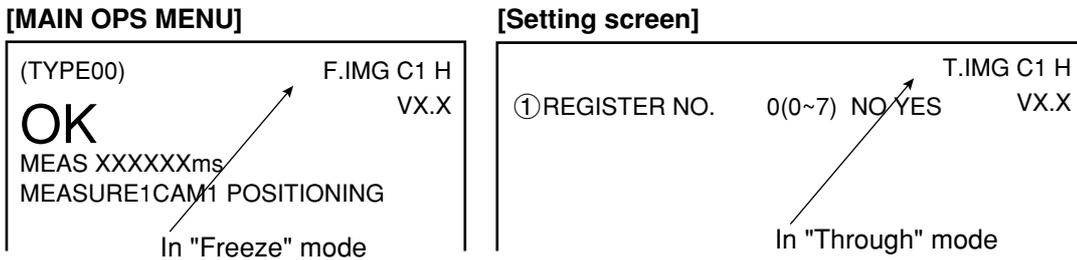
[1] Image display modes

There are two image display modes, i.e. through (moving images) and freeze (still images).

Display mode	Description
Through	- Raw images taken by the specified camera are displayed on the monitor. - This mode is used for adjusting the camera focus, adjusting an image, and moving a workpiece during testing.
Freeze	- When a measurement trigger is input, and an image is captured, the still image is displayed on the monitor. - This mode is used for setting measurement conditions, while looking at the still image, and for performing settings on the MAIN OPS MENU.

■ Changing operation

To change the image display mode between "freeze" and "through," use the SEL key on the remote keypad (IV-S30RK1).



Notes

- To register a reference image for gray scale searches

If these operations are started in the through mode, the message "CHANGE TO FREEZE MODE" will be displayed. Before starting these operations, change to the image F mode (freeze display mode).

[2] Adjustment of image brightness

The image brightness can be adjusted on any setting screen (other than the run screen) shown on the monitor.

- Purpose

This function is used when the image is so bright that the characters and pattern display are difficult to see.

- Status display

The brightness level, "H" or "L," is displayed in the upper right corner of the screen.

Level display	Description
H	The image captured by the camera is displayed at its original brightness.
L	The image captured by the camera is displayed at half the brightness of the original.

■ How to change the contrast

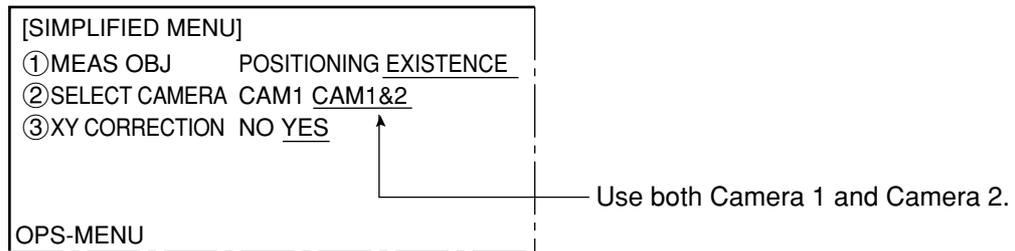
On the MAIN OPS MENU: Move the cursor to the "ADJ-CONTRAST" item using the left and right keys, and press the SET key.

On the contrast setting screen: Use the TRG/BRT key on the remote keypad to set the contrast (IV-S30RK1).

[3] Changing cameras

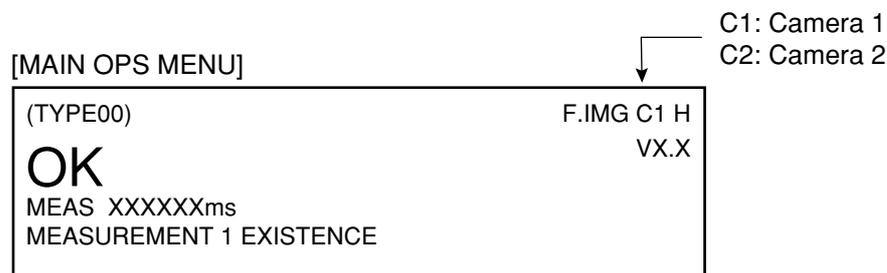
When two cameras have been connected to the controller, select the camera whose image will be displayed on the monitor.

You can display images from two cameras at the same time by selecting "CAM1&2" in the "② SELECT CAMERA" column on the [SIMPLIFIED MENU].



■ How to change cameras

Move the cursor to the "SEL-CAMERA" item using the left and right keys on the MAIN OPS MENU, and press the SET key.



The camera number that you specify on this menu will also be used for setting the measurement and evaluation conditions.

7-3 Setting functions that are different with each controller

The setting functions which depend on the individual controllers (IV-S31M/S32M/S33M) on the simplified menu are as follows:

Item	IV-S31M	IV-S32M	IV-S33M	Reference page (item)
Number of object types that can be registered	16	32	64	7-11 (Operation screen)
Camera setting	-	-	○	7-31, 7-32 (camera selection, image capture mode, camera synchronize)
Timer setting	-	○	○	7-27, 7-30 (system conditions)

(-: Unavailable, O: Available)

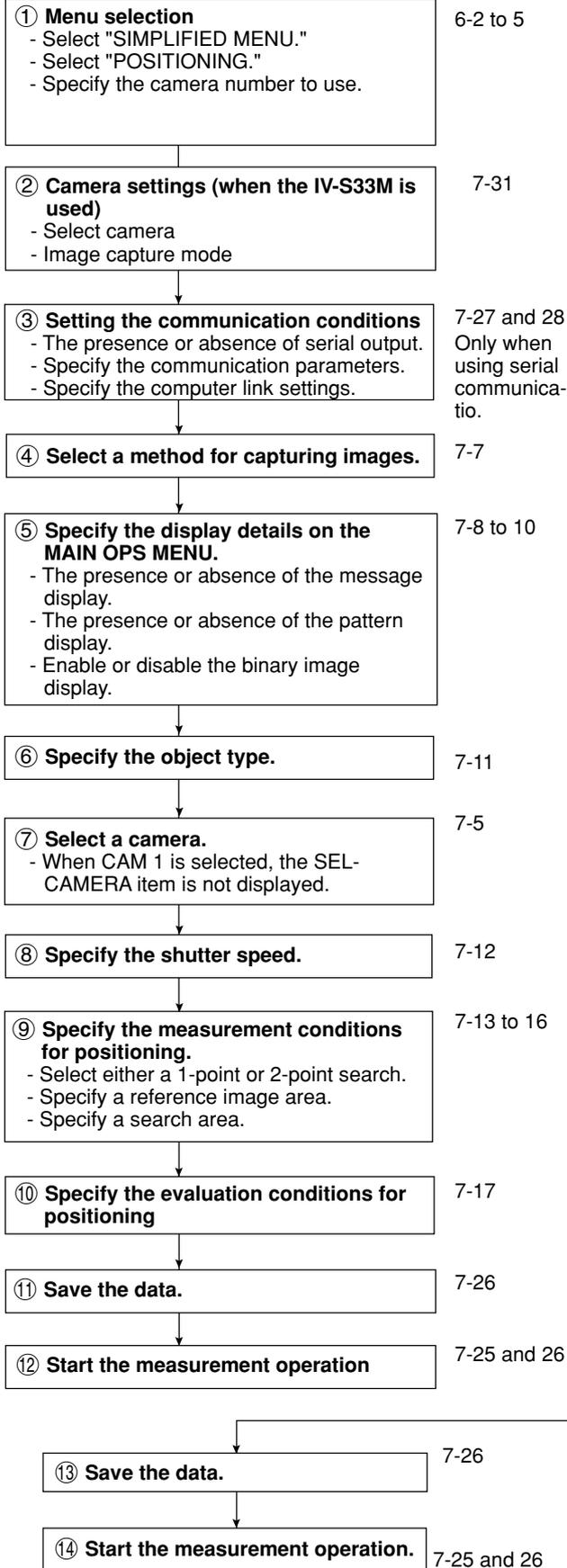
- For details about the standard menu, see the "IV-S30 User's Manual, Function and Operation, Ver. 2.0."

7-4 Setting procedures

The flow charts shown below outline the setting procedures on the simplified menus.

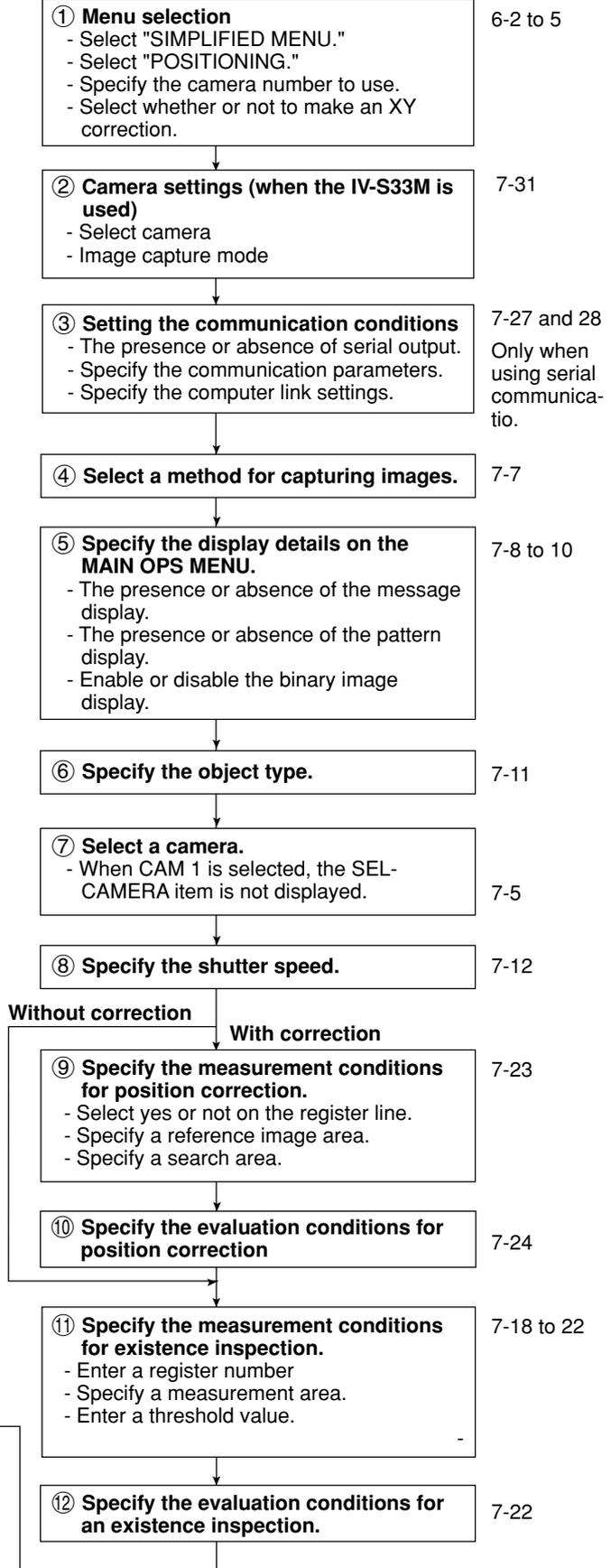
Positioning

(Reference pages)



Existence inspection

(Reference pages)



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7-5 Setting the operation conditions

[1] Image capture

Specify the range of lines which will be captured during operation.

On the MAIN OPS MENU, move the cursor to the "OPS-CND" item, and press the SET key.

[TYPE RUN COND]
① CAPTURE IMG PARTIAL-IMG WHOLE-IMG NO
② MESSAGE DISPLAY YES(NUMERIC) YES(NO NUMERIC) NO
③ PATTERN DISPLAY YES NO
④ SHOW BINARY IMG YES NO

① CAPTURE AN IMAGE	Description
PARTIAL-IMG (partial image)	- An image consisting of only the specified line, required for inspection or measurement, will be captured. - The number of lines is determined by the measurement window setting. - The processing time of a partial image is shorter than in the WHOLE-IMG mode.
WHOLE-IMG (whole image)	- A whole image will be captured, irrespective of the window settings for inspection or measurement. - This mode is used to monitor portions of an image outside the window set up for inspection or measurement. Note: When the IV-S33M is used and "FULL+HALF" is selected for the image capture mode (see page 7-31), it will process the whole area in the full mode.
NO (no image)	- No image will be captured during operation. Measurements will be carried out with an image currently being displayed. - This mode is only used to carry out measurements on an image transmitted from a personal computer to the IV-S30.

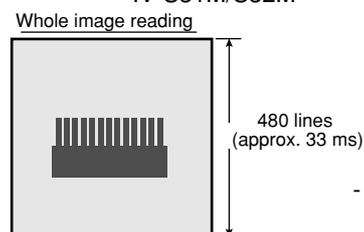
■ Operation procedure

1. On the [TYPE RUN COND] (shown above), move the cursor to the "① CAPTURE IMG" item with the up and down keys, and press the SET key.
2. Move the cursor to "PARTIAL-IMG," "WHOLE-IMG" or "NO" with the left and right keys, and press the SET key.

■ Example of a comparison of the capture times

- When "WHOLE-IMG" is specified

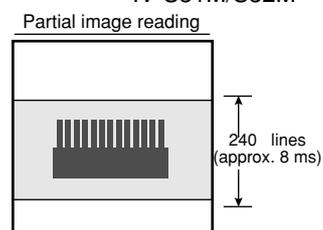
IV-S33M	16.7 ms (high-speed camera and full mode)
	8.3 ms (high-speed camera and half mode)
IV-S31M/S32M	33.3 ms (standard camera)



- Image capture mode (full/half mode)
⇒ See page 7-31

- When "PARTIAL-IMG" is specified: (When 240 scan lines is specified)

IV-S33M	8.3 ms (high-speed camera and full mode)*
	4.2 ms (high-speed camera and half mode)*
	12.5 ms (high-speed camera and full + half mode)*
IV-S31M/S32M	16.6 ms (standard camera)

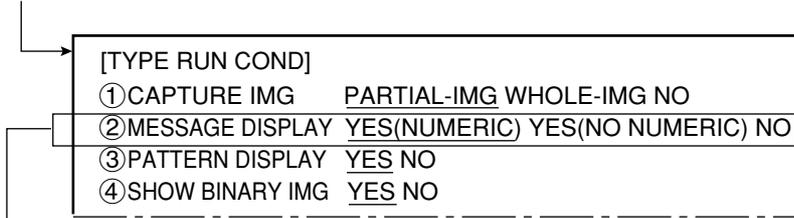


* The image capture time may vary with the position of the partial image. (In the example shown above, the maximum variation is 0.4 ms)

[2] Message display

Select "YES" or "NO" to display messages on the MAIN OPS MENU.

On the MAIN OPS MENU, move the cursor to the "OPS-CND" item, and press the SET key.



② MESSAGE DISPLAY	Description
YES (NUMERIC)	All information will be displayed.
YES (NO NUMERIC)	Information other than the numerical results will be displayed.
NO	No messages will be displayed.

Selecting "NO" reduces the processing time.

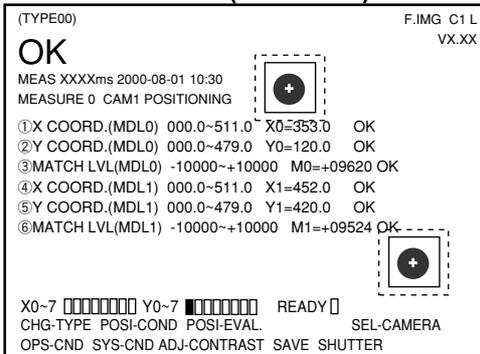
YES (NUMERIC) > YES (NO NUMERIC) > NO

■ Operation procedure

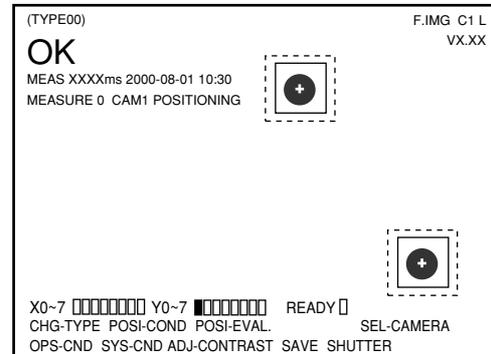
1. On the [TYPE RUN COND], move the cursor to the item "② MESSAGE DISPLAY" with the up and down keys, and press the SET key.
2. Move the cursor to "YES (NUMERIC)," "YES (NO NUMERIC)" or "NO" with the left and right keys, and press the SET key.

■ Display examples

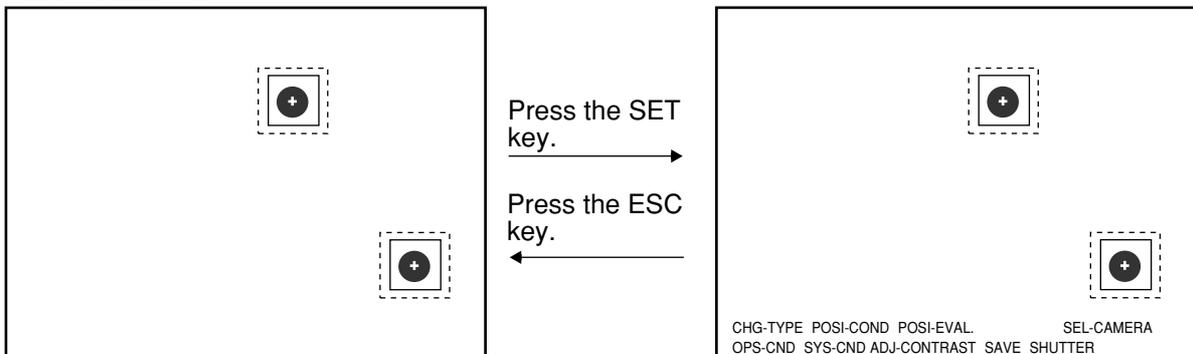
- When the message display mode has been set to YES (NUMERIC)



- When the message display mode has been set to YES (NO NUMERIC)



- When the message display mode has been set to NO

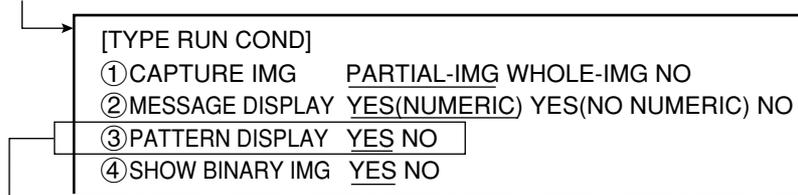


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[3] Pattern display

Select "YES or NO," to determine whether to display windows and other markings over the working image displayed on the MAIN OPS MENU.

On the MAIN OPS MENU, move the cursor to the "OPS-CND" item, and press the SET key.



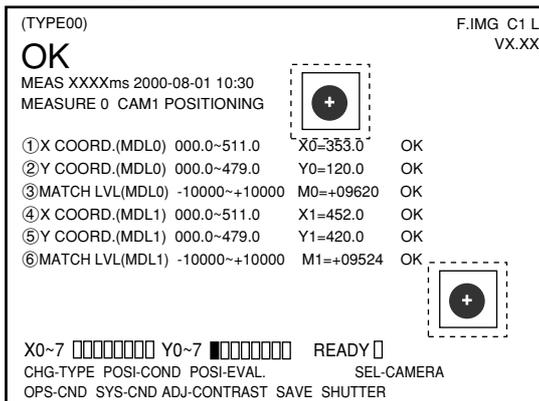
③ PATTERN DISPLAY	Description
YES	Patterns will be displayed on the [MAIN OPS MENU.]
NO	Patterns will not be displayed on the [MAIN OPS MENU.]

■ Operation procedure

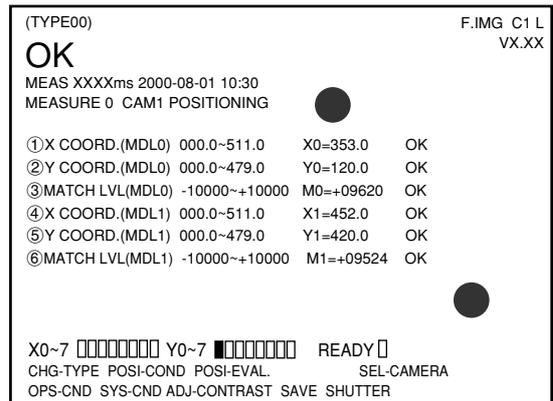
1. On the [TYPE RUN COND], move the cursor to the item "③ PATTERN DISPLAY" item with the up and down keys, and press the SET key.
2. Move the cursor to "YES" or "NO" with the right and left keys, and press the SET key.

■ Display examples

- When the pattern display mode has been set to YES.



- When the pattern display mode has been set to NO.



[4] Binary image display

Select "YES or NO" to display a binary image on the MAIN OPS MENU.

On the MAIN OPS MENU, move the cursor to "OPS-CND," and press the SET key.

[TYPE RUN COND]

① CAPTURE IMG PARTIAL-IMG WHOLE-IMG NO

② MESSAGE DISPLAY YES(NUMERIC) YES(NO NUMERIC) NO

③ PATTERN DISPLAY YES NO

④ SHOW BINARY IMG YES NO

④ SHOW BINARY IMG	Description
YES	A binary image will be displayed on the MAIN OPS MENU.
NO	A binary image will not be displayed on the MAIN OPS MENU.

The line "④SHOW BINARY IMG" will only be displayed when "③PATTERN DISPLAY" is set to "YES."

■ Operation procedure

1. On the [TYPE RUN COND], move the cursor to the "④ SHOW BINARY IMG" item with the up and down keys, and press the SET key.
2. Move the cursor to "YES" or "NO" with the left and right keys, and press the SET key.

■ Display examples

- When "show binary image" has been set to YES

(TYPE00) F.IMG C1 L
VX.XX

OK

MEAS XXXXms 2000-08-01 10:30

MEASUREMENT 1 EXISTENCE

① REG00	000000~245760	A00=018190	OK
② REG01	000000~245760	A01=	
③ REG02	000000~245760	A02=	
④ REG03	000000~245760	A03=	
⑤ REG04	000000~245760	A04=	●
⑥ REG05	000000~245760	A05=	
⑦ REG06	000000~245760	A06=	
⑧ REG07	000000~245760	A07=	

X0~7 ██████████ Y0~7 ██████████ READY

CHG-TYPE EXIST-COND EXIST-EVAL. SEL-CAMERA

OPS-CND SYS-CND ADJ-CONTRAST SAVE SHUTTER

- When "show binary image" has been set to NO

(TYPE00) F.IMG C1 L
VX.XX

OK

MEAS XXXXms 2000-08-01 10:30

MEASUREMENT 1 EXISTENCE

① REG00	000000~245760	A00=018190	OK
② REG01	000000~245760	A01=	
③ REG02	000000~245760	A02=	
④ REG03	000000~245760	A03=	
⑤ REG04	000000~245760	A04=	○
⑥ REG05	000000~245760	A05=	
⑦ REG06	000000~245760	A06=	
⑧ REG07	000000~245760	A07=	

X0~7 ██████████ Y0~7 ██████████ READY

CHG-TYPE EXIST-COND EXIST-EVAL. SEL-CAMERA

OPS-CND SYS-CND ADJ-CONTRAST SAVE SHUTTER

7-6 Setting object types

Specify the type of object to be measured. A number of object types can be registered (16 types (0 to 15) on the IV-S31M, 32 types (0 to 31) on the IV-S32M and 64 types (0 to 63) on the IV-S33M).

■ Setting procedure

1. Move the cursor to the "CHG-TYPE" item on the MAIN OPS MENU using the left and right keys and then press the SET key.
⇒ The object type setting list will be displayed.

(TYPE00)	F.IMG C1 L
	VX.XX
MEAS XXXXms 2000-08-01 10:30	Object type No. (00 to 63)
MEASURE0 CAM1 POSITIONING	O: Registered x: Not registered
00 × 08 × 16 × 24 × 32 × 40 × 48 × 56 ×	
01 × 09 × 17 × 25 × 33 × 41 × 49 × 57 ×	
02 × 10 × 18 × 26 × 34 × 42 × 50 × 58 ×	
03 × 11 × 19 × 27 × 35 × 43 × 51 × 59 ×	
04 × 12 × 20 × 28 × 36 × 44 × 52 × 60 ×	
05 × 13 × 21 × 29 × 37 × 45 × 53 × 61 ×	
06 × 14 × 22 × 30 × 38 × 46 × 54 × 62 ×	
07 × 15 × 23 × 31 × 39 × 47 × 55 × 63 ×	
X0~7 □□□□□□□□ Y0~7 □□□□□□□□ READY □	
CHG-TYPE POSI-COND POSI-EVAL.	
OPS-CND SYS-CND ADJ-CONTRAST SAVE SHUTTER	

When the IV-S33M is used

[When the IV-S31M is used 00 to 15]
[When the IV-S32M is used 00 to 31]

2. Move the cursor to the object number that you want to set up using the up and down keys, and press the SET key.

⇒ The object type conditions can then be specified. (○: Registered, ×: Not registered)

[When the IV-S33M is used, "Object type number 00 Yes/No" will be displayed. Select "Yes" by pressing the left and right cursor keys.]

E.g.) The registered conditions for object type 00

(TYPE00)	F.IMG C1 L
	VX.XX
MEAS XXXXms 2000-08-01 10:30	
MEASURE0 CAM1 POSITIONING	
00 ○ 08 × 16 × 24 × 32 × 40 × 48 × 56 ×	
01 × 09 × 17 × 25 × 33 × 41 × 49 × 57 ×	
02 × 10 × 18 × 26 × 34 × 42 × 50 × 58 ×	

- The object type currently selected by the cursor will be the place where the measurement and evaluation conditions are stored and the operation will be executed.
- After setting up the object type, if you press the SET key again, the settings will be ignored.

7-7 Setting the shutter speed

- The shutter speed can be set independently for each object type.
- Since the shutter speed can be set continuously in the range of 1/30 to 1/10,000 of a second, very fine adjustment is possible.
- If you want to measure moving objects and increase the image processing speed, set the shutter speed to around 1/1000 or 1/2000 seconds. However, if you use a faster shutter speed than you need, very bright lights will be necessary, and bright lighting is not economical.
- For details about the relationship between the brightness of objects (objects to be measured) and the shutter speed, see section "5-1 [2] Illumination and shutter speed."

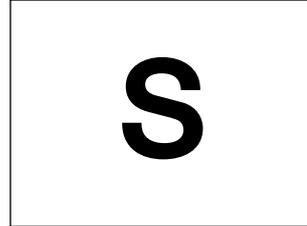
[Example]

- When the shutter speed is slow
(1/60 of a second)



The object is blurred across the screen.

- When the shutter speed is fast
(1/1000 of a second)



The object is frozen on the screen.

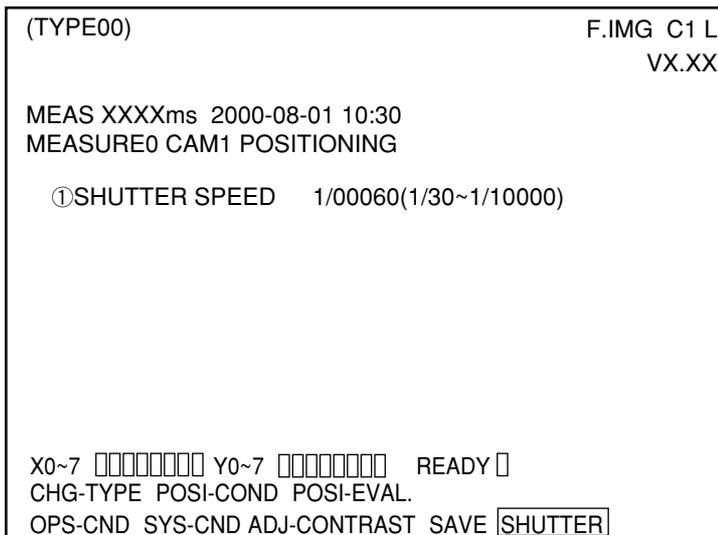
Setting procedure

1. Move the cursor to the SHUTTER item on the MAIN OPS MENU using the left and right keys, and press the SET key.
⇒ The shutter speed will be displayed.
2. Press the SET key.
3. Press the SET key again, and move the cursor to the digit you want, using the left and right keys.

1/00060

This cursor will move to the left and right.

4. Set the value using the up and down keys.
5. Repeat steps 3 and 4 to set each digit.
6. After setting all of the digits, press the SET key.



7. To complete the setting of the shutter speed, press the ESC key.

7-8 Setting the positioning conditions

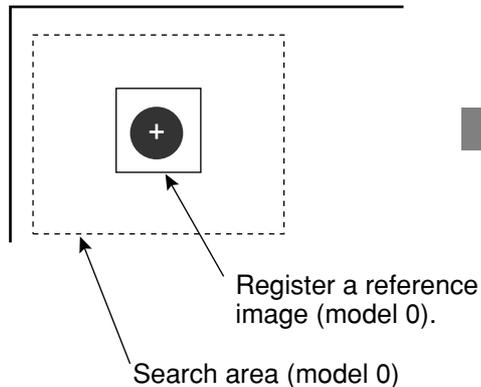
In the positioning function, you can measure the absolute position of the workpiece using a gray search, and also the degree of match between the measured image and the reference image.

It is also possible to evaluate whether the measurement result is within the OK range.

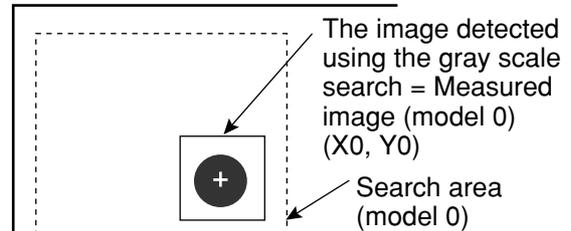
The gray scale search has two search modes: a 1-point search (measuring one point) and a 2-point search (measuring two points).

(1) 1-point search

When a reference image is registered



When operating

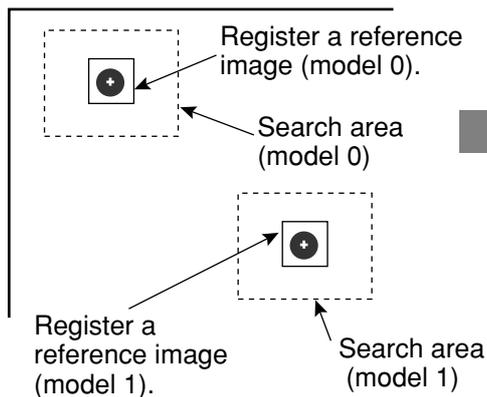


[Measured result]

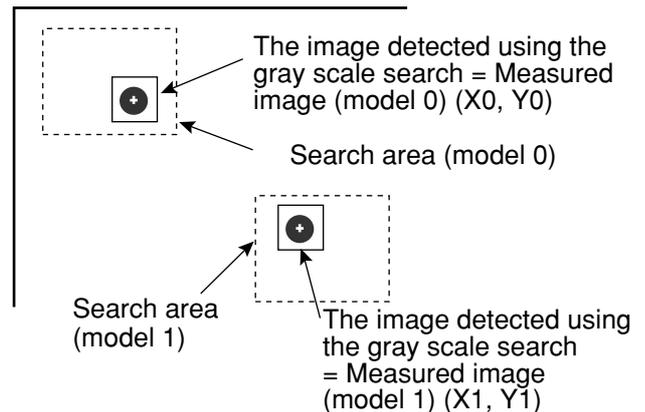
- Center coordinates of the measured image
X0 = 0 to 511.0 Y0 = 0 to 479.0
- Degree of match between the reference image and the measured image
M0 = - 10000 to + 10000

(2) 2-point search

When a reference image is registered



When operating



[Measured result]

- Range of center coordinates of the measured image
Model 0 X0 = 0 to 511.0 Y0 = 0 to 479.0
Model 1 X1 = 0 to 511.0 Y1 = 0 to 479.0
- Range of degree of match between the reference image and the measured image
Model 0 M0 = - 10000 to + 10000
Model 1 M1 = - 10000 to + 10000

* The degree of match refers to the level of sameness in the corresponding pixels when comparing the reference image and the image of the measured object.

E.g.: + 09640 ⇒ 96.4 %

● Gray scale search conditions

Pixel contraction: Search the image in units of 4 pixels.
(This is equal to a pixel contraction setting of "2" in the CONTR. PIXEL line on the standard menu.)

Detection precision: In units of pixels
(This equals the "STANDARD" detection precision setting in the DTECT PRECISION line on the standard menu.)

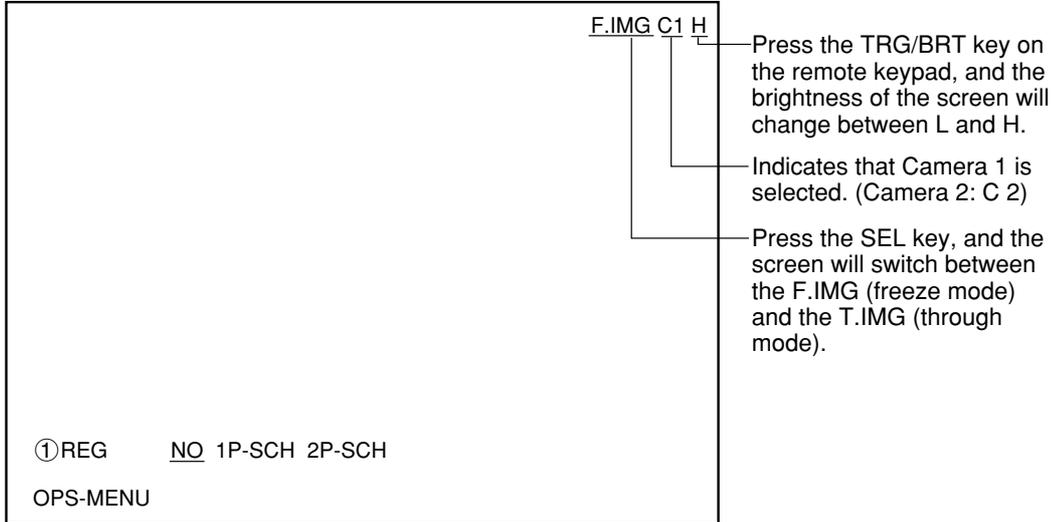
Detection coordinate: The center of the rectangular window

[1] Setting the measurement conditions

Set the reference image area and the search area using rectangular windows.

■ Setting procedure

1. Move the cursor to the "POSI-COND" item on the menu bar of the MAIN OPS MENU, and press the SET key.
 ⇨ The screen will change to the measurement condition setting screen.



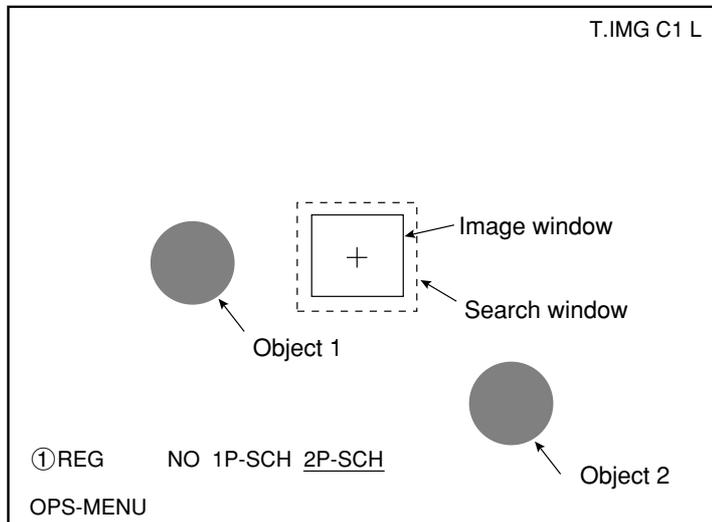
Note

- Before setting the measurement conditions, make sure to select camera type (when the IV-S33M is used: page 7-31), set the object type (page 7-11), and select camera (page 7-5).

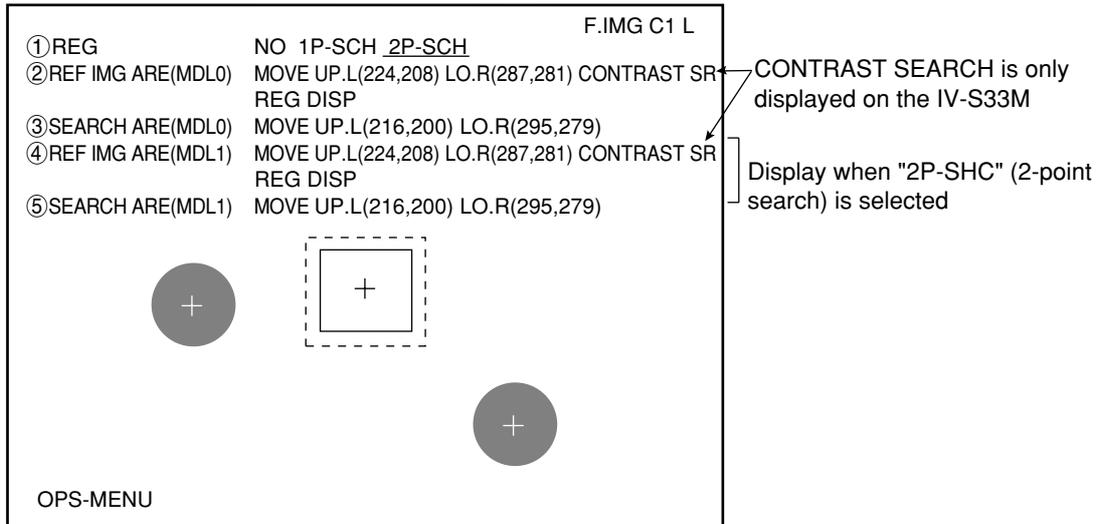
2. Press the SEL key.
 ⇨ The image will be displayed. The indicator in the upper right corner of the screen will change from F (freeze) to T (through).

When the image is so bright that the menu display is difficult to see, press the TRG/BRT key to reduce the brightness of the image. The indicator in the upper right corner of the screen will change from "H" to "L."

3. To display the image of the object measured clearly, adjust the focus and iris opening of the camera lens.
4. Move the cursor to the "① REG" line, and press the SET key. Then, move the cursor to the "1P-SCH" or "2P-SCH" item, and press the SET key.
 ⇨ The image window and search window will be displayed in the center of the screen.



5. Press the SEL key to change the screen to the freeze mode.
 - ⇒ The indicator in the upper right corner of the screen will change from T to F.
 - To register reference images, you must make sure to display the freeze screen.
6. Press the ESC key to display all of the measurement condition items.

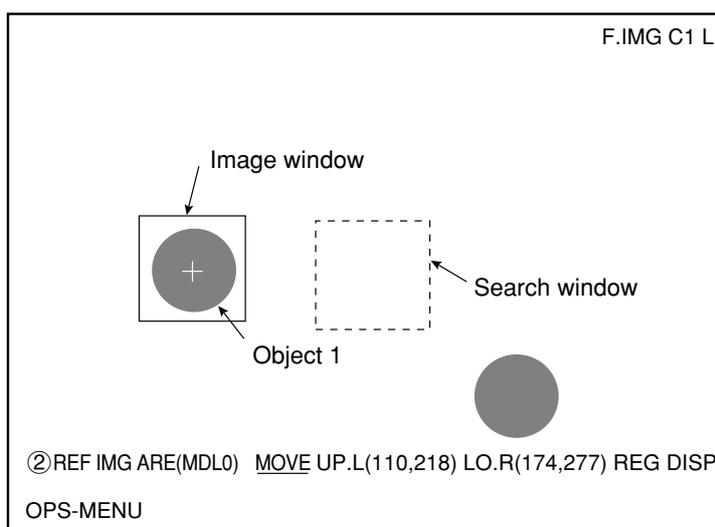


- If the menu overlaps the object to be measured, so that further image condition setting is difficult, press the ESC key. Only one item will be displayed at a time. (You can move the cursor to each item and display each of them in order on the screen, using the up and down keys. The following illustration shows only one item being displayed.)

7. Move the cursor to the "② REF. IMG ARE (MDL 0)" item, and press the SET key.
8. Surround the object to be measured with the image window (solid line).
 - Move the cursor to the "MOVE," "UP.L," or "LO. R," label and press the SET key.

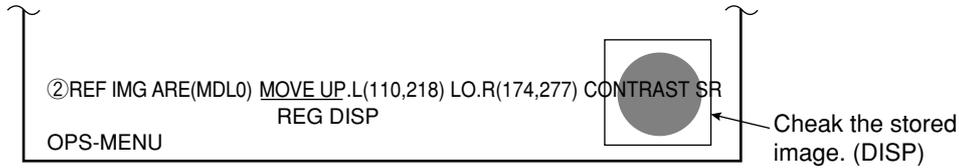
MOVE	The whole rectangle is moved using the up, down, left or right keys (one pixel at a time).
UP.L	The upper left corner is moved using the up, down, left or right keys (one pixel at a time).
LO.R	The lower right corner is moved using the up, down, left or right keys (one pixel at a time).

After the window position has been finalized, press the SET key.

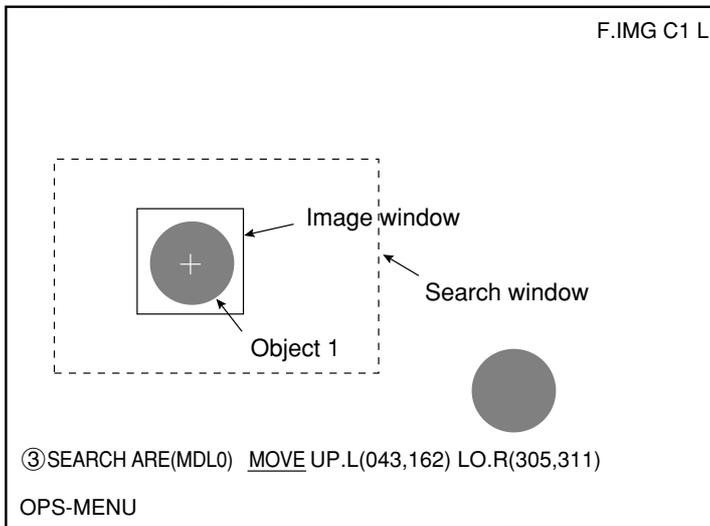


Simplified Menu Operation

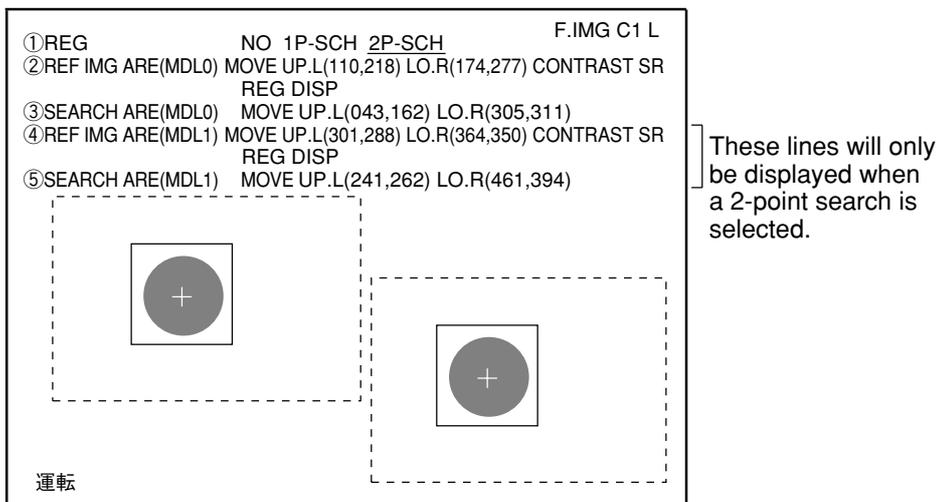
9. After the image window position has been set, move the cursor to the "REG." item using the left and right keys, and press the SET key.
- ⇒ The image will be registered in the memory and displayed in lower right corner of the screen.
 - Move the cursor to the "DISP" item using the left and right keys, and press the SET key. Then, the stored image will be displayed in the lower right corner of the screen. After checking the image, press the ESC key.



10. Press the ESC key and move the cursor to the "③ SEARCH ARE (MDL 0)" item. Then, press the SET key.
11. Create a search window to be used as the search area (area to be used for a gray scale search).
- The procedure for creating the search area is the same as described for the image window in step 8.



12. Press the ESC key.
13. When a 2-point search is selected in the "① REG" line, set items "④ REF. IMG ARE (MDL 1)" and "⑤ SEARCH ARE (MDL 1)" by following the same procedures described in steps 7 to 12.
14. Press the ESC key to display all of the measurement condition items.



15. Move the cursor to the "OPS-MENU" item using the up and down keys, and press the SET key.
- ⇒ The screen will return to the MAIN OPS MENU. That completes the setting of the measurement conditions.

[2] Setting the position evaluation conditions

Set the X and Y coordinates for the image to be measured, and the OK range that will be used for the degree of match.

■ Setting procedure

1. Move the cursor to the "POSI-EVAL." item on the MAIN OPS MENU using the left and right keys, and press the SET key.
⇒ The position evaluation conditions will be displayed.

(TYPE00)	F.IMG C1 L
	VX.XX
MEAS XXXXms 2000-08-01 10:30	
MEASURE 0 CAM1 POSITIONING	
①X COORD.(MDL0) 000.0~511.0	X0=
②Y COORD.(MDL0) 000.0~479.0	Y0=
③MATCH LVL(MDL0) -10000~+10000	M0=
④X COORD.(MDL1) 000.0~511.0	X1=
⑤Y COORD.(MDL1) 000.0~479.0	Y1=
⑥MATCH LVL(MDL1) -10000~+10000	M1=
X0~7 <input type="text"/> Y0~7 <input type="text"/> READY <input type="checkbox"/>	
CHG-TYPE POSI-COND <input type="checkbox"/> POSI-EVAL <input type="checkbox"/> SEL-CAMERA	
OPS-CND SYS-CND ADJ-CONTRAST SAVE SHUTTER	

2. Move the cursor to the item you want to set or change using the up and down keys, and press the SET key.
3. Move the cursor to the minimum and maximum values using the left and right keys, and press the SET key
4. Move the cursor to each digit using the left and right keys, and increase or decrease the value using the up and down keys. Then, press the SET key.
5. Press the ESC key.
6. Press the ESC key again. That completes the setting of the position evaluation conditions.

7-9 Setting the existence inspection conditions

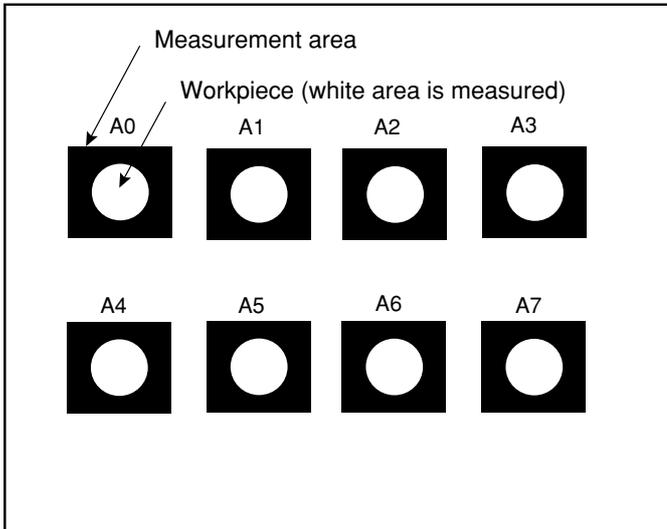
The existence inspection function lets you determine whether or not a workpiece is present by measuring the area after binary conversion.

Each object type can have up to 16 areas registered for it (8 each for Camera 1 and 8 more for Camera 2).

You can correct the measuring area's X and Y specifications for conversion into binary, using the correction values supplied by the gray search function.

In addition, you can evaluate whether the measurement result is within the OK range.

(1) When the XY correction function is set to "NO"

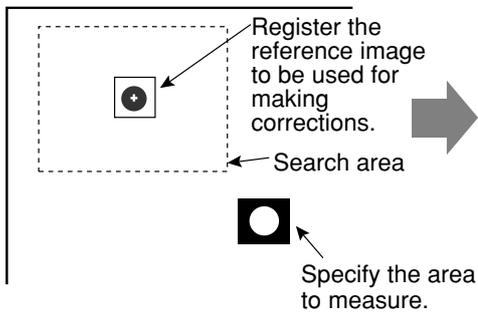


[Measurement result]

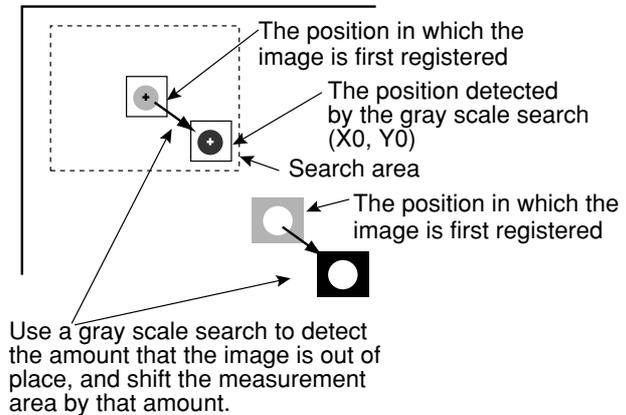
- The area of each workpiece A0 to A7 = 0 to 245760

(2) When the XY correction function is set to "YES"

When a reference image is registered



When operating



[Measured result]

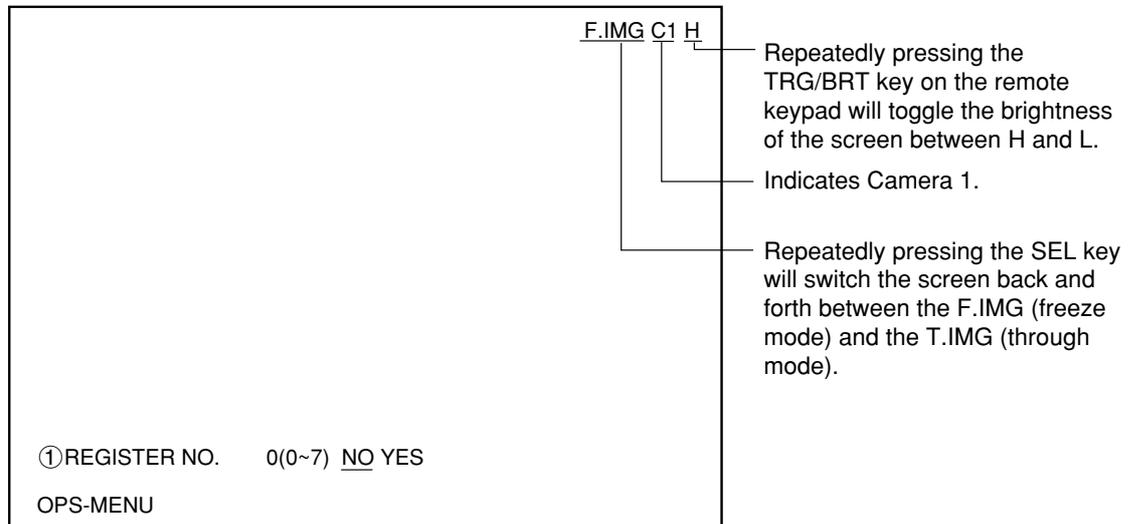
- Center coordinates of the measured image that needs to be corrected
X0 = 0 to 511.0 Y0 = 0 to 479.0
- Degree of match between the reference image and the measured image M0 = - 10000 to + 10000
- The area of the workpiece (white area is measured)
A0 to A7 = 0 to 245760

[1] Setting the measurement conditions

Define the binary measurement area using a rectangular window.

■ Setting procedure

1. Move the cursor to the "EXIST-COND" item on the menu bar of the MAIN OPS MENU, and press the SET key.
⇒ The screen will change to the measurement condition setting screen.



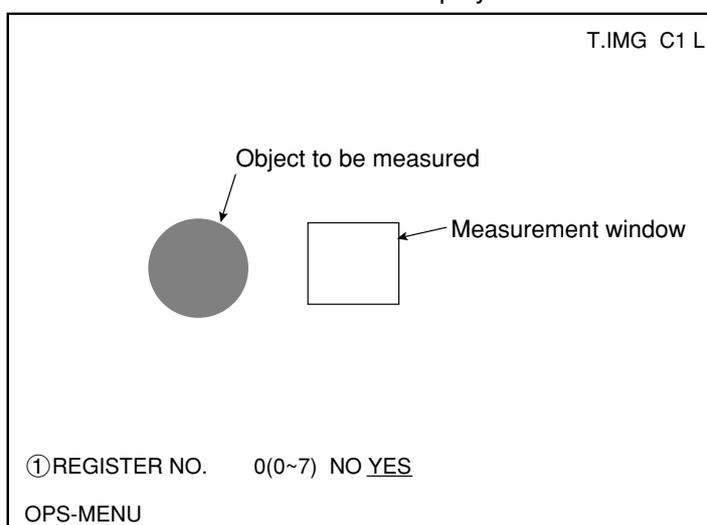
Note

- Before setting the measurement conditions, make sure to select camera type (when the IV-S33M is used: page 7-31), set the object type (page 7-11) and select camera (page 7-5).

2. Press the SEL key.
⇒ The image will be displayed. The indicator in the upper right corner of the screen will change from F (freeze) to T (through).

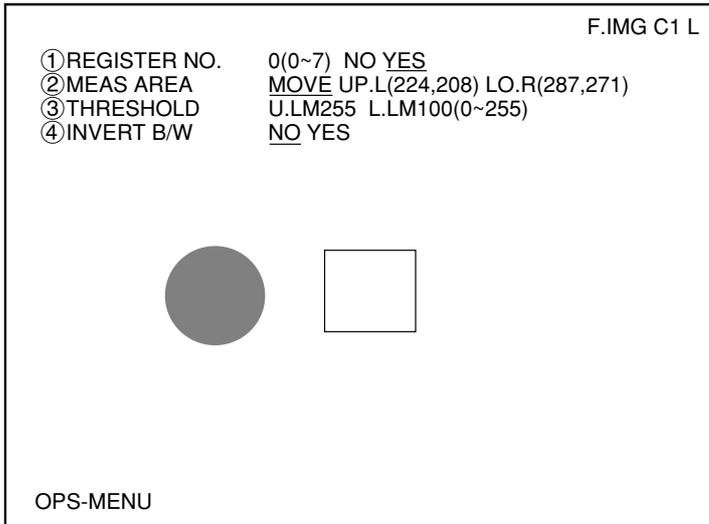
When the image is so bright that the menu display is difficult to see, press the TRG/BRT key to reduce the brightness of the image. The indicator in the upper right corner of the screen will change from "H" to "L."

3. To display the image of the object measured clearly, adjust the focus and iris opening of the camera lens.
4. Move the cursor to the "① REGISTER NO." line, and press the SET key. Select a register No. (0 to 7) using the up and down keys, and move the cursor to "YES" using the left and right keys. Then, press the SET key.
⇒ The measurement window will be displayed in the center of the screen.



Simplified Menu Operation

5. Press the SEL key to change the screen to the freeze mode.
 - ⇒ The indicator in the upper right corner of the screen will change from T to F.
 - To set a threshold for a binary area, make sure the machine is displaying the freeze screen.
6. Press the ESC key to display all of the measurement condition items.

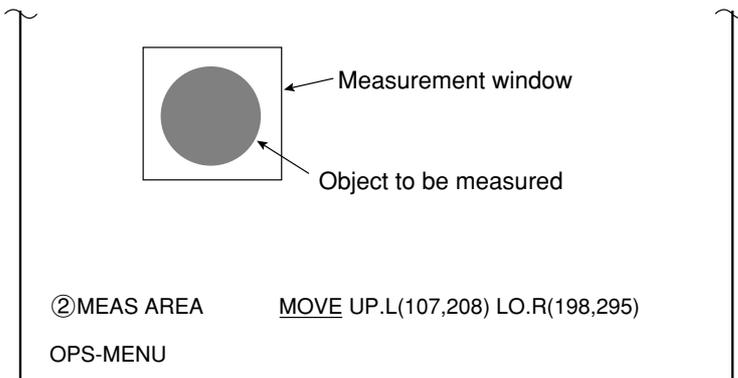


- If the menu overlaps the object to be measured, so that further image condition setting is difficult, press the ESC key. Only one item "①" will be displayed at a time. (You can move the cursor to each item and display each of them in order on the screen, using the up and down keys. The following illustration shows only one item being displayed.)

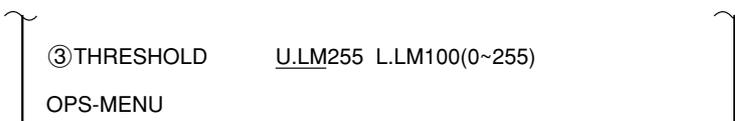
7. Move the cursor to the "② MEAS AREA" item, and press the SET key.
8. Place a measurement window around the object to be measured (solid line).
 - Move the cursor to the "MOVE," "UP.L" or "LO.R," and press the set key.

MOVE	The whole rectangle is moved using the up, down, right or left keys (one pixel at a time).
UP.L	The upper left corner is moved using the up, down, right or left keys (one pixel at a time).
LO.R	The lower right corner is moved using the up, down, right or left keys (one pixel at a time).

-After the window position has been finalized, press the SET key.



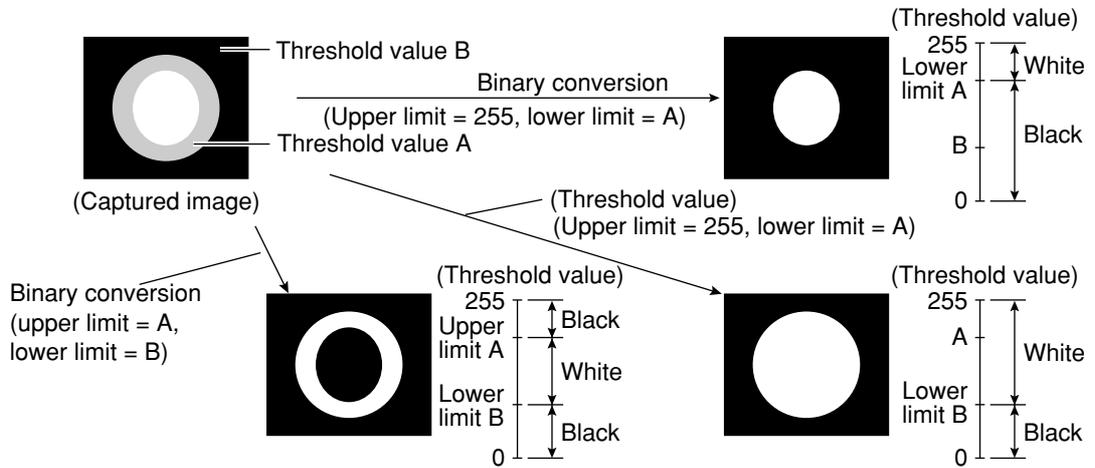
9. After the measurement window position is satisfactory, press the SET key.
10. Move the cursor to the "③ THRESHOLD" item using the up and down keys, and press the SET key.



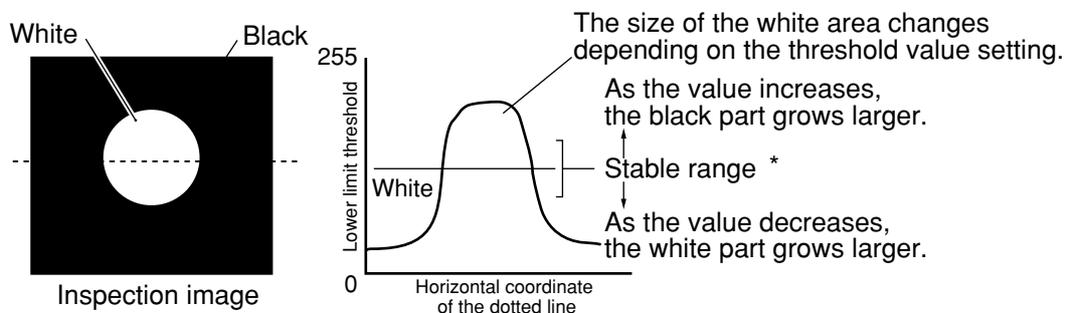
11. Move the cursor to the "U.LM" or "L.LM" items and then press the SET key.
12. Move the cursor to each digit using the left and right keys, and increase or decrease the values using the up and down keys. Then, press the SET key.

Threshold value setting

The IV-S30 treats the "areas darker than the lower limit value" or "brighter than the upper limit value" as "black." It treats that the areas between the upper limit value and lower limit value as "white." However, if the white-black reverse function is enabled, conversion to white/black will be reversed. Normally, if you want to use only one threshold value for binary conversion, set the upper limit value to "255." Then you only need to adjust the lower limit value to a threshold value that works for your application.



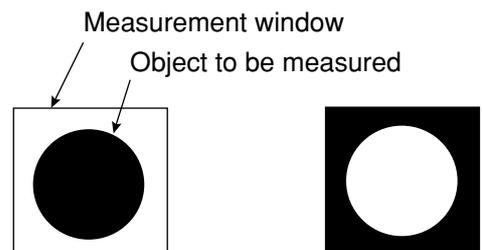
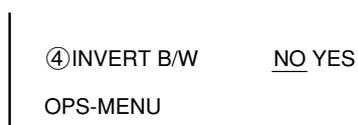
An example of adjustment is shown below, using a white object on a black background. When the dotted line in the window is converted to a binary image, if the lower limit is set higher, the black part in the binary image will become larger. If the lower limit is set lower, the white part will become larger. Increase and decrease the lower limit value, find the value at which the white part in the binary image starts growing and the value at which the black part starts growing. Then set the lower limit at the value halfway between these points. This will ensure reliable operation.



Changing the lower limit threshold value

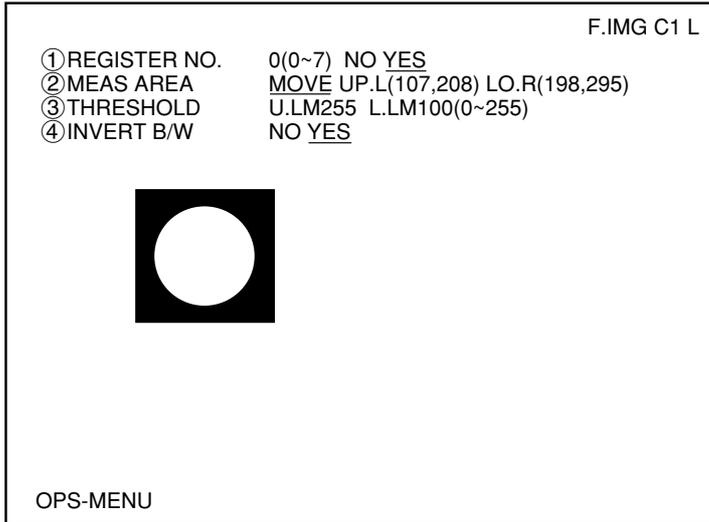
[* If the stable range in the lower limit threshold value is less than 20, (actual measurement) measurement errors may occur.]

13. Move the cursor to the "④ INVERT B/W" item using the up and down keys, and press the SET key.



14. Move the cursor to "NO" or "YES" using the left and right keys, and press the SET key.
 - Since only the number of white pixels can be measured, select "YES" if the object is black.

15. Press the ESC key to display all of the measurement condition items.



16. Move the cursor to the "OPS-MENU" item using the up and down keys, and press the SET key.
 ⇨ The screen will return to the MAIN OPS MENU. That completes the setting of the measurement conditions.

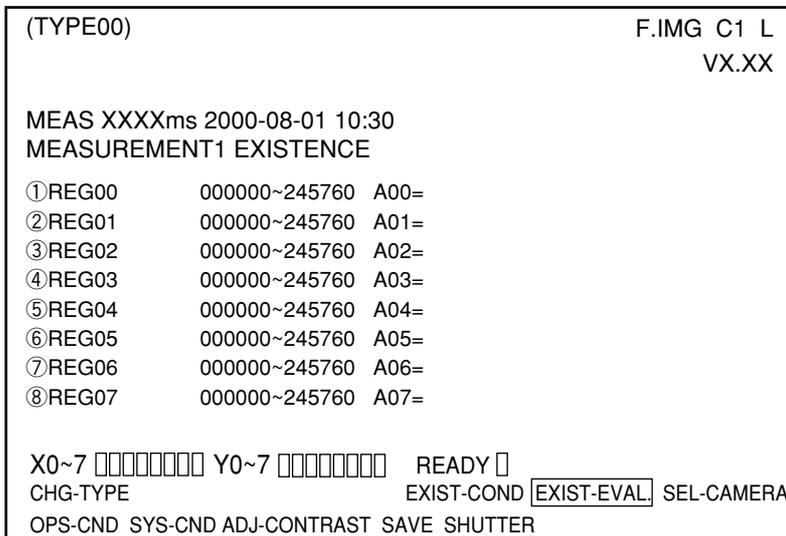
7

[2] Setting the evaluation conditions

Set the OK range for a measured area.

■ Operating procedure

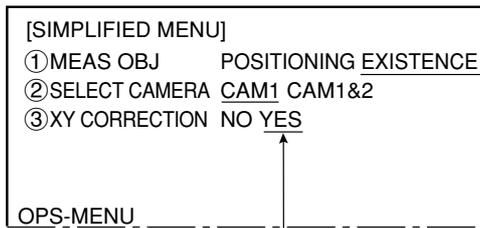
1. Move the cursor to the "EXIST-EVAL." item on the MAIN OPS MENU using the left and right keys, and press the SET key.
 ⇨ The evaluation conditions will be displayed.



2. Move the cursor to the item you want to set using the up and down keys, and press the SET key.
3. Move the cursor to the minimum and maximum value entries using the left and right keys, and press the SET key
4. Move the cursor to each digit using the left and right keys, and increase or decrease the values using the up and down keys. Then, press the SET key.
5. Press the ESC key.
6. Press the ESC key again. That completes the setting of the evaluation conditions.

[3] Setting the measurement conditions for correcting a position

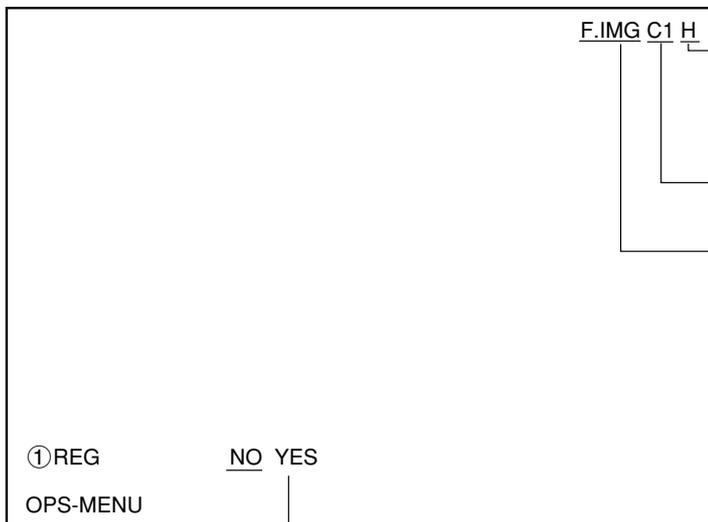
When the "③ XY CORRECTION" item is set to "YES" on the [SIMPLIFIED MENU] screen, when the position of the object to be measured is not correct, the correct area can still be measured by correcting the position.



Select "YES" to run the XY correction function.

■ Operating procedure

1. Move the cursor to the "AUX-COND" item on the menu bar of the MAIN OPS MENU, and press the SET key.
 ⇨ The screen will change to the measurement condition setting screen.



Repeatedly pressing the TRG/BRT key on the remote keypad will toggle the brightness of the screen between H and L.

Indicates Camera 1.
(Camera 2: C 2)

Repeatedly pressing the SEL key will switch the screen back and forth between the F.IMG (freeze mode) and the T.IMG (through mode).

When "YES" is selected, a 1-point search is enabled.

The following procedures are the same as the 1-point search made for positioning. (See page 7-14 to 7-16.)

Notes

- Before setting the measurement conditions, make sure to select camera type (when the IV-S33M is selected : page 7-31), set the object type (page 7-11) and select camera (page 7-5). Select the same object type No. and Camera No. as were used for the existence inspection condition settings.

[4] Setting the evaluation conditions for correcting a position

Set the X and Y coordinates of the image used for making the correction, and the OK range that will be used for determining the degree of match.

■ Operating procedure

1. Move the cursor to the "AUX-EVAL" item on the MAIN OPS MENU using the left and right keys, and press the SET key.
⇒ The evaluation conditions will be displayed.

```
(TYPE00)                                F.IMG C1 L
                                           VX.XX

MEAS XXXXms 2000-08-01 10:30
MEASURE0 CAM1 POSITION CORRECTION

①X COORD. (MDL0) 000.0~511.0    X0=
②Y COORD. (MDL0) 000.0~479.0    Y0=
③MATCH LVL (MDL0) -10000~+10000 M0=

X0~7 □□□□□□□□ Y0~7 □□□□□□□□  READY □
CHG-TYPE AUX-COND AUX-EVAL EXIST-COND EXIST-EVAL. SEL-CAMERA
OPS-CND SYS-CND ADJ-CONTRAST SAVE SHUTTER
```

2. Move the cursor to the item you want to set using the up and down keys, and press the SET key.
3. Move the cursor to the minimum and maximum value entries using the left and right keys, and press the SET key
4. Move the cursor to each digit using the left and right keys, and increase or decrease the values using the up and down keys.
5. Press the ESC key.
6. Press the ESC key again. That completes the setting of the evaluation conditions.

7-10 Measurement triggering

[1] Trigger measurement

The IV-S30 has three methods for triggering measurements, as shown below.

- ① Using the TRG/BRT key on the remote keypad
- ② Triggered by an input terminal (IV-S31M : X0 to X4, IV-S32M : X0 to X5, IV-S33M : X0 to X6)
- ③ Triggered by a message on the general-purpose serial communication port

(1) Using the TRG/BRT key

1. Select the object type No. that you want to measure on the MAIN OPS MENU. ⇨ See page 7-11.
2. Press the TRG/BRT key to start the measurement function. The result will be displayed on the monitor.

■ A display example of positioning

```

(TYPE00)                                     F.IMG C1 L
OK                                             VX.XX
MEAS XXXXms 2000-08-01 10:30
MEASURE 0 CAM1 POSITIONING
①X COORD.(MDL0) 250.0~260.0 X0=253.0 OK
②Y COORD.(MDL0) 210.0~230.0 Y0=220.0 OK
③MATCH LVL(MDL0) -10000~+10000 M0=+09620 OK
④X COORD.(MDL1) 150.0~160.0 X1=156.0 OK
⑤Y COORD.(MDL1) 055.0~058.0 Y1=056.0 OK
⑥MATCH LVL(MDL1) -10000~+10000 M1=+09524 OK

X0~7 □□□□□□□□ Y0~7 ■□□□□□□□ READY □
CHG-TYPE [POSI-COND] POSI-EVAL. SEL-CAMERA
OPS-CND SYS-CND ADJ-CONTRAST SAVE SHUTTER

```

■ A display example of an existence inspection

```

(TYPE00)                                     F.IMG C1 L
OK                                             VX.XX
MEAS XXXXms 2000-08-01 10:30
MEASUREMENT 1 EXISTENCE
①REG00      001600~001650 A00=001619 OK
②REG01      000000~245760 A01=
③REG02      002600~027000 A02=026720 OK
④REG03      000000~245760 A03=
⑤REG04      000000~245760 A04=
⑥REG05      000000~245760 A05=
⑦REG06      000000~245760 A06=
⑧REG07      000000~245760 A07=

X0~7 □□□□□□□□ Y0~7 ■□□□□□□□ READY □
CHG-TYPE [EXIST-COND] EXIST-EVAL. SEL-CAMERA
OPS-CND SYS-CND ADJ-CONTRAST SAVE SHUTTER

```

(2) Triggered by an input terminal

When the measurement start input (input terminal: X0) on the MAIN OPS MENU changes from OFF to ON, the IV-S30 will start the measurement function. Specify the object type No. that will be measured on input terminals, (IV-S31M : X1 to X4, IV-S32M : X1 to X5, IV-S33M : X1 to X6) ⇨ See page 5-17 and 5-18.

(3) Triggered by a message on the general-purpose serial communication port

In this method, the IV-S30 and a personal computer communicate with each other using commands and responses.

- Specify the communication setting parameters by referring to the "② COMM. SET" item on the [SYSTEM COND] menu. ⇨ See page 7-27
- For details about the communication commands, see the IV-S30 User's Manual (Function and Operation).

[2] Result output

The IV-S30 has three methods for outputting results, as shown below.

- ① Output on the output terminals (Y0, Y1)
- ② Output over the general-purpose serial communication port
- ③ Output using a programmable controller computer link

(1) Output on the output terminals

The IV-S30 outputs the measured result to the output terminal.

Y0: Final output result

This will be ON when the results of all the items are OK. (This is equivalent to the auxiliary relay C112.)

Y1: Measurement execution error

This will be ON when a measurement processing error occurs. (This is equivalent to the auxiliary relay C118.)

For details about the auxiliary relays C112 and C118, see the IV-S30 User's manual (Function and Operation).

(2) Output over the general-purpose serial communication port

With this method, the IV-S30 and a personal computer communicate with each other using commands and responses.

- Specify the serial port parameters in the items "① SERIAL OUTPUT" and "② COMM. SET" on the [SYSTEM COND] menu. ⇨ See page 7-27.
- For details about the communication commands, see the IV-S30 User's Manual (Function and Operation).

(3) Output using a programmable controller computer link

With this method, the IV-S30 and a programmable controller communicate with each other using the computer link.

- Specify the computer link setting parameters in the items "① SERIAL OUTPUT," "② COMM. SET" and "③ COMPUTER LINK" on the [SYSTEM COND] menu. ⇨ See pages 7-27 and 7-28.
- For details about the computer link, see the IV-S30 User's Manual (Function and Operation).

7-11 Saving data

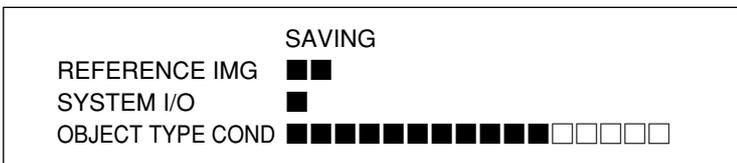
All the data entered on the condition setting menus, such as the measurement conditions and evaluation conditions, are saved in the IV-S30 flash memory.

■ Operating procedure

1. On the [MAIN OPS MENU], move the cursor to "SAVE" using the left and right keys, and press the SET key.
⇨ The following message will be displayed on the upper part of the screen.

DATA SAVE? (Do you want to save the data?) (YES=[SET]/NO=[ESC])

2. Press the SET key.
⇨ The IV-S30 will start saving the data and the progress will be displayed on the bottom of the screen.

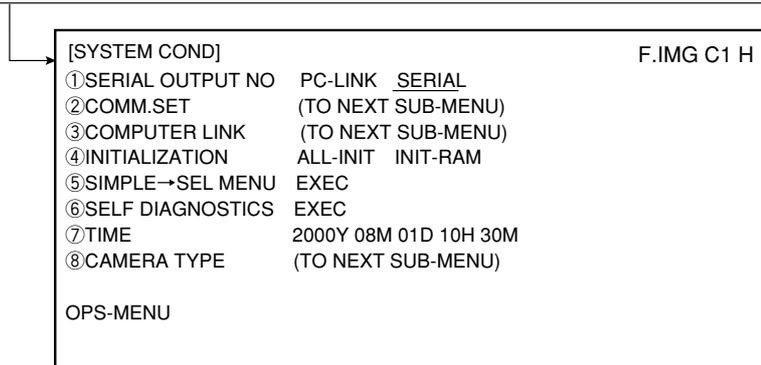


When the data has been saved in the IV-S30 flash memory, the display will change from "SAVING" to "COMPLETE SAVE."

7-12 Specify the system conditions

This section describes how to set the communication conditions and system time.

Move the cursor to the "SYS-CND" item on the menu bar of the MAIN OPS MENU, and press the SET key.



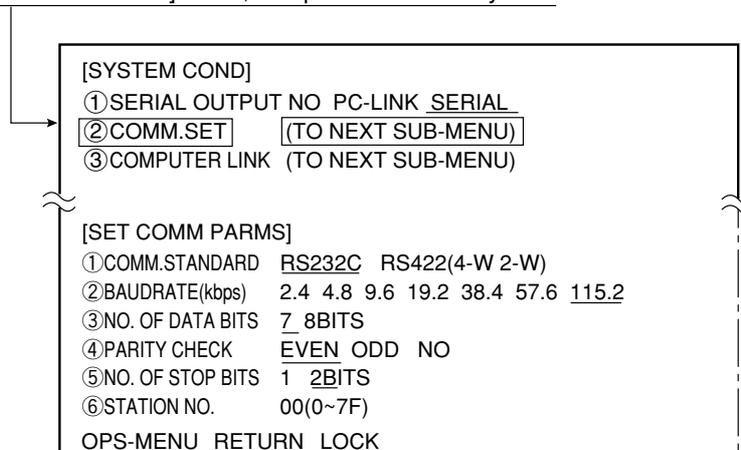
Menu	Setting details	Reference pages
① SERIAL OUTPUT	Use the serial output menu for setting the communication parameters for the computer link or for the general-purpose serial communication port.	7-26
② COMM. SET	When you select this item, the [SET COMM PARMS] menu will be displayed on the lower screen. You can specify the communication conditions.	7-27
③ COMPUTER LINK	When you select this item, the [COMPUTER LINK] menu will be displayed on the lower screen. You can specify the computer link communication conditions.	7-28
④ INITIALIZATION	Initializes the flash memory and the RAM (Initialize all).	7-29
⑤ SIMPLE MENU ⇒ STD	The screen will change to the menu selection screen (select the simplified or standard menus).	6-5
⑥ SELF DIAGNOSTICS	Checks whether or not the IV-S30's hardware is operating normally.	7-30
⑦ TIME	Set the time when IV-S32M/S33M is used.	7-30
⑧ CAMERA TYPE	When the IV-S33M is used, select the camera type that is connected (high-speed, standard, or EIA).	7-31

[1] Communication setting

When you want to use general-purpose serial communication or computer link communication, you must set the communication conditions.

- Specify each item so that it will match the communication parameters of the target machine that you will communicate with.

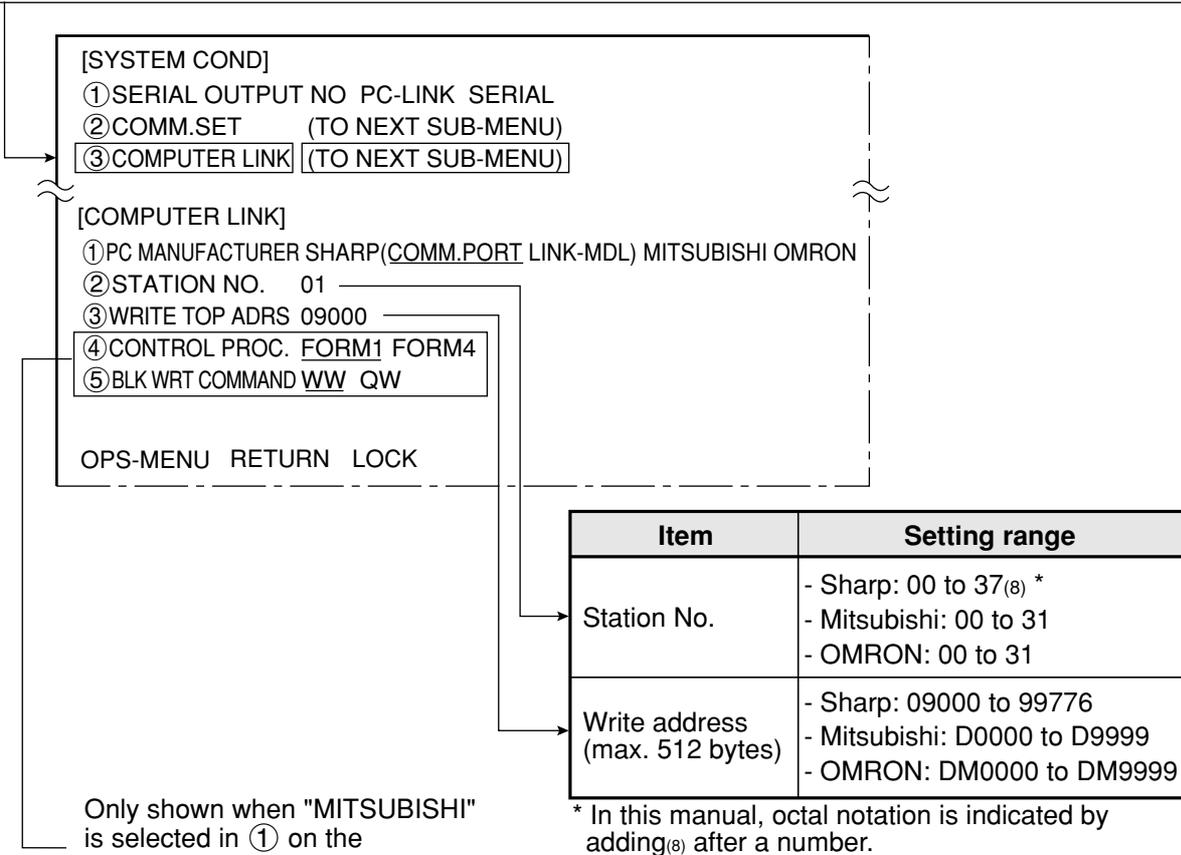
Move the cursor to the "② COMM. SET" item on the [SYSTEM COND] menu, and press the SET key.



- For details about general-purpose serial port communications and computer link communications, see the IV-S30 User's Manual (Function and Operation).

[2] Specify the computer link conditions

When you want to use computer link communications, you must specify the communication conditions. On the [SYSTEM COND] menu, move the cursor to item "③ COMPUTER LINK" and press the SET key.



Only shown when "MITSUBISHI" is selected in ① on the [COMPUTER LINK] menu.

Menu	Setting details				
④ CONTROL PROC.	Select either FORM 1 or 4 for the control procedure. <table border="1"> <tr> <td>FORM 1</td> <td>No line terminator</td> </tr> <tr> <td>FORM 4</td> <td>With line terminators: CR + LF</td> </tr> </table> <p>- In version 2.01, only FORM 1 was available.</p>	FORM 1	No line terminator	FORM 4	With line terminators: CR + LF
FORM 1	No line terminator				
FORM 4	With line terminators: CR + LF				
⑤ BLK WRT COMMAND	Select either WW or QW for the block write command. <table border="1"> <tr> <td>WW</td> <td>Data writing address range: D0000 to D1023</td> </tr> <tr> <td>QW</td> <td>Data writing address range: D000000 to D008191</td> </tr> </table> <p>- In version 2.01, only WW was available.</p>	WW	Data writing address range: D0000 to D1023	QW	Data writing address range: D000000 to D008191
WW	Data writing address range: D0000 to D1023				
QW	Data writing address range: D000000 to D008191				

- If "SHARP" or "OMRON" is selected, items ④ and ⑤ will not be displayed.

- For details about computer link communications, see the IV-S30 User's Manual (Function and Operation).

[4] Self-diagnosis

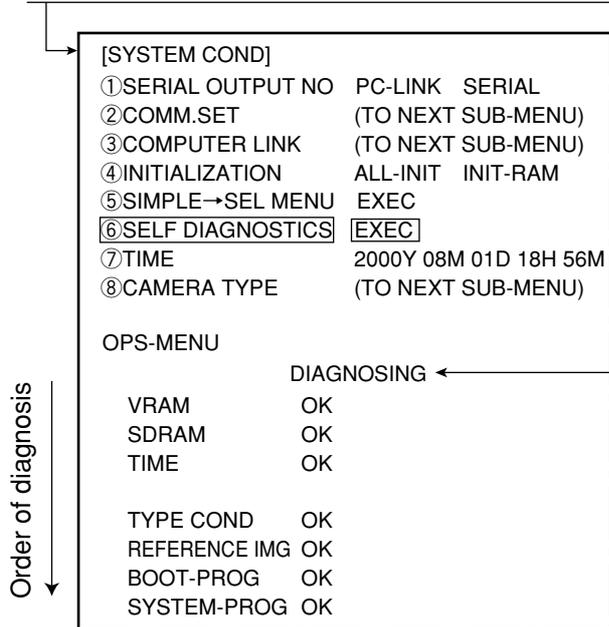
The IV-S31M/S32M/S33M controller can check all of its own hardware, to ensure that it is operating normally.

(1) Diagnostic items and methods

Item	Object	Check method	Error display
VRAM	VRAM (memory)	Read after write	NG
SDRAM	SDRAM (memory)	Read after write	NG
Timer			NG
Object type conditions	Flash memory	Checksum	NG + error object No.
Reference image	Flash memory	Checksum	NG
Boot program	Flash memory	Checksum	NG
System program	Flash memory	Checksum	NG

(2) Operating procedure

On the MAIN OPS MENU, move the cursor to the "SYS-CND" item, and press the SET key.



1. Move the cursor to item "⑥ SELF DIAGNOSTICS" with the up and down keys, and press the SET key.
 ⇨ The [SELF DIAGNOSTICS] menu will be displayed, and each item will be checked. If the result of each diagnosis is normal, OK will be displayed. If the result is abnormal, NG will be displayed.

After the diagnosis is complete, the message will change to "COMPLETE DIAGNOSIS."

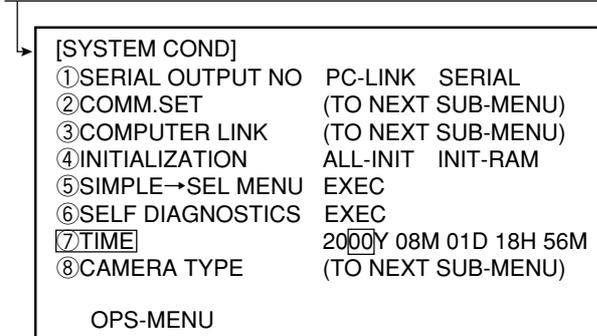
If any abnormality occurs, consult our service center.

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[5] Setting the system time (IV-S32M/S33M)

Set the time displayed on the monitor for the IV-S32M/S33M.

On the MAIN OPS MENU, move the cursor to the "SYS-CND" item, and press the SET key.



1. Move the cursor to the "⑦ TIME" item using the up and down keys, and press the SET key.
2. Move the cursor to "SEC.," "MIN.," "D," "M," and "Y" using the left and right keys, and enter the correct value at each location using the up and down keys.
 Y = 1999 to 2098
 M = 01 to 12
 D = 01 to 31
 H = 00 to 23
 MIN. = 00 to 59
3. Press the SET key. The time will be set and the system will start using the new time.

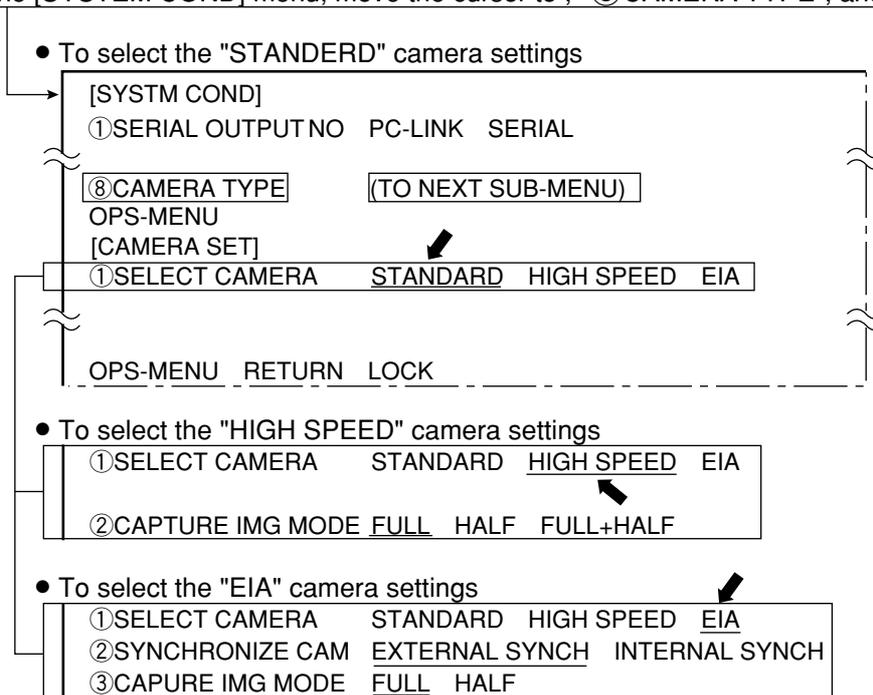
[6] Camera setting (IV-S33M)

Select the camera type (standard, high-speed, or EIA) that is connected to the controller.

Camera selection	Details
Standard	Select when SHARP's standard camera (IV-S30C1/S30C2) is connected to the IV-S33M.
High-speed	Select when SHARP's high-speed camera (IV-S30C3/S30C4) is connected to the IV-S33M.
EIA	Select when a commercially available EIA camera (Sony XC-75 or similar) is connected to the IV-S33M. In this case, you also have to set the camera synchronization mode (External or Internal).

On the MAIN OPS MENU screen, move the cursor to the "SYS-CND" item and press the SET key.

⇒ On the [SYSTEM COND] menu, move the cursor to , "⑧CAMERA TYPE", and press the SET key.



- When "HIGH SPEED" or "EIA" is selected, choose the image capture mode.

Image capture mode	Details
Full	Scan all the lines in the image
Half	Scan only the odd lines in the image
Full + half *	In the partial image mode, the measurement target lines are scanned in full mode and the others are scanned in half mode

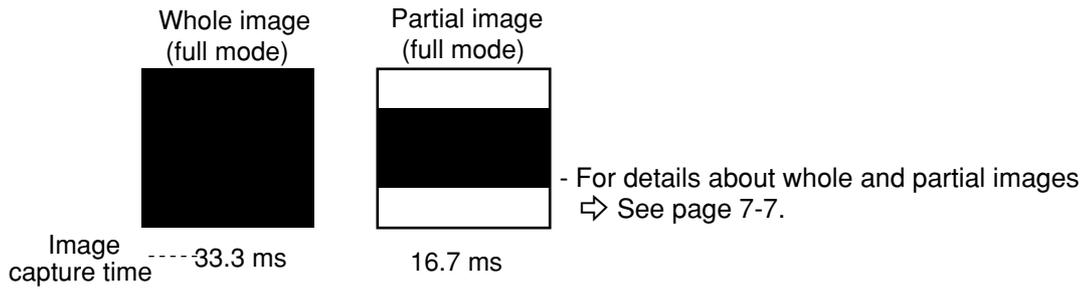
* The "Full + half" mode can only be selected when the camera type is set to "HIGH SPEED"

For more image capture time and processing details, see the next page.

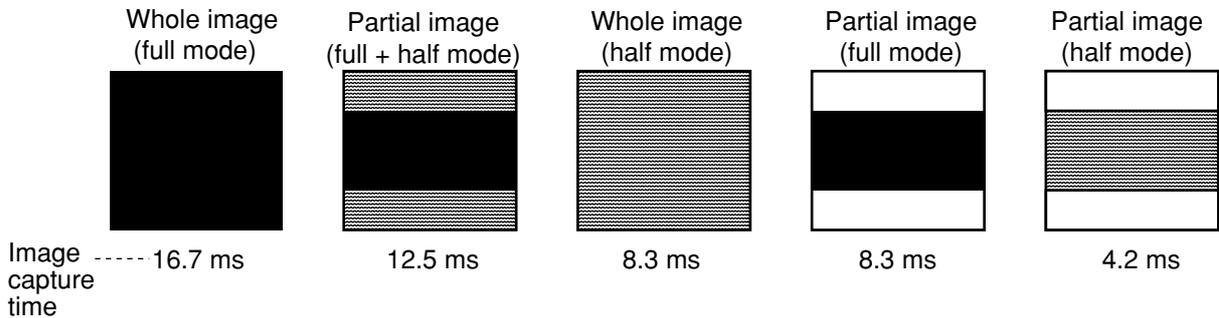
- When "EIA" is selected, you must select a camera synchronization mode (External or Internal).
For details about camera synchronization, see page 6-8.

■ Comparative examples of image capture times

① When a standard camera is used and the partial image size is 50 % (240 lines of the 480 lines).



② When a high-speed camera is used and the partial image size is 50% (240 lines of the 480 lines).



■ Processing details of the image capture mode

Image capture mode	Full	Full + half	Half
Image capture	- Transfer the specified lines	- Transfer only the full mode area	- Correct the specified area and transfer - The even line image will be supplemented by the odd line image.
Process for setting up the screen	- Put all of the captured line area in the full mode	- Put all of the captured line area in the full mode	- Put all of the captured line area in the half mode.
Process from run to setting up the screen	---	- Delete the half mode area	---

7

Chapter 8: Specifications

8-1 Controller (IV-S31M/S32M/S33M)

Item	Specifications		
	IV-S31M	IV-S32M	IV-S33M
Image sampling system	256 level gray scale, binary conversion, edge detection		
Image memory	One screen for displaying captured images. One monochrome screen for displaying camera information and messages		
No. of assignable object type	16 object types	32 object types	64 object types
Maximum number of reference images stored / number of whole screens stored	300 / 3 screens	600 / 8 screens	
Image scan time	Standard camera (IV-S30C1/C2)	33.3 ms *2	
	High-speed camera (IV-S30C3/C4)	---	16.7 ms [full mode] 8.3 ms [half mode] *2
	Commercially available EIA camera	---	33.3 ms [full mode] 16.7 ms [half mode]
Gray search time *1	18 ms	12 ms	9 ms
Gray search, edge detection precision	Pixel, sub-pixel		
Image pre-processing	Shading correction	Dividing, subtracting, and filtering	
	Comparative calculation between images	Subtracting, absolute value of difference (between camera 1 and reference image, between camera 2 and reference image, between camera 1 and camera 2)	
	Gray level changes	Magnification by "n" processing, γ (+/-) correction, histogram widening, mid-range emphasis	
	Space filter	Smoothing (center/average), edge emphasis, edge extraction, horizontal edge, vertical edge	
Binary threshold value	Fixed and threshold value corrections (variation difference/variation rate)		
Binary noise elimination	Expansion \Rightarrow contraction, contraction \Rightarrow expansion, area filter		
Binary image mask	Specified window(rectangle, circle, oval), any binary image mask		
Positional correction method	X/Y correction, rotation correction		
Measurement program (standard menu)	Positional deviation measurement	XY coordinate, deviation amount in X and Y axes, degree of match (1-point search, 2-point search, 1-point edge, 2-point edge, 1-point search and 1-point edge) Angle: ± 15 , ± 30 , ± 45 , 360 (1-point search, 1-point search + 1-point edge) [Maximum 8 windows x 2 models]	
	Degree of match inspection	Degree of match, XY coordinate, density (1-point search, 2-point search) [Maximum 16 windows x 2 models]	
	Area measurement by binary conversion	Area [Maximum 16 windows]	
	Object counting by binary conversion	Quantity (maximum 3,000 items per window), total area [Maximum 4 windows]	
	Object identification by binary conversion	Quantity (maximum 128 per window), total area, area of each object identified, gravity center, main axis angle, fillet diameter, peripheral length, center point [Maximum 4 windows]	
	Point measurement	Number in binary image (maximum 256 points), average density (Maximum 128 points)	
	Lead inspection	Number of leads, distance between leads (max., min.), lead width (max., min.), lead length (max., min.) [Maximum 16 windows]	
	BGA/CSP inspection	Number of labels, total area, area of each label, XY pitch (max., min.) XY fillet diameter (max., min.), [Maximum 4 windows] (IV-S32M/S33M only)	
	Multiple position inspection	Number of objects (max. 128), degree of match, XY coordinate (1-point search, 1-point edge) [Maximum 4 windows]	
	Multiple degree of match inspection	Number of objects (max. 128), degree of match, XY coordinate (1-point search) [Maximum 4 windows]	

*1. The gray search time is true when the search area is 256 x 256 pixels, the model size is 64 x 64 pixels, and the contraction function is set to 3.

*2. Variable, with partial-image capturing.

Specifications

Item		Specifications		
		IV-S31M	IV-S32M	IV-S33M
Number of measurement programs		Maximum 6 per object type (measurement 0 - camera 1, measurement 0 - camera 2, measurements 1 to 4) Note: Measurement 0 is only used for positional deviation measurement.		
Simplified menu	Positioning	XY coordinate, degree of match (1-point search, 2-point search) [1 window]		
	Existence inspection	Area [Maximum 8 windows]		
Window shape		Rectangle, circle, oval (when using area measurement by binary conversion, object counting by binary conversion, object identification by binary measurement)		
Distance and angle measurement		Measure distance (between two points, X coordinate, Y coordinate), measure angle (3 points, 2 points against horizontal line, 2 points against vertical line), auxiliary point (center, circle center, gravity center, line over 2 points, crossing point of two straight lines)		
Arithmetic operation		Four basic operations (+, -, X, /), root, absolute value, TAN, ATAN, maximum, minimum, average, total.		
NG image memory function		---	Maximum 128 images (8 whole screens)	
Calendar timer		---	Year, month, day, hour, minute	
Other functions		Display measuring time, light level monitor function, crosshair cursor display, change display language between Japanese and English, Run screen lock function, setting menu display "yes/no", change image display (through/freeze), change image brightness (bright/dark)		
Micro PC section	Input relays	Parallel input: 8 points (X0 to X7)		
	Output relays	Parallel output: 8 points (Y0 to Y7)		
	Auxiliary relays	General-purpose serial interface, computer link: 16 points (Y0 to Y15)		
	Timers	128 points (C0 to C127), special area 18 points (C110 to C127)		
	Counters	8 points (TM0 to TM7), timer setting range: 0.01 to 9.99 seconds (countdown timer)		
External interface	Parallel interface	Input: 8 points, 12/24 VDC, approx. 7 mA (24VDC) Output: 9 points, 12/24 VDC, max. 100 mA, FET output		
	General-purpose serial interface	RS232C/RS422 (2.4 to 115.2 kbps)		
	Computer link	Built-in compatibility with certain SHARP, OMON, and Mitsubishi models		
	USB	USB device node, 12 Mbps		
Image output		1 channel, EIA 525 lines, 2:1 interlace		
Number of cameras		Maximum of 2		
Make settings		Using the IV-S30RK1 remote keypad and/or the IV-S30SP parameter setting support software		
Measurement start input	Internal trigger	CCD trigger (using the CCD camera)		
	External trigger	Trigger input (parallel I/F), general-purpose serial I/F, keypad trigger (for manual measuring)		
Terminal block	Interrupt processing input	1 point: External trigger (X0)		
	Inputs	7 points: Object type change (X1 to X4), external input (X5 to X7)	7 points: Object type change (X1 to X5), external input (X6 and X7)	7 points: Object type change (X1 to X6), external input (X7)
	Common for input	1 point: + or - common		
	Output	9 points: 1 READY, 8 user settable logical outputs (Y0 to Y7)		
	Common for output	1 point: + or - common		
Power supply		2 points: +24 VDC, 0 V		
Power supply voltage / power consumption		24 VDC (±10%), 7 W		24 VDC (±10%), 8 W

Item	Specifications		
	IV-S31M	IV-S32M	IV-S33M
Storage ambient temperature	-20 to 70°C		
Operation ambient temperature	0 to 45°C		
Operation ambient humidity	35 to 85% RH (non-condensing)		
Operation atmosphere	No corrosive gases or dust		
Vibration resistance	JIS C 0911 or equivalent - Amplitude 0.15 mm (10 to 57 Hz), 9.8 m/s ² (57 to 150 Hz) Number of sweeps: 10 (1 octave/min.), 3 directions (X, Y, Z)		
Shock resistance	JIS C 0912 or equivalent : 147 m/s ² (three times each in X, Y, and Z directions)		
Noise immunity	1000 Vp-p 1μs width impulse (by noise simulator) when applied to the primary side (100 VAC) of an external DC power supply		
Outside dimensions	130 (W) × 100 (D) × 42 (H) mm (except protruding portions)		
Weight	510 g		
Accessories	<ul style="list-style-type: none"> - 2 main housing angle bracket - 1 monitor cable - 1 conversion connector - 1 D-sub connector (9-pin, D-sub, male, M2.6 lock screw: for communication connector of the controller) - 4 securing screws (M3 x 6: for fixing the angle bracket) - 1 instruction manual 		

8-2 Camera specifications

[1] Camera (IV-S30C1/C2/C3/C4)

Item		Specifications			
		Standard, IV-S30C1	Micro, IV-S30C2	Hight speed, IV-S30C3	Micro and hight speed, IV-S30C4
Optical system	Lens mount method	C mount	custom $\phi 17$ mm mount	C mount	custom $\phi 17$ mm mount
Picture taking element	Method	Interline transmission method, monochrome CCD			
	Reading system	Full pixel type, partial image scanning is available			
	Reading	33.3 ms *		16.7 ms [full mode], 8.3m [half mode]*	
	Size	1/3 inch			
	No. of effective pixels	512 (horizontal) \times 480 (vertical)			
	Pixel shape	Square			
Shutter	Shutter speed (s)	Settable between 1/30 and 1/10,000 for each object type			
	Method	Random shutter			
Conncter		Round, 12-pin male connector			
Connection to controller		- Using custom camera cables (IV-S30KC3: 3 m, IV-S30KC5: 5 m, IV-S30KC7: 7 m)		- Using custom camera cables (IV-S30KC3: 3 m, IV-S30KC5: 5 m)	
Operation ambient temperature		0 to 45°C			
Operation ambient humidity		35 to 85% RH (non-condensing)			
Operation atmosphere		No corrosive gases or dust			
Outside dimensions (mm)	Camera body	30 (W) \times 32 (H) \times 40 (D)	30 (W) \times 32 (H) \times 50 (D)	30 (W) \times 32 (H) \times 40 (D)	30 (W) \times 32 (H) \times 44.7 (D)
	Head	---	$\phi 17 \times 35.6$ mm	---	$\phi 17 \times 35.6$ mm
	Head cable	---	1m	---	1m
Weight		50 g (not including the lens)	125 g(The head weighs approximately 12 g)	50 g (not including the lens)	140 g(The head weighs approximately 13 g)
Accessories		- 1 camera angle bracket - 2 securing screws	- 1 camera angle bracket - 1 camera head bracket - 3 securing screws - 1 Instruction Manual	- 1 camera angle bracket - 2 securing screws - 1 Instruction Manual	- 1 camera angle bracket - 1 camera head bracket - 3 securing screws - 1 Instruction Manual

* Variable with partial-image capturing

[2] Camera converter (IV-S30EA1)

Item		Function
Camera to be connected	TV system	EIA equivalent camera
	Image input	1 Vp-p (75 ohm load)
	Number of scan lines	525
	Scanning method	2:1 interlace
	Synchronization system	Internal/external Note: External synchronization may not be available with some EIA cameras (The converter is compatible with Sony's S-DNPISHA and the special shutter made by Tokyo Electronic Industries)
	Scanning frequency	Horizontal: 15. 734 KHz, Vertical: 59.94 Hz
	Pulse width	HD: 6.4 ±0.3 μs, VD: 150 to 800 μs
	Power supply	12V ± 10%(300mA / one set or less)
Number of cameras that can be connected	2	
Camera connectors	Round, 12-pin female connectors	
Main housing connector	D-sub, 25-pin female connectors	
Power supply voltage	24 V, 0.5 A (12 W)	
Ambient operating temperature	0 to 45° C	
Operating humidity	35 to 85% RH (non condensing)	
Outside dimensions	70 (W) x 100 (H) x 25 (D) mm	
Connection to the controller	Using the supplied main housing cable (250 mm)	
Weight	Camera converter: approximately 255 g, main interface cable: approximately 150 g	
Accessories	1 main interface cable [Cable length: 250 mm, Connector: D-sub 25 pin male,] Hirose round, 12-pin male 2 main housing mounting brackets 4 securing screws 1 instruction manual	

Specifications

[3] Camera lens (IV-S20L16)

Item	Specifications
Focal distance	16 mm
Maximum f-stop	1.6
Aperture range	1.6 to 16, Close
Focal range	50 mm to ∞
Filter installation dia.	M 25.5, P = 0.75, U1
Mount system	C mount
Compatible cameras	IV-S30C1/C3, IV-S20C1 (camera for the IV-S20)

[4] Camera cable: IV-S30KC3/S30KC5/S30KC7

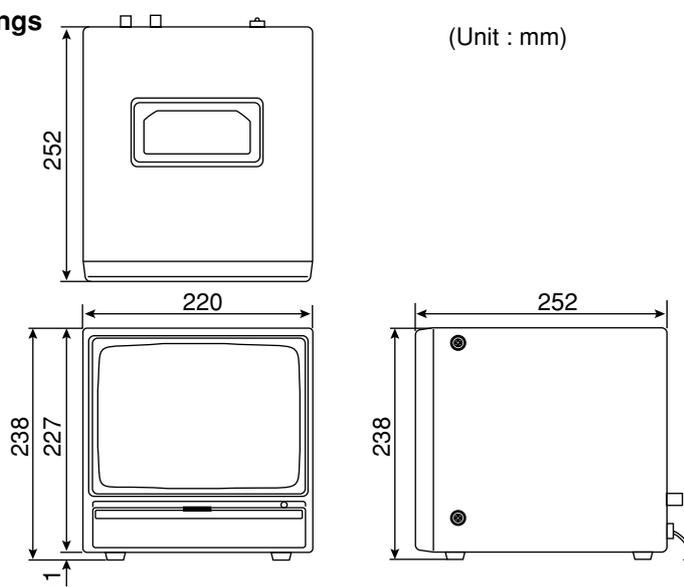
Item	Specifications
Overall length	3m (IV-S30KC3), 5m (IV-S30KC5), 7m (IV-S30KC7)
Cable sheath	Polyvinyl chloride
Video connectors	Main housing: Round, 12-pin male connector
	Camera: Round, 12-pin male connector
Minimum bending radius	75 mm

8-3 Support tools

[1] Monochrome monitor IV-09MT

Item		Specifications
Power input voltage		90 to 110VAC, 50/60Hz
Input capacity		25 VA
Signal voltage		1.0Vp-p/75 ohms
Screen display resolution		900 scanning lines (center), 600 scanning lines (edges)
Scan method		EIA 525 lines (2:1 interlaced)
Scan frequency		Horizontal : 15.75 kHz, vertical : 48 to 62 Hz
Image size		8% under scan
Linearity		Horizontal : 10% or less, vertical : max. 10%
Image input connector		BNC
Image input impedance		75 ohms/ High-Z
Video output connector		BNC
Adjustments	Front	Brightness, contrast, vertical position, horizontal position
	Back	Focus, vertical width, horizontal linearity, sub-brightness (only used by our service staff)
Storage ambient temperature		-20 to 60°C
Operation ambient temperature		0 to 45°C
Operation ambient humidity		35 to 85 %RH (non-considering)
Atmosphere		No corrosive gases
Vibration resistance		JIS C 0911 or equivalent - Amplitude 0.15mm, (10 to 57Hz), 9.8m/s ² (57 to 150Hz), No. of sweeps : 10 (1 octave/min.) 3 directions (X, Y, Z)
Shock resistance		JIS C 0912 or equivalent, 147m/s ² (3 times each in X,Y, and Z directions)
Weight		Approx. 6 kg
Dimensions (mm)		220 (W) × 238 (H) × 257 (D) (not including protrusion)
Dielectric resistance		1000 VAC, 1 minute (between AC plug and shassis)
Insulation resistance		DC 500VDC, 10M ohms or more (between AC plug and chassis)
Accessories		One instruction manual

■ External dimension drawings

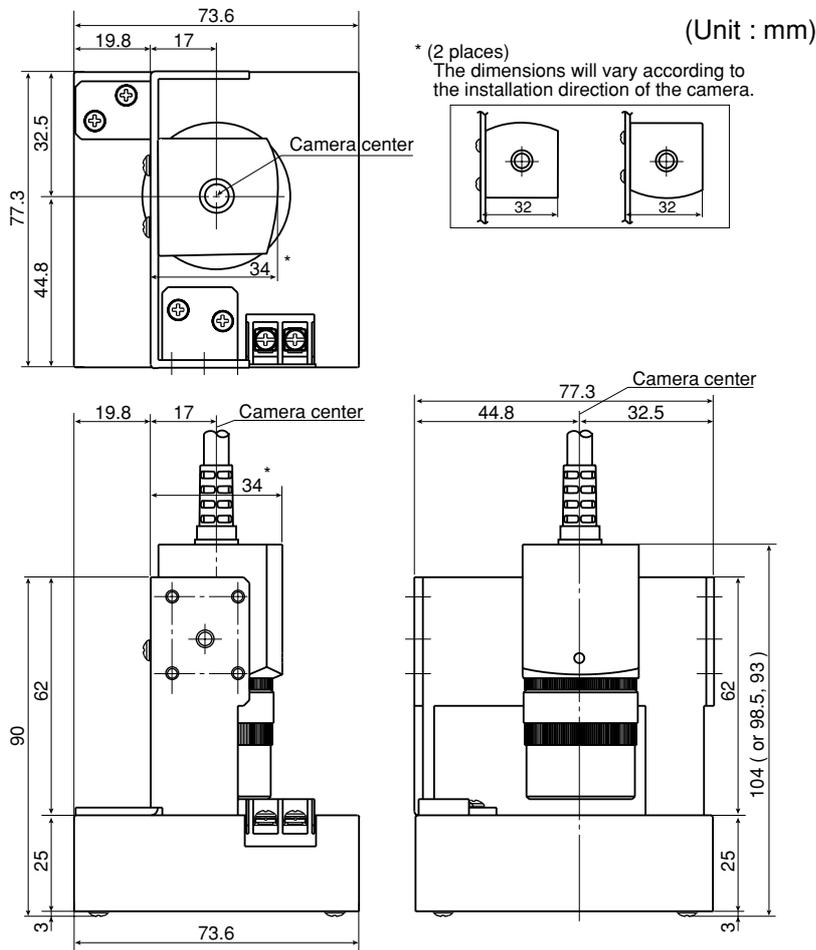


[2] LED lighting equipment IV-60LD specifications

Item	Specifications
LEDs used	36 pcs of 5mm diameter - High brightness LEDs
Standard lighting range	Approx. 50mm × 50mm (workpiece distance at 150mm)
Input voltage	24 VDC ±10% , 2P terminal
Current consumption	Approx. 2W
Lighting level adjustment	Semi-fixed volume
Operation ambient temperature	0 to 45°C
Storage ambient temperature	-10 to 60°C
Operation ambient humidity	35 to 90%RH (non-condensing)
Operation atmosphere	No corrosive gases or dust
Vibration resistance	JIS C 0911 or equivalent - Amplitude 2mm (10 to 61 Hz), 147m/s ² (61 to 150Hz), No. of sweeps : 10 (1 octave/min.), 3 directions (X,Y,Z)
Shock resistance	JIS C 0912 or equivalent, 147m/s ² (each 3 times in X, Y, and Z directions)
Outside dimensions (mm)	76.9 × 73.6 × 25.0 (except camera angle bracket)
Weight	Approx. 230g (IV-60LD body : Approx. 140g + Camera angle bracket : Approx. 90g)
Accessories	One camera angle bracket, 6 installation screws (M3 × 6mm), one instruction manual

External dimension drawings

Shown below are an IV-S30C1 camera with an IV-S20L16 camera lens installed.



Chapter 9: Operation Examples

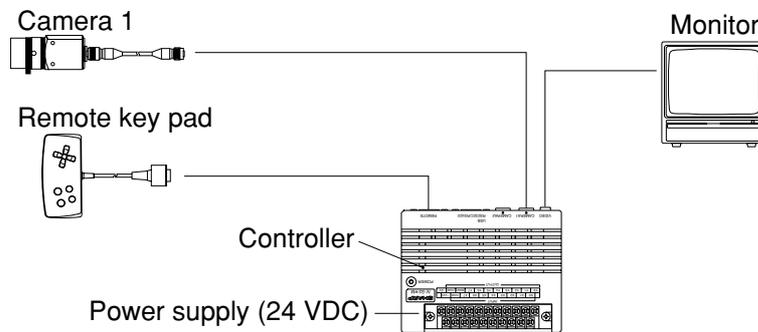
This chapter explains how to operate each measurement program. Be sure you understand the general operation procedures described in this chapter.

		Item	Page
9-1 Simplified menu	[1]	Positioning measurement	9-2 to 9-5
	[2]	Existence inspection	9-6 to 9-9
9-2 Standard menu	[1]	Area measurement by binary conversion	9-10 to 9-14
	[2]	Positional deviation measurement	9-15 to 9-21

■ Preparation for operation

Before turning ON the power, connect the IV-S30 controller, the camera, monitor, remote key pad and power supply (24 VDC). Connect the camera to the camera 1 connector (CAMERA 1) on the IV-S30 controller.

See Chapter 5 "Installation Conditions and Method" for connecting procedures.



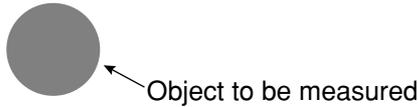
Notes

- Sections 9-1 and 9-2 give the instructions for making each measurement, starting from the initial conditions of the machine. To follow the instructions, first initialize all the machine's conditions and then start the procedures. For details about performing a complete initialization, see the respective pages, described below.
- Simplified menus ⇨ Page 7-29
- Standard menus ⇨ "Total initialization" in the IV-S30 user's manual (Function and Operation)

9-1 Simplified menu

[1] Positioning measurement

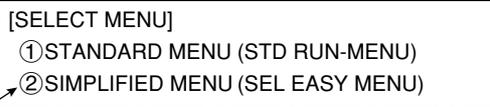
The following sections cover an example of how to measure the positioning of the object shown below.



(1) Power ON

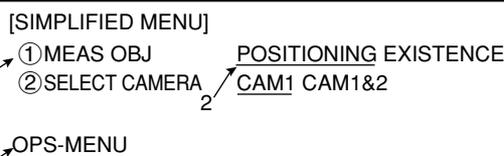
- When power is first turned ON after the machine is delivered, the [SELECT MENU] screen will appear.
- When the MAIN OPS MENU used by the simplified menus (positioning) is displayed, the operations covered in steps (2) and (3) are not needed.
 - If the MAIN OPS MENU used by the standard menus is displayed, please change to the simplified menu screen. ⇨ See page 6-5.

(2) Select menu



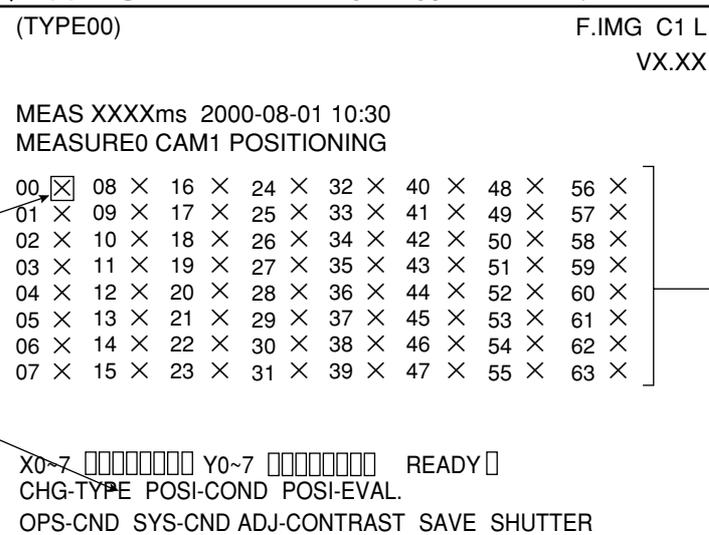
1. Move the cursor to the "②SIMPLIFIED MENU" item with the up and down keys, and press the SET key.
⇨ The [SIMPLIFIED MENU] menu screen will appear.

(3) Placing the object to be measured (positioning)



1. Move the cursor to the "①MEAS OBJ" item using the up and down keys, and press the SET key.
2. Move the cursor to "POSITIONING" using the left and right keys, and press the SET key.
3. Move the cursor to the "OPS-MENU" item using the up and down keys, and press the SET key.
⇨ The MAIN OPS MENU for setting up positioning measurements will be displayed.

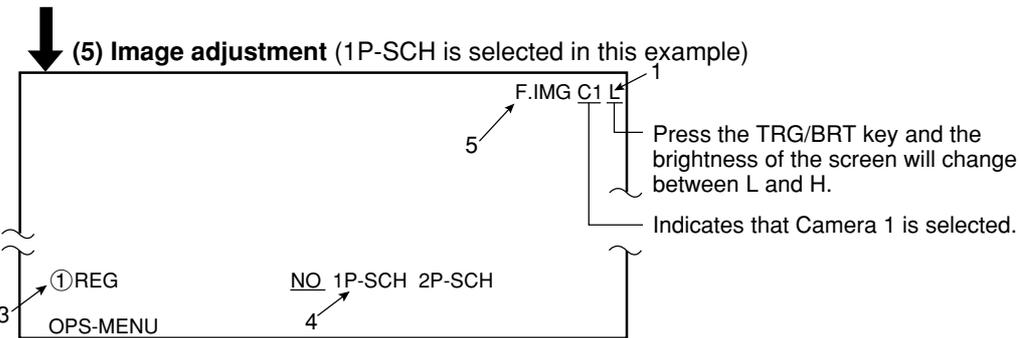
(4) Registration of an object type number (IV-S33M is registered in 00 in this example)



When the IV-S33M is used
 [When the IV-S31M is used 00 to 15]
 [When the IV-S32M is used 00 to 31]

1. Move the cursor to the X next to object type number 00 using the up and down keys. Then press the SET key.
⇨ The X will change to a circle meaning that object type 00 has been registered.
2. Move the cursor to the "POSI-COND" item using the left and right keys, and press the SET key.
⇨ The measurement condition setting screen will be displayed.

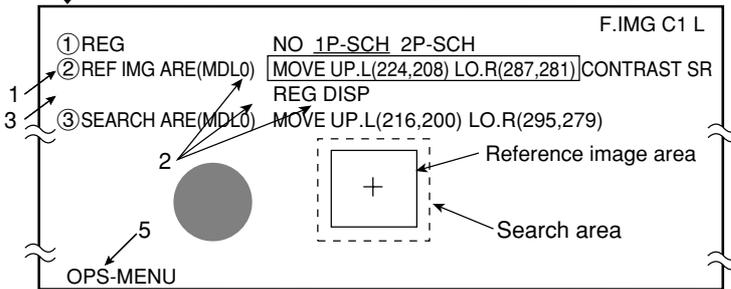
Continued from the previous page



(5) Image adjustment (1P-SCH is selected in this example)

1. Press the SEL key.
 - ⇒ The image taken by camera 1 will be displayed.
 - When the image is so bright that the menu display is difficult to see, press the TRG/BRT key to reduce the brightness of the image. The indicator in the upper right corner of the screen will change from "H" to "L."
2. To display the image of the object measured clearly, adjust the focus and iris opening of the camera lens (page 4-1).
3. Move the cursor to the "①REG" line, and press the SET key.
4. Move the cursor to the "1P-SCH" item with the left and right keys, and press the SET key.
 - ⇒ The reference image area and search area will be displayed in the center of the screen.
5. Press the SEL key to change the screen to the freeze mode.
 - ⇒ The indicator in the upper right corner of the screen will change from T to F.
 - To register reference images, you must make sure to display the freeze screen.
6. Press the ESC key to display all of the measurement condition items.

(6) Setting the measurement conditions

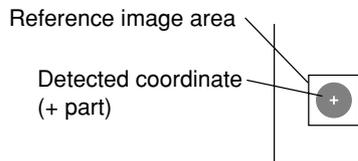


- If the menu overlaps the object to be measured, so that further image condition setting is difficult, press the ESC key. Only item ① will be displayed at a time.

1. Move the cursor to the "②REF. IMG ARE (MDL 0)" item with the up and down keys, and press the SET key.
2. Surround the object to be measured with the reference image area (solid line).
 - Move the cursor to the "MOVE," "UP.L," or "LO. R," label and press the SET key.

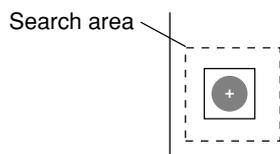
MOVE	The whole rectangle is moved using the up, down, left or right keys (one pixel at a time).
UP.L	The upper left corner is moved using the up, down, left or right keys (one pixel at a time).
LO.R	The lower right corner is moved using the up, down, left or right keys (one pixel at a time).

After the position has been finalized, press the SET key.



- After the reference image area position has been set, move the cursor to the "REG." item using the left and right keys, and press the SET key.
- ⇒ The stored image will be displayed in the lower right corner of the screen. After storing the image, press the ESC key.

3. Press the ESC key and move the cursor to the "③ SEARCH ARE (MDL 0)" item. Then, press the SET key.
4. Create a search area (dotted line).
 - The search area described above is the range for detecting the image registered in step 2, using the gray scale search function (see the Glossary).
 - The procedure for creating the search area is the same as described for the reference image area in step 2.



- After specifying the search area position, press the ESC key.

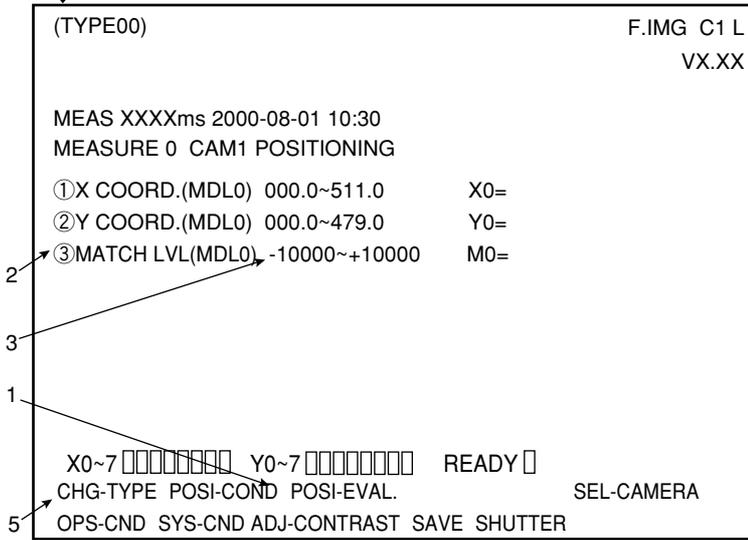
5. Move the cursor to the "OPS-MENU" item using the up and down keys, and press the SET key.
 - ⇒ The screen will return to the MAIN OPS MENU.

To the next page

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(7) Setting the position evaluation conditions

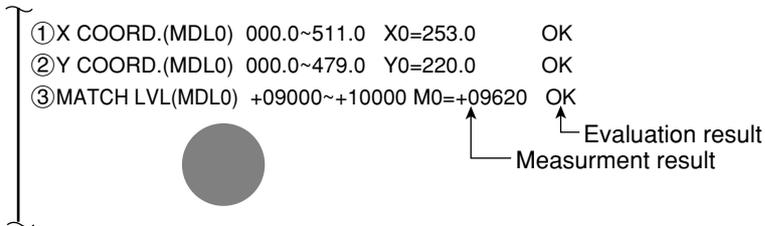
1. Move the cursor to the "POSI-EVAL." item on the MAIN OPS MENU using the left and right keys, and press the SET key.
⇒ The items ① to ③ will be displayed.



2. Move the cursor to "③ MATCH LVL (MDL0)" with the up and down keys, and press the SET key.
3. Move the cursor to the minimum value position with the left and right keys, and press the SET key.
- Select the digit to change with the left and right keys, and then set the value to +09000 with the up and down keys.
(Criteria for a successful match: 90.00% to 100.00%)



- After defining the minimum value, press the SET key, and then the ESC key.
4. Press the TRG/BRT key.
⇒ The measurement (evaluation) results for items ① to ③ and the image will be displayed.



5. Press "ESC," and move the cursor to the "CHG-TYPE" item using the left and right keys, to confirm that "Object type number 00" has been selected.
6. Move the cursor away from the "CHG-TYPE" item using the left and right keys.

To the next page

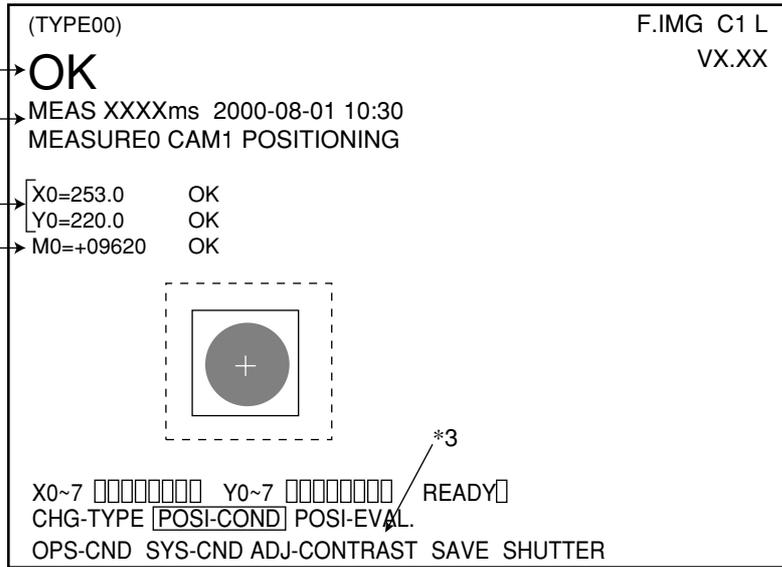
Continued from the previous page

Press the TRG/BRT key, and the result of measuring (evaluating) and image (search) area will be displayed.

[Display of the measured result]

Final evaluation result (*1)
 Measuring time
 Detection coordinates of the reference image
 Degree of match of the reference image (*2)

(8) Measuring the position



*1 The final evaluation result will be displayed as "OK" in the upper left corner of the screen when all of the items have been evaluated acceptable. If there is a single unacceptable item, "NG" will be displayed.

*2 "M0 +09620" means that the degree of match (percentage of pixels that match) between pixels in the stored image and the measured image is 96.20%.

[The acceptance and rejection criteria based on the degree of match]

In order to evaluate acceptability based on the degree of match, first an image of a good specimen is stored for reference. Then, an image of defective specimen is compared for degree of match. Finally an image of another good specimen is compared. These comparisons establish the degree of match to be used for setting the limits used for working comparisons.

For example, the degree of match for a non-defective object is 90% or more and that for a defective object is 70% or less, then the threshold value for degree of match can be set to approx. 85%. This allows the evaluation acceptability to be made.

*3 Although the specified data is temporarily stored in RAM memory, it is not stored in the flash memory. So, you must save the data manually using the save operation. If you do not save the data in the flash memory, it will be deleted when the IV-S30 controller is turned OFF. ⇨ See page 7-26.

[2] Existence inspection

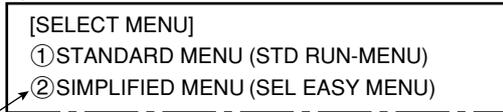
The following sections describe an example of the existence inspection, using the object shown below as the target.



(1) Power ON

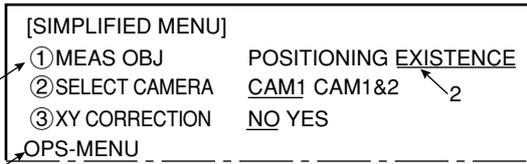
When power is first turned ON after the machine is delivered, the [SELECT MENU] screen will appear.
 - When the MAIN OPS MENU used by the simplified menus (existence inspection) is displayed, the operations covered in steps (2) and (3) are not needed.
 - If the MAIN OPS MENU used by the standard menus is displayed, please change to the simplified menus screen. ⇨ See page 6-5.

(2) Select menu



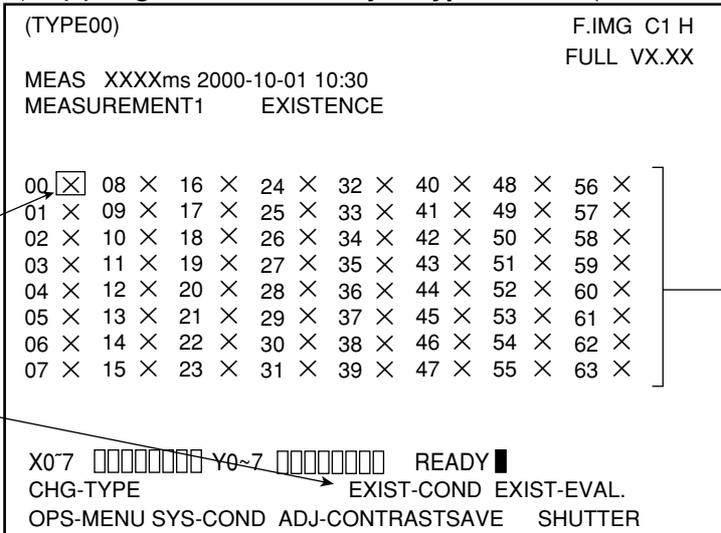
1. Move the cursor to the [② SIMPLIFIED MENU] item with the up and down keys, and press the SET key.
 ⇨ The [SIMPLIFIED MENU] menu screen will appear.

(3) Placing the object to be measured (existence inspection)



1. Move the cursor to the "① MEAS OBJ" item using the up and down keys, and press the SET key.
 2. Move the cursor to "EXISTENCE" using the left and right keys, and press the SET key.
 3. Move the cursor to the "OPS-MENU" item using the up and down keys, and press the SET key.
 ⇨ The MAIN OPS MENU for existence inspection will be displayed.

(4) Registration of an object type number (IV-S33M is registered in 00 in this example)



When the IV-S33M is used
 [When the IV-S31M is used 00 to 15]
 [When the IV-S32M is used 00 to 31]

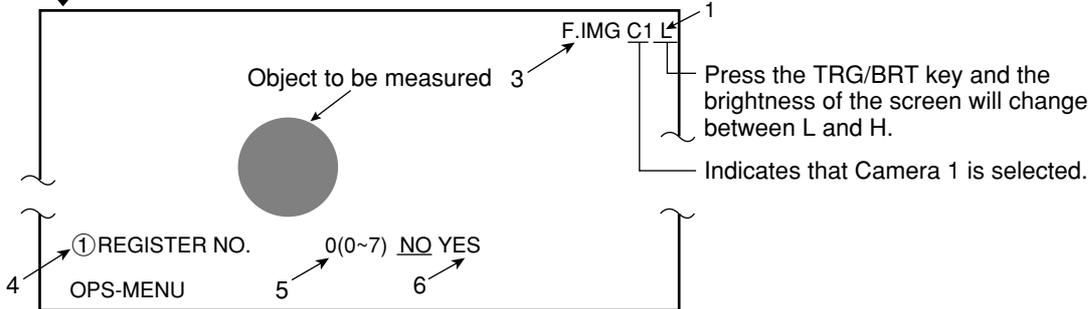
1. Move the cursor to the X on the object type number 00 using the up and down keys. Then press the SET key.
 ⇨ The X will change to a circle meaning that the object type has been registered.
 2. Move the cursor to the "EXIST-COND" item using the left and right keys, and press the SET key.
 ⇨ The measurement condition setting screen will be displayed.

To the next page

Continued from the previous page

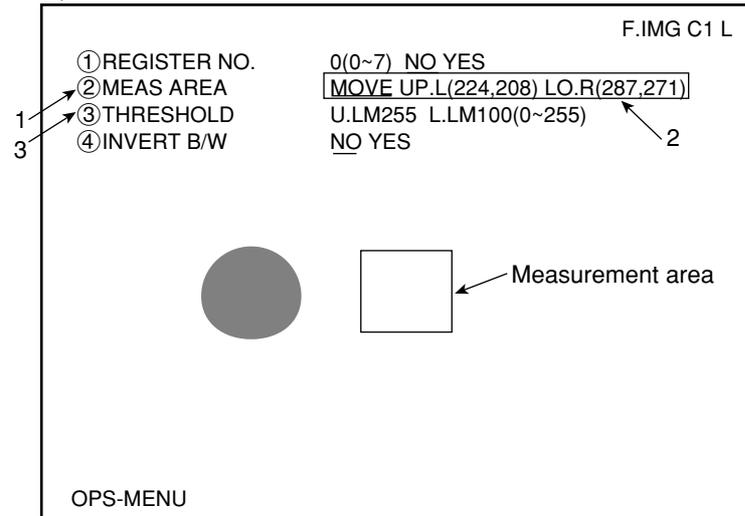
(5) Image adjustment

1. Press the SEL key.
 - ⇒ The image taken by camera 1 will be displayed.
 - When the image is so bright that the menu display is difficult to see, press the TRG/BRT key to reduce the brightness of the image. The indicator in the upper right corner of the screen will change from "H" to "L."



2. To display the image of the object measured clearly, adjust the focus and iris opening of the camera lens (page 4-1).
3. Press the SEL key to change the screen to the freeze mode.
 - ⇒ The indicator in the upper right corner of the screen will change from T.IMG to F.IMG.
 - To set a threshold for a binary area, make sure the IV-S30 is displaying the freeze screen. (For details about the through and freeze modes, see page 7-4.)
4. Move the cursor to the "① REGISTER NO." item using the up and down keys, and press the SET key.
5. Specify "0" for the registration number using the up and down keys.
6. Move the cursor to "YES" using the left and right keys.
 - ⇒ The measurement area will be displayed in the center of the screen.
7. Press the ESC key to display all of the measurement condition items.

(6) Setting the binary area condition (measurement area)

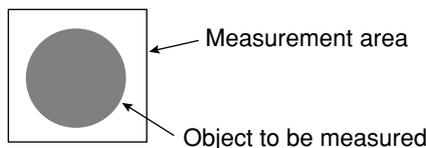


- If the menu overlaps the object to be measured, so that further image condition setting is difficult, press the ESC key. Only item ① will be displayed at a time.

1. Move the cursor to the "② MEAS AREA" item, and press the SET key.
2. Surround the object to be measured with the measurement area (solid line).
 - Move the cursor to the "MOVE," "UP.L," or "LO. R," label and press the SET key.

MOVE	The whole rectangle is moved using the up, down, left or right keys (one pixel at a time).
UP.L	The upper left corner is moved using the up, down, left or right keys (one pixel at a time).
LO.R	The lower right corner is moved using the up, down, left or right keys (one pixel at a time).

After the position has been finalized, press the SET key.



- After specifying the position of each measurement area, press the SET key.

To the next page

Continued from the previous page

Press the TRG/BRT key, and the result of measuring (evaluating) and image (search) area will be displayed.

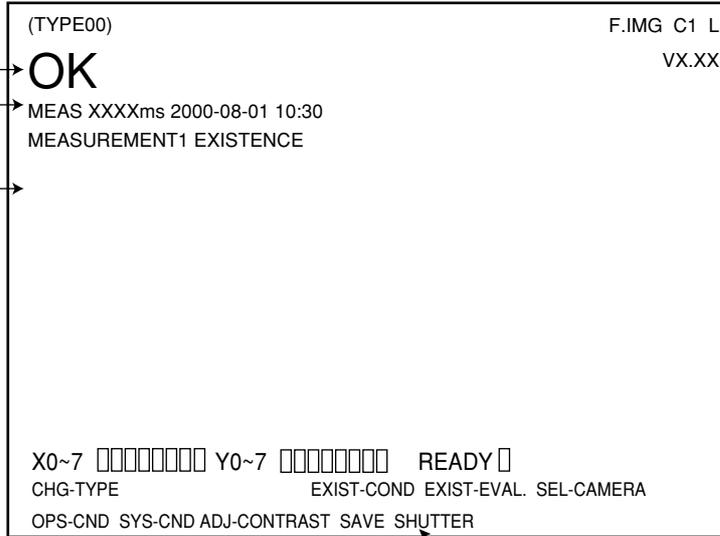
[Display of the measured result]

Final evaluation result (*1)

Measuring time

Area of registration number 00
(number of pixels) and
evaluation result

(9) Existence inspection



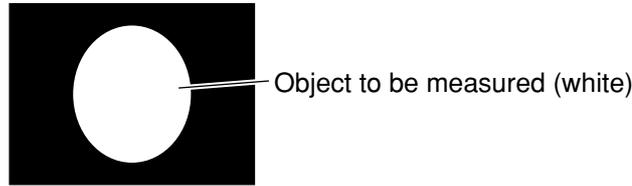
*1 The final evaluation result will be displayed as "OK" in the upper left corner of the screen when all of the items have been evaluated as acceptable. If there is a single unacceptable item, "NG" will be displayed. The only item evaluated in the existence inspection is the area. The result will be OK if it falls within the evaluation conditions that are specified in step (8) (upper and lower limits).

*2 Although the specified data is temporarily stored in RAM memory, it is not stored in the flash memory. So, you must save the data manually using the save operation. If you do not save the data in the flash memory, it will be deleted when the IV-S30 controller is turned OFF. ⇨ See page 7-26.

9-2 Standard menu

[1] Area measurement by binary conversion

The following sections describe the operation for measuring the area of the object shown below. The area is measured by counting the number of pixels after the image has been subjected to binary processing.



(1) Power ON

When power is first turned ON after the machine is delivered, the [SELECT MENU] screen will appear.

- When the MAIN OPS MENU used by the simplified menus (positioning) is displayed, the operations covered in step (2) is not needed.
- If the MAIN OPS MENU used by the standard menu is displayed, please change to the simplified menu screen. ⇨ See page 6-5.

(2) Select menu

[SELECT MENU]
 ① STANDARD MENU (STD RUN-MENU)
 ② SIMPLIFIED MENU (SEL EASY MENU)

1. Move the cursor to the "① STANDARD MENU" item with the up and down keys, and press the SET key.
 ⇨ The standard mode [MAIN OPS MENU] screen will appear.

(3) Operation on the MAIN OPS MENU (all the conditions are initialized)

(TYPE00) T.IMG C1 L
 VX.X
 MEAS 0000ms XXXX-XX-XX XX:XX
 MEASURE 0 CAM1 NO
 X0~7 □□□□□□□□ Y0~7 □□□□□□□□ READY □
 CHG-MEA CHG-REG CHG-RST CHG-C1 CHG-C2 CHG-EVAL CUSTOM-MNU
 OPS-CND MEA-CND SYS-CND CHG-TYPE NG-IMG-DSP NEXT-NG MANL-MEAS

1. Move the cursor to the "MEA-CND" item using the left and right keys, and press the SET key.
 ⇨ The "TYPE MEAS COND" menu will be displayed.

(4) Registration of an object type number (the object is registered in 00 with the IV-S33M)

[TYPE MEAS COND]
 ① OBJECT TYPE NO. 00(0~63) NO YES
 OPS-MENU SAVE LOCK TITLE FINAL-CALC FINAL-OUTPUT I/O SYSTEM
 [OBJECT REG.LIST]

00	01	02	03	04	05	06	07	08	09	10	11	12	13	14	15
X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X
16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	31
X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X
32	33	34	35	36	37	38	39	40	41	42	43	44	45	46	47
X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X
48	49	50	51	52	53	54	55	56	57	58	59	60	61	62	63
X	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X

* Object type number
 IV-S33M: 00 to 63
 IV-S32M: 00 to 31
 IV-S31M: 00 to 15

← Circles will be displayed below object type number that is already registered.

1. Move the cursor to the "① OBJECT TYPE NO." item using the up and down keys, and press the SET key.
2. Move the cursor to "YES" using the left and right keys, and press the SET key.
 ⇨ Items ② to ⑧ will be displayed.

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Continued from the previous page

(5) Setting the measurement number ("MEASUREMENT 1" is selected for the IV-S33M)

```

[TYPE MEAS COND]
① OBJECT TYPE NO. 00(0~63) NO YES
② SELECT CAMRA  CAM1&2 CAM1&NG-IMG
③ IMG PRE-PROCESS (TO NEXT SUB-MENU)
④ MEASURE 0 CAM1 NO (MEAS-COND) NO
⑤ MEASURE 0 CAM2 NO (MEAS-COND) NO
⑥ MEASUREMENT 1 NO (MEAS-COND)
⑦ MEASUREMENT 2 NO (MEAS-COND)
⑧ MEASUREMENT 3 NO (MEAS-COND)
⑨ MEASUREMENT 4 NO (MEAS-COND)

OPS-MENU SAVE LOCK TITLE FINAL-CALC FINAL-OUTPUT I/O SYSTEM
[MEASUREMENT 1]
① MEAS SELECTION NO POSI-DEVIATION CHK-DEG-MATCH
INSPECT-LEAD INSPECT-BGA/CSP
MEAS-BIN-AREA CNT-BIN-OBJ LABEL-BIN-OBJ
POINT-MEAS MULTI-POSI MULTI-MATCHES
② SELECT CAMERA CAM1 CAM2
③ CHNG GRAY LABEL NO YES(00.0TIMES  $\gamma+$   $\gamma-$  CHNG-L INCRS-M)
④ SPACE FILTER NO NUM-OF-TIMES 0(0~5)

OPS-MENU RETURN LOCK
    
```

1. Move the cursor to the "⑤ MEASUREMENT 1" item using the up and down keys, and press the SET key.
2. Move the cursor to "NO" using the left and right keys, and press the SET key.
3. Move the cursor to the "① MEAS SELECTION" item in the lower part of the window using the up and down keys. Then press the SET key.

(6) Setting the measurement program

```

[TYPE MEAS COND]
[MEASUREMENT 1]
① MEAS SELECTION NO POSI-DEVIATION CHK-DEG-MATCH
INSPECT-LEAD INSPECT-BGA/CSP
MEAS-BIN-AREA CNT-BIN-OBJ LABEL-BIN-OBJ
POINT-MEAS MULTI-POSI MULTI-MATCHES
② SELECT CAMERA CAM1 CAM2
③ CHNG GRAY LABEL NO YES(00.0TIMES  $\gamma+$   $\gamma-$  CHNG-L INCRS-M)
④ SPACE FILTER NO NUM-OF-TIMES 0(0~5)

OPS-MENU RETURN LOCK
    
```

1. Move the cursor to the "MEAS-BIN-AREA" item using the left and right keys, and press the SET key.
2. Press the ESC key.

(7) Setting the registration number (00 is selected in this example)

```

[TYPE MEAS COND]
⑥ MEASUREMENT 1 MEAS-BIN-AREA C1 (MEAS-COND)
[MEAS COND]
⑦ WINDOW NUM-OF-MASKS(1 2 4) BINARY-IMG-MASK
⑧ REGISTER NO. 00(0~15) NO YES
⑨ BINARY AREA COND NUMERIC CALC
OPS-MENU RETURN LOCK EVALUATION NUM-CALC OUT-COND
OPS-MENU RETURN LOCK EVALUATION NUM-CALC OUT-COND
    
```

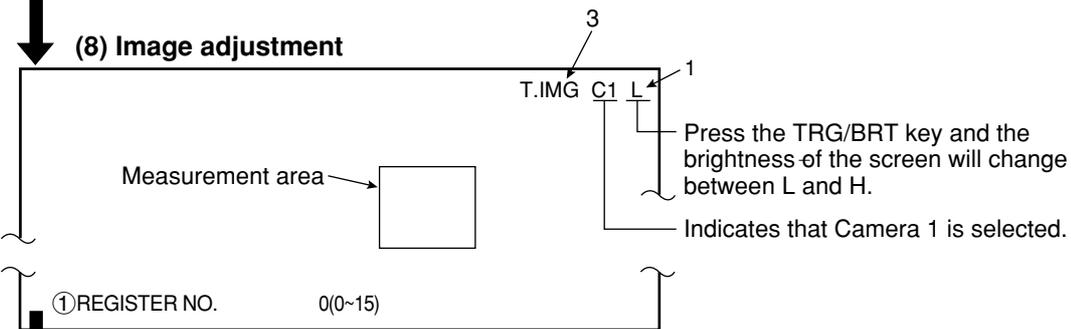
00	01	02	03	04	05	06	07	08	09	10	11	12	13	14	15
○	X	X	X	X	X	X	X	X	X	X	X	X	X	X	X

1. Move the cursor to "MEAS-COND" using the left and right keys, and press the SET key.
2. Move the cursor to the "② REGISTER NO." item in the lower part of the window using the up and down keys. Then press the SET key.
3. Move the cursor to "YES" using the left and right keys, and press the SET key.
4. Move the cursor to the "③ BINARY AREA COND" item using the up and down keys, and press the SET key.
5. Move the cursor to the circle below the registration number 00, and press the SET key.

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Continued from the previous page

(8) Image adjustment



1. Press the SEL key.
 - ⇒ The image taken by camera 1 will be displayed.
 - When the image is so bright that the menu display is difficult to see, press the TRG/BRT key to reduce the brightness of the image. The indicator in the upper right corner of the screen will change from "H" to "L."
2. To display the image of the object measured clearly, adjust the focus and iris opening of the camera lens (page 4-1).
3. Press the SEL key to change the screen to the freeze mode.
 - ⇒ The indicator in the upper right corner of the screen will change from T.IMG to F.IMG.
 - To set a threshold for a binary area, make sure the machine is displaying the freeze screen. (For details about the through and freeze modes, see page 7-4.)
4. Press the ESC key to display all of the binary area conditions.

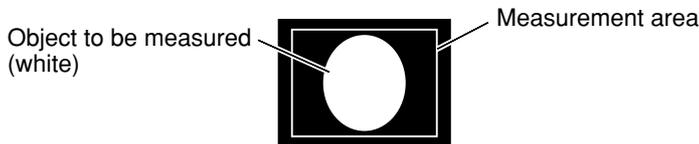
(9) Setting the binary area condition (measurement area)

① REGISTER NO.	00(0~15)
② MEAS SHAPE	RECTANGLE CIRCLE ELLIPSE
③ MEAS AREA	MOVE UP.L(224,208) LO.R(287,271)
④ MASK SHAPE	NO RECTANGLE CIRCLE ELLIPSE
⑤ AUTO REGIST	EXEC(L LIMIT ONRY U&L LIMITS)
⑥ THRESHOLD	U.LM255 L.LM100(0~255)
⑦ INVERT B/W	NO YES
⑧ BINARY PROCESS	FIXED THRESHOLD-ADJ(VAR-DIFF VAR-RATE)
⑨ BINARY NOISE FILT	NO EXPD.→CONTR. CONTR.→EXPD
⑩ NUM.OF FILT PASS	EXPD.0 CONTR.0(0~5)
OPS-MENU	RETURN LOCK EVALUATION

- If the menu overlaps the object to be measured, so that further image condition setting is difficult, press the ESC key. Only one item will be displayed at a time.
- The image shown in the measurement area has already been through binary conversion.

1. Move the cursor to the "③ MEAS AREA" item, and press the SET key.
2. Surround the object to be measured with the measurement area (RECTANGLE: solid line).
 - Move the cursor to the "MOVE," "UP.L," or "LO. R," label and press the SET key.
 - After the position has been finalized, press the SET key.

MOVE	The whole rectangle is moved using the up, down, left or right keys (one pixel at a time).
UP.L	The upper left corner is moved using the up, down, left or right keys (one pixel at a time).
LO.R	The lower right corner is moved using the up, down, left or right keys (one pixel at a time).

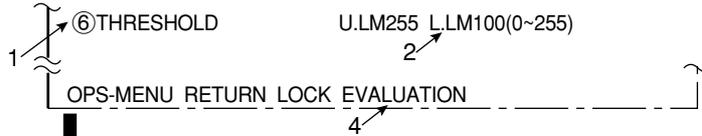


- After determining each position in the measurement area, press the SET key.

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(10) Setting the binary area conditions (threshold)



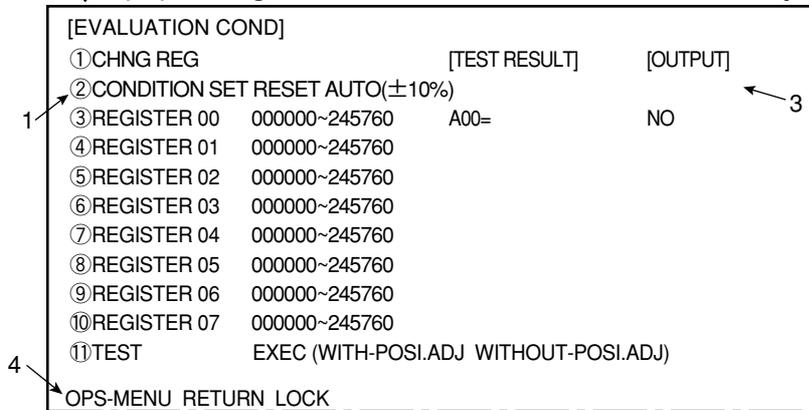
1. Move the cursor to the "⑥ THRESHOLD" item using the up and down keys, and press the SET key.
2. Move the cursor to the "L.LM" item and then press the SET key.
3. Move the cursor to each digit using the left and right keys, and increase or decrease the values using the up and down keys.

L.LM 100(0~255)

This cursor will move to the left and right.

- To set the threshold parameters, see the section in the Glossary which describes them.
 - After determining the lower limit, press the SET key, and then the ESC key.
4. Move the cursor to the bottom line using the up and down keys, and select the "EVALUATION" item using the left and right keys. Then press the SET key.
⇒ The [EVALUATION COND] menu will be displayed.

(11) Setting the evaluation conditions and result output



1. Move the cursor to "② REGISTER 00" and press the SET key.
2. Move the cursor to the upper limit position with the left and right keys, and press the SET key.
- Select the digit to change with the left and right keys, and then set the value to 002000 with the up and down keys.

② REGISTER 00 000000~002000

- After specifying the upper limit value, press the SET key, and then the ESC key.
3. Move the cursor to "OUTPUT" using the left and right keys.
- Select "Y0" using the up and down keys, and press the SET keys.

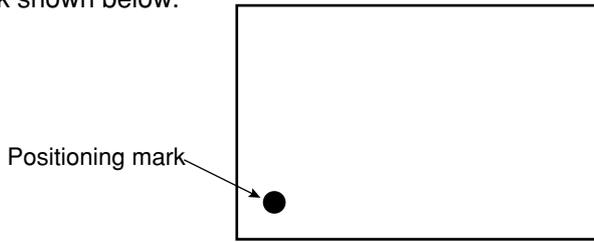
[OUTPUT] Y0

4. Move the cursor to the "OPS-MENU" item using the up and down keys.
⇒ The screen will return to the MAIN OPS MENU.

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[2] Positional deviation measurement

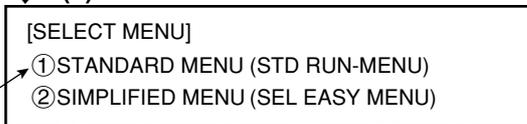
The following sections cover an example of how to measure the positional deviation of the positioning mark shown below.



(1) Power ON

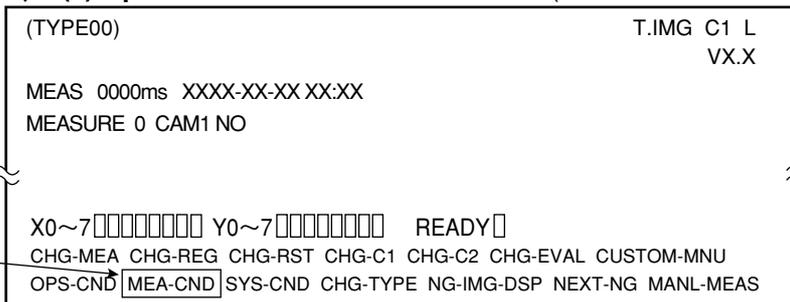
When power is first turned ON after the machine is delivered, the [SELECT MENU] screen will appear.
 - When the MAIN OPS MENU used by the simplified menus (positioning) is displayed, the operations covered in step (2) is not needed.
 - If the MAIN OPS MENU used by the standard menus is displayed, please change to the simplified menus screen. ⇨ See page 6-5.

(2) Select menu



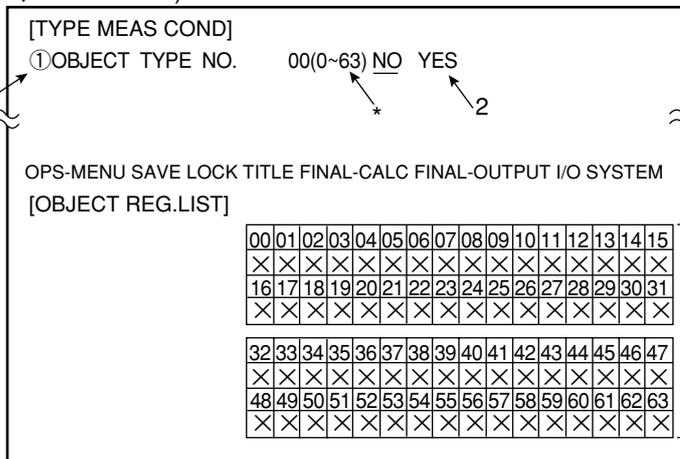
1. Move the cursor to the "① STANDARD MENU" item with the up and down keys, and press the SET key.
 ⇨ The standard mode [MAIN OPS MENU] screen will appear.

(3) Operation on the MAIN OPS MENU (all the conditions are initialized)



1. Move the cursor to the "MEA-CND" item using the left and right keys, and press the SET key.
 ⇨ The [TYPE MEAS COND] menu will be displayed.

(4) Registration of an object type number (the object is registered in 00 with the IV-S33M)



* Object type number
 IV-S33M: 00 to 63
 IV-S32M: 00 to 31
 IV-S31M: 00 to 15

← Circles will be displayed below object type numbers that are already registered.

1. Move the cursor to the "① OBJECT TYPE NO." item using the up and down keys, and press the SET key.
 2. Move the cursor to "YES" using the left and right keys, and press the SET key.
 ⇨ Items ② to ⑧ will be displayed.

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Continued from the previous page



(6) Setting the gray scale search conditions

① REGISTER NO.	0(0~7)
② MEAS SHAPE(MDL0)	RECTANGLE X-LINE Y-LINE
③ REF IMG(MDL0)	NEW EXIST000(000~000)
④ REF IMG ARE(MDL0)	MOVE UP.L(216,200) LO.R(295,279) CONTRAST SR REG DISP
⑤ SEARCH ARE(MDL0)	MOVE UP.L(216,200) LO.R(295,279)
⑥ DTECT CRD(MDL0)	CENTER FREE(255,239)
⑦ CONTR.PIXL(MDL0)	1 2 3

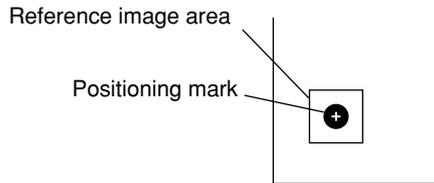
OPS-MENU RETURN LOCK EVALUATION

- If the menu overlaps the object to be measured, so that further image condition setting is difficult, press the ESC key. Only one item will be displayed at a time.

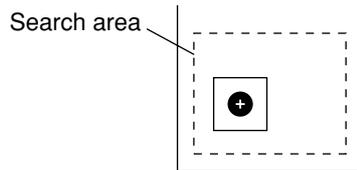
1. Move the cursor to the "④REF. IMG ARE (MDL 0)" item, and press the SET key.
2. Surround the object to be measured with the reference image area (solid line).
 - Move the cursor to the "MOVE," "UP.L," or "LO. R," label and press the SET key.

MOVE	The whole rectangle is moved using the up, down, left or right keys (one pixel at a time).
UP.L	The upper left corner is moved using the up, down, left or right keys (one pixel at a time).
LO.R	The lower right corner is moved using the up, down, left or right keys (one pixel at a time).

After the position has been finalized, press the SET key.



- After the reference image area position has been set, move the cursor to the "REG." item using the left and right keys, and press the SET key.
 - The stored image will be displayed in the lower right corner of the screen. After storing the image, press the ESC key.
3. Press the ESC key and move the cursor to the "⑤SEARCH ARE (MDL 0)" item. Then, press the SET key.
 4. Create a search area (dotted line).
 - The search area described above is the range for detecting the image registered in step 2, using the gray scale search function (see the Glossary).
 - The procedure for creating the search area is the same as described for the reference image area in step 2.



- After determining the search area position, press the ESC key.
5. Move the cursor to the bottom line using the up and down keys, and select the "EVALUATION" item using the left and right keys. Then press the SET key.
 - ⇒ The [EVALUATION COND] menu will be displayed.

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(9) Setting the position evaluation conditions

[EVALUATION COND]			
	[REGISTER NO.]	[TEST RESULT]	[OUTPUT]
1	① REGISTER NO. → 0(0~7)	AUTO(±10%)	
	② CONDITION SET RESET	NO	
	③ X COORD.(MDL0) 000.0~511.0 X0=	Y0=	NO
	④ Y COORD.(MDL0) 000.0~479.0	x0=	NO
	⑤ x DEVIATE(MDL0) -511.0~+511.0	y0=	NO
2	⑥ y DEVIATE(MDL0) -479.0~+479.0	M0=	NO
	⑦ MATCH LVL(MDL0) → -10000~+10000		
3	OPS-MENU RETURN LOCK		

1. Move the cursor to the "① REGISTER NO." item using the up and down keys, and press the SET key. Select "0" using the up and down keys, and press the SET key.
2. Move the cursor to "⑥ MATCH LVL (MDL0)" and press the SET key.
3. Move the cursor to the lower limit position with the left and right keys, and press the SET key.
 - Select the digit to change with the left and right keys, and then set the value to +09000 with the up and down keys.
 - (Criteria for a successful match: 90.00% to 100.00%)

⑦ MATCH LVL(MDL0) +09000~+10000

- After specifying the lower limit value, press the SET key, and then the ESC key.
4. Move the cursor to the bottom line using the up and down keys, and select the "RETURN" item using the left and right keys. Then press the SET key.
 - ⇒ The screen will return to the gray scale search menu.
 5. Move the cursor to the bottom line using the up and down keys, and select the "RETURN" item using the left and right keys. Then press the SET key.
 - ⇒ The screen will return to the [TYPE MEAS COND] menu.

[TYPE MEAS COND]			
①	OBJECT TYPE NO.	00(0~63)	NO YES
②	SELECT CAMERA	CAM1&2	CAM1&NG-IMG
③	IMG PRE-PROCESS	(TO NEXT SUB-MENU)	
OPS-MENU SAVE LOCK TITLE FINAL-CALC FINAL-OUTPUT I/O SYSTEM			

6. Press the ESC key three times.
7. Move the cursor to the "FINAL-OUTPUT" item using the up/down and left/right keys. Then press the SET key.
 - ⇒ The [FINAL OUTPUT COND] menu will be displayed.

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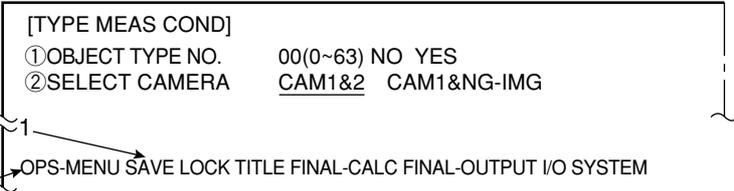
Continued from the previous page

(11) Saving data

Although the specified data is temporarily stored in RAM memory, it is not stored in the flash memory. So, you must save the data manually using the save operation. If you do not save the data in the flash memory, it will be deleted when the IV-S30 controller is turned OFF.

- You can save data at any time using the "SAVE" item on the [TYPE MEAS COND], [TYPE RUN COND], or [SYSTEM COND] menu.

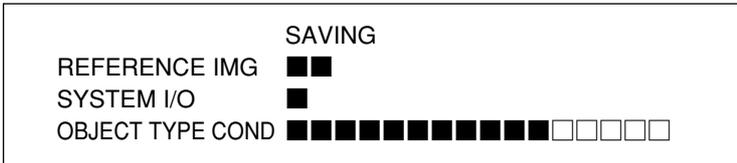
(In this example, data is saved while in the [TYPE MEAS COND] menu.)



1. Move the cursor to the "SAVE" item using the left and right keys, and press the SET key.
⇒ The following message will be displayed on the screen.

DATA SAVE? (Do you want to save the data?) (YES=[SET]/NO=[ESC])

2. Press the SET key.
⇒ The IV-S30 will start saving the data and the progress will be displayed on the bottom of the screen.



When the data has been saved in the IV-S30 flash memory, the display will change from "SAVING" to "COMPLETE SAVE."

3. Move the cursor to the "OPS-MENU" item using the left and right keys, and press the SET key.
⇒ The screen will return to the MAIN OPS MENU.

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Continued from the previous page

Press the TRG/BRT key, and the result of the positional deviation measurement of the registered positioning mark will be displayed.

(12) Positional deviation measurement

[Display of the measured result]

Final evaluation result (*1)
 Measuring time
 Registration number
 Detection coordinates of the reference image
 Amount of deviation from the reference image
 Degree of match of the reference image (*2)

```

(TYPE00)
F.IMG C1 L
VX.X
OK
MEAS XXXXms 1999-08-01 10:30
MEASURE 0 CAM1 POSI-DEVIATION
REGISTER NO(0~7)
X0=379.0 OK
Y0=214.0 OK
x0=+001.0 OK
y0=+000.0 OK
M0=+09735 OK
B0=

X0~7  Y0~7  READY
CHG-MEA CHG-REG CHG-RST CHG-C1 CHG-C2 CHG-EVAL CUSTOM-MNU
OPS-CND MEA-CND SYS-CND CHG-TYPE NEXT-NG RE-EXAM-NG MANL-MEAS
    
```

*3

*1 The final evaluation result will be displayed as "OK" in the upper left corner of the screen when all of the items have been evaluated acceptable. If there is a single unacceptable item, "NG" will be displayed.

*2 "M0 +09735" means that the degree of match (percentage of pixels that match) between pixels in the stored image and the measured image is 97.35%.

[The acceptance and rejection criteria based on the degree of match]

In order to evaluate acceptability based on the degree of match, first an image of a good specimen is stored for reference. Then, an image of defective specimen is compared for degree of match. Finally an image of another good specimen is compared. These comparisons establish the degree of match to be used for setting the limits used for working comparisons. For example, the degree of match for a non-defective object is 90% or more and that for a defective object is 70% or less, then the threshold value for degree of match can be set to approx. 85%. This allows the evaluation acceptability to be made.

*3 When the final evaluation result is OK, Y0 is turned ON, and a filled box is displayed. (When the result is NG, an empty box is displayed.) When the auxiliary relay C112 is turned ON, Y0 is turned ON according to the condition set in step (10) for final evaluation output.

- For details about saving data, see page 9-14.

Glossary

[A]

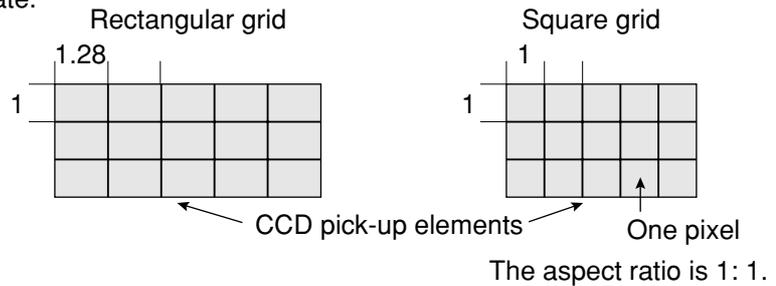
■ **Area filter**

A function used to eliminate an island if its area is smaller than the specified size after each of the objects in an image have been identified.

■ **Arrangement of the square pixels**

This refers to CCD elements whose pixels are square and arranged at the same vertical and horizontal interval.

If this type of CCD element is used, length corrections do not need to be calculated and the precision and processing time do not deteriorate.

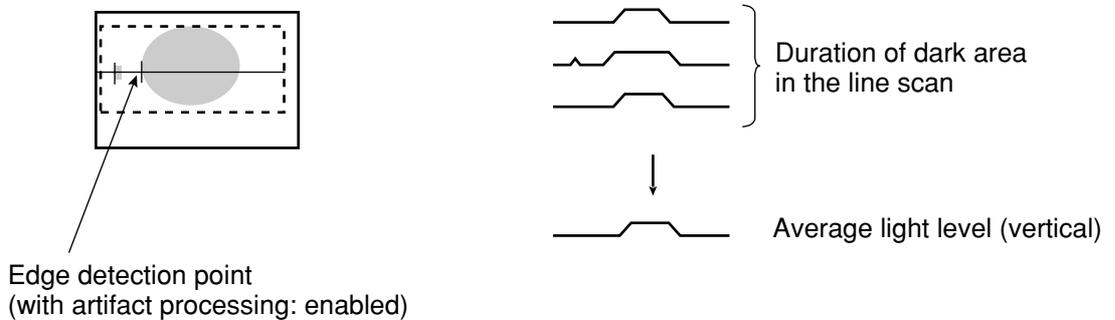


■ **Artifact processing**

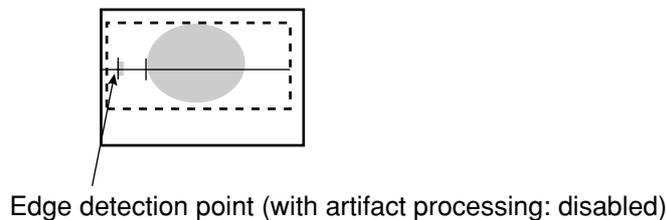
Artifact processing is a method of processing that eliminates the false detection of the edge of the target object when an artifact is in the line being scanned. This process can be used during edge detection. The real edge of the target object is detected by computing the average duration of the dark area.

[Example of detection]

- An example of light to dark averaging (DTCT MODE: BRT ⇔ DRK) while scanning horizontally (SEARCH DIR.: HORIZ ⇔), with artifact processing (enabled) .



When artifact processing is disabled in the above example, the edge detection point changes.



[B]

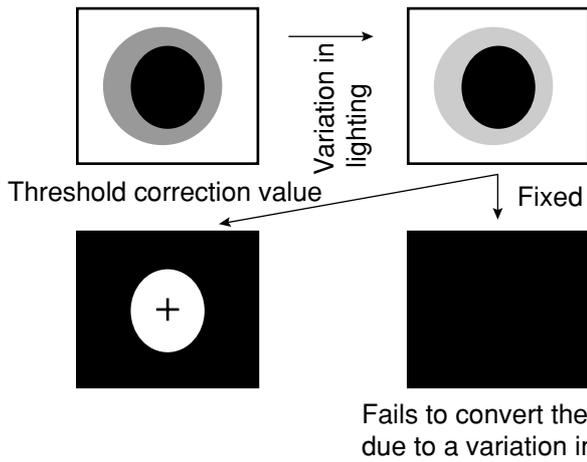
■ **Binary image**

Pixels in images are converted to one of two values, "1" when the pixel is lighter than the specified threshold value (level), and "0" when it is darker than the specified threshold value (level).



■ **Binary processing (fixed/threshold value correction)**

By setting THESHLD. ADJ (threshold adjustment function), the IV-S30 can cope with variations in lighting.



Note: In order to use the THRESHOLD (threshold adjustment function), the monitor brightness functions must be selected to measure variations in lighting. If you don't select the monitor brightness function, a BINARY CORR.: LIGHT LVL NOT SET (correcting binary value: monitor illumination not selected) error will occur.

■ **Boundary processing**

⇒ See "Setting window boundaries (enable/disable)."

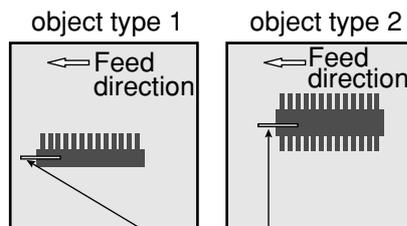
[C]

■ **CCD (charge capture device)**

A charge capture device (CCD) converts light into electric signals. It consists of a photo-electric converter to convert light and store it as an electric charge signal, a scanner to read the stored electric charges, and an output section to transmit the signals as a stream of data.

■ **CCD trigger**

The CCD trigger allows sampling a part of the CCD camera image at high speed. When the sampled image changes, the camera starts the shutter operation to capture a new image. With this built-in shutter operation, an external sensor, such as a photo sensor, is not needed to trigger the shutter. A window can be created to trigger the shutter operation. The window can be set for each item on the production line so that adjustments to the position of an external sensor are no longer needed. This feature reduces the down time needed to change object types on production lines.



■ **Center of gravity**

The "center of gravity" is the geographical center of the image. It is determined by treating the binary image to be measured as an object that has mass.

■ **C mount**

A system for mounting lenses on a camera body. The flange back (the distance from the reference level for mounting a lens to the focal plane surface) is defined as 17.526 mm.

■ **Computer link**

Programmable controllers (PC) are equipped with communication protocols. The "computer link" is used to transfer data between the PC and an external computer, or the like, using this communication protocol. The IV-S30 supports the computer link protocols used by Sharp, Omron, and Mitsubishi PCs. Therefore, the PC does not need a custom communication program in order to create a computer link with the IV-S30.

■ **Contraction**

⇒ See "Expansion and contraction to eliminate binary noise in the image."

[E]

■ **Edge emphasis**

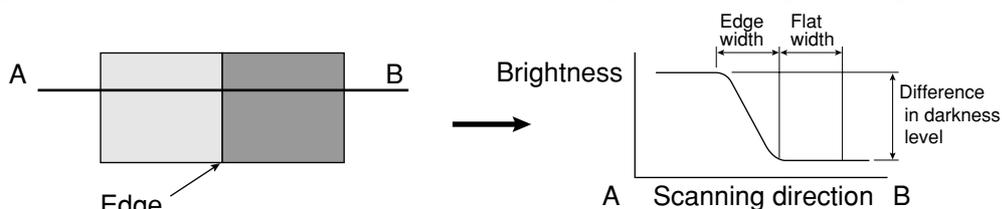
⇒ See "Space filter."

■ **Edge extraction**

⇒ See "Space filter."

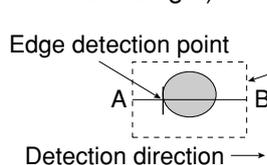
■ **Edge detection**

The "edge" refers to the boundaries between the brighter (white) and darker (black) parts in an image. The "edge detection" function is used to detect this boundary by processing the image.

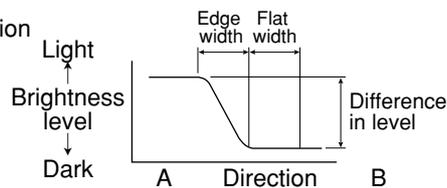
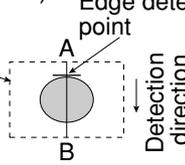


[An example of detecting a point using the edge detection function and user specified criteria]

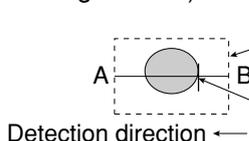
- Horizontal transition point from light to dark (moving from left to right)



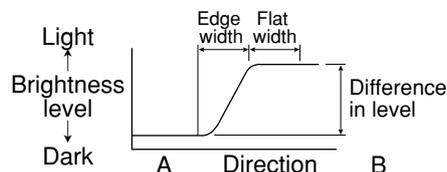
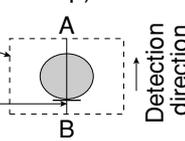
- Vertical transition point from light to dark (moving from top to bottom)



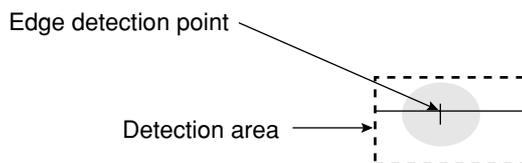
- Horizontal transition point from light to dark (moving from right to left)



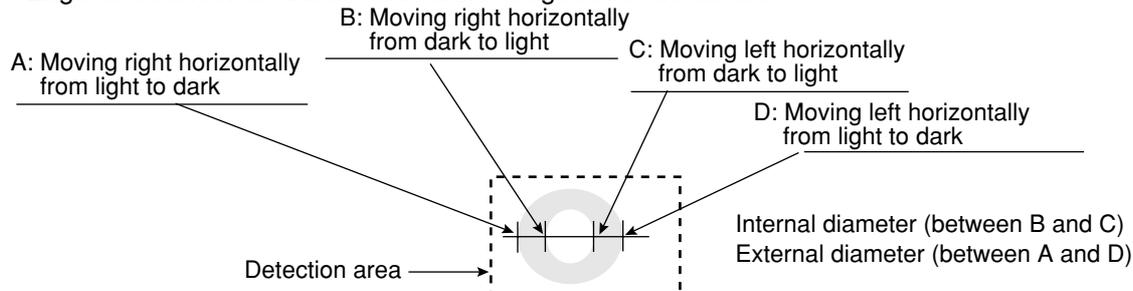
- Vertical transition point from light to dark (moving from bottom to top)



- Center (dark), horizontal (left and right)



- Edge detection of the inside and outside edges of a two circles



■ **Expansion**

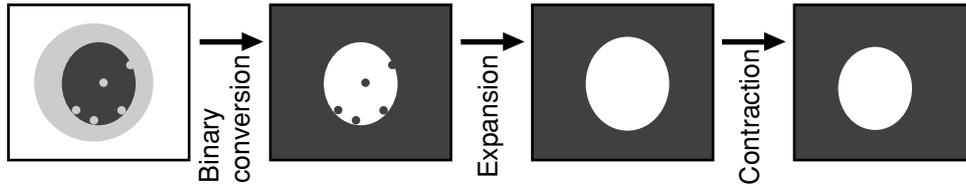
⇒ See "Expansion and contraction to eliminate binary noise in the image."



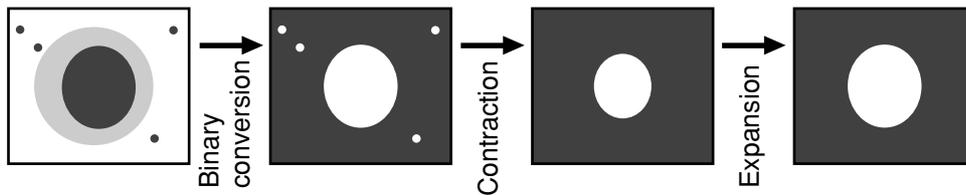
■ **Expansion and contraction to eliminate binary noise in the image**

When an image is converted to black and white, a number of unwanted dots may appear in the image. These noises can be eliminated during the preliminary processing. Dot control processing of binary values is used to eliminate this problem, as described below.

- ① Expansion
If a white area contains a single, isolated black point, the system will interrupt the black point to white.
- ② Contraction
If a black area contains a single, isolated white point, the system will convert the white point to black.
- ① Expansion → contraction
Delete isolated black points by expansion and then restore the original image size by contraction.



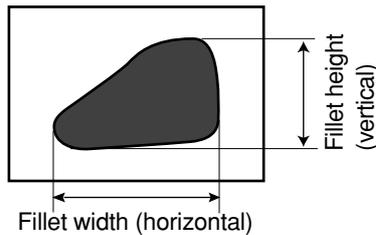
- ② Contraction → expansion
Delete isolated white points by contraction and then restore the original image size by expansion.



[F]

■ **Fillet width (shading width)**

Size of a hollow rectangle which closely matches to the target object in a binary image (white part). Horizontal direction: Length of a side parallel to the X axis. Vertical direction: Length of a side parallel to the Y axis.



■ **Flat width**

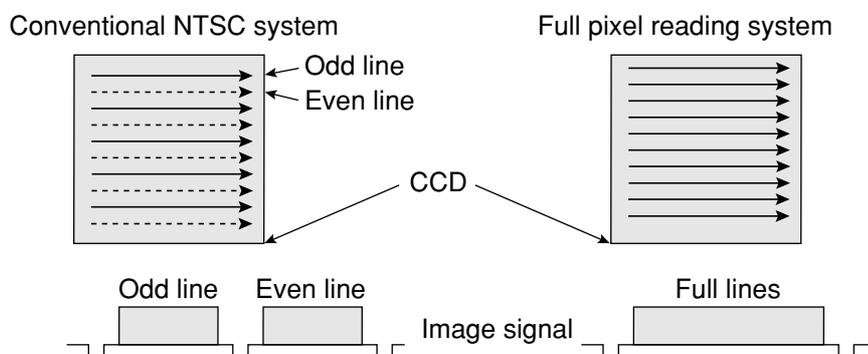
⇒ See "Edge detection."

G

■ Full pixel reading (progressive scan)

A system which reads all of pixels of image information from the CCD element one after another is referred to as "full pixel reading system." This system provides the same high resolution for moving objects as it does for static objects.

On the other hand, conventional CCDs using the NTSC scanning technique must read an object two times. First the odd lines are read and then the even lines. Therefore, NTSC system produces blurry images of moving objects. In order to solve this problem, the NTSC system can read only the odd lines. The disadvantage is that only half the resolution is available.



[G]

■ Gray scale check using the normalization correlation method

Even when the IV-S30 is looking at the same object as the object used for the reference image, the new target image and the previously stored reference image may not match completely, due to variations in the illumination conditions and the ambient light.

In order to check the resemblance between the two sets of image data, the normalization correlation method can be used.

In order to check whether or not the levels match using the normalization correlation method, the system slides the reference image one pixel at a time in the measurement objective range (measurement window), and calculates correlation value between the reference image and the target image. The position where the maximum correlation value can be obtained is treated as the position where the target image might exist, and the IV-S30 calculates resemblance level at this position.

The normalization correlation method also can be applied to binary images. However, gray scale images (images with shades of light) contain large volumes of information, compared with binary images (images with 256 levels of gray have 256 times the volume of information than in binary images). Therefore, gray-scale images offer more precision and more reliable results.

However, the larger the information volume, the larger the number of calculations that must be made for correlation values. This means that high speed processing hardware and software are required to use the normalization correlation method on the gray scale images.

■ Gray scale processing (gray image processing)

This is a process used to handle the unmodified captured image data, obtained from the CCD camera. In other words, the image data is not converted to binary values.

- This process produces more precise results than binary image processing (one pixel = one bit) by using 8 bits (one pixel = 256 gray levels) to represent each pixel in a gray scale image.

[Advantage] Theoretically, better precision and reliability can be offered because the image contains more information about the brightness of each pixel in the image.

[Disadvantage] More processing time is required because this approach must handle a large amount of data.

■ **Gray scale search (corrected gray scale search)**

The "gray scale search" function is a system for detecting a point where the input image and the reference image match, after calculating the matching levels in the input image and the reference image.

[Procedures]

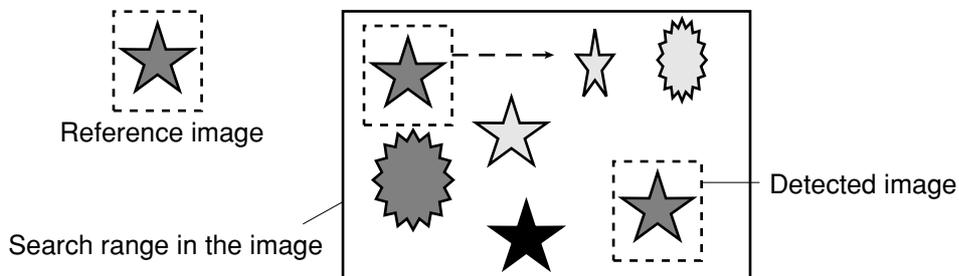
- ① Store the reference image as a gray scale image with 256 levels of gray.
- ② Capture the workpiece image to be measured.
- ③ Move the captured image of the object so that the upper left corner of the captured image is right on top of the upper left edge of the reference image. Calculates the level of matching between the two images, based on the stored gray scale image data.
- ④ Slide the reference image over one pixel width and then measure the level of matching at that position.
- ⑤ Repeat step ④ above for the whole workpiece image until a good match is found.

(Output)

Maximum matching level value
The center coordinates where the highest level of matching is obtained

(Application)

Shape inspection
Positional deviation measurement



[H]

G

■ **Halogen lamp**

Light source with halogen gas in the bulb. When a halogen lamp is lit, the halogen gas and vaporized tungsten combine. When the filament is heated, these combined particles reattach to the tungsten, instead of being deposited on the glass bulb, so that the original brightness of the lamp is maintained throughout its life span.

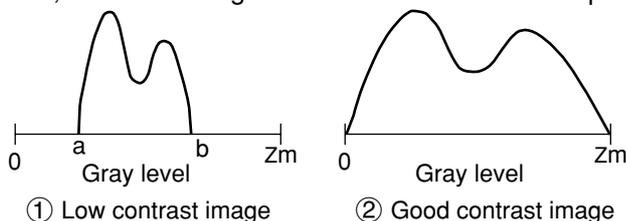
■ **High frequency lighting**

If a fluorescent lamp is powered by commercial electricity, it will flicker at 50 Hz or 60 Hz. Since the CCD scans images at 60 Hz, the brightness of the image may fluctuate due to the flickering of the fluorescent lamp.

By increasing frequency used to power the fluorescent lamp (employing a high frequency light), this type interference is eliminated and a stable image can be obtained.

■ **Histogram widening**

This is a method to widen the histogram for an image in which the histogram only occupies part of the available scale, thus improving the contrast. For example, in figure 1, the gray level values are concentrated in the [a, b] part of the range, and the [0, a] and [b, Zm] parts of the range are not used (the histogram is not expanded to use all of the gray scale values). This image has low contrast, since the image does not use the full dynamic range efficiently. Expand the histogram to cover the entire range of gray scale values, as shown in figure 2. The contrast will be improved.



[I]

■ Illumination monitor alarm density setting

The "illumination (light level) monitor" is a function which automatically monitors the environmental lighting conditions when measuring objects.

If the illuminance exceeds the alarm density setting, the IV-S30 will display an alarm message.

■ Interline transfer system

The interline transfer system is a system for transferring electrical charges from the CCD receiving elements to the read-out matrix.

The frame transfer system is a system for transferring electrical charge which uses the photo sensitive area to read out the charges. This system is subject to smearing noise since the area is used for both receiving and transferring the image.

■ Island

An "island" is a separate area which is created after labeling (object identification) process of the binary image.

[M]

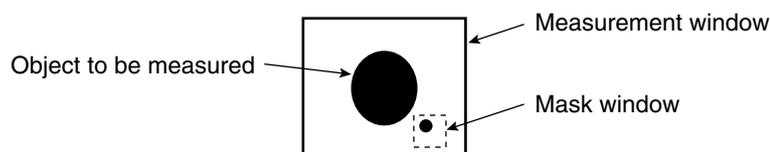
■ Main axis angle

The acute angle between the longitudinal and horizontal axes of a shape in the image after the measurement object is converted to binary. This angle cannot be measured for nearly circular or square-shaped objects.



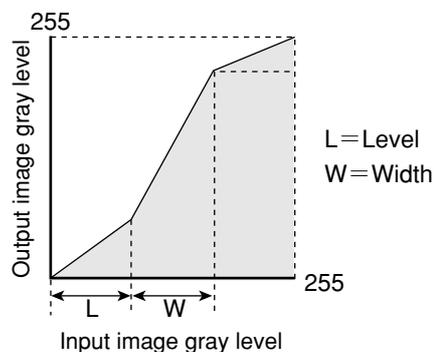
■ Mask window

The image being examined may contain an area that does not need to be processed. To eliminate such an area, a mask window is used.



■ Mid gray level emphasis

Emphasize the mid gray level. This improves contrast while remaining the background image.



[N]

■ **Normalization correlation**

To determine whether the levels between the reference image and the input image match, the IV-S30 uses an information processing method called "normalization correlation." This is a method used to calculate relationship between two groups of data.

- Factors determining the correlation value

If the densities of the two images have the same tendency (positive correlation), the two images are said to resemble each other. If the densities of the two images have opposite tendencies (negative correlation), the two images are said not to resemble each other. Therefore, areas of the reference image and the input image which resemble each other (the areas of both images are brighter, or darker) are positive, and areas which do not (the areas of one is brighter and the other is darker) are negative.

- Correlation formula = $\{ A \div \sqrt{B \times C} \} \times 10000$

A = $N \Sigma (I \times T) - (\Sigma I) \times (\Sigma T)$: Correlation between input image and reference image

B = $N \Sigma (I \times I) - (\Sigma I) \times (\Sigma I)$: Correlation between input images

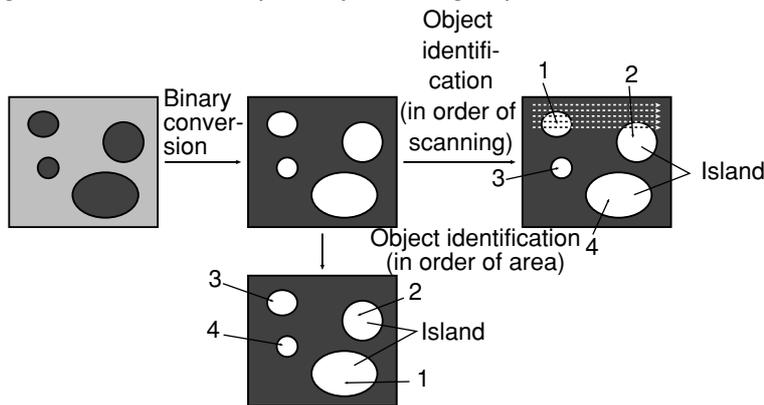
C = $N \Sigma (T \times T) - (\Sigma T) \times (\Sigma T)$: Correlation between reference images

(N: Area of reference image, T: Density of reference image, I: Density of input image)

[O]

■ **Object identification and numbering function (labeling)**

Object identification and numbering (labeling) is a process for locating separate object and assigning serial numbers (labels) one at a time in a binary image. By this process, multiple objects in the same binary image can be handled separately or as a group.



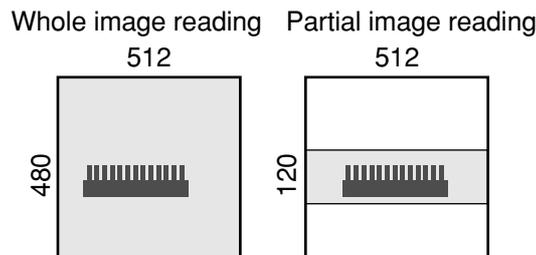
G

[P]

■ **Partial CCD reading**

The "partial CCD reading" technique reads only that part of the CCD which contains the object needed for image processing. This can shorten the data transfer time from the CCD camera to the image memory. To read the entire CCD image (480 horizontal lines) takes approximately 33 ms. With the partial reading technique (e. g.: 120 horizontal lines) can take only 25 % of the time to read the entire image.

The IV-S30 can automatically determine the width of the partial image window. You can change back and forth between reading the whole image and a partial image.



■ **Pixel**

On the CCD, the electrically charged elements are in close proximity, arranged in a matrix (480 lines in vertical direction, 512 rows in horizontal direction). One element is equivalent to one pixel.

■ **Progressive scan**

⇒ See "Full pixel reading."

[R]

■ **Random shutter function**

This function allows the CCD camera shutter operation to be triggered when even an object to be measured reaches a specified position in the camera's field of view.

In order to make a partial reading of the CCD image at high speed, the IV-S30 is equipped with the detection function described above with the works just like a proximity sensor to trigger the CCD. A proximity sensor can also be connected to the system.

■ **Resolution**

The CCD in the IV-S30 contains 512 pixels horizontally and 480 pixels vertically. If it takes a full picture, the resolution will be X/512 and Y/480.

[S]

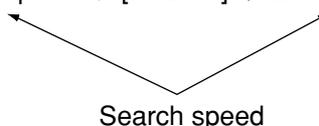
■ **Search area**

A portion of the target image to be compared with the reference image, using the gray scale search function.

■ **Search pixel**

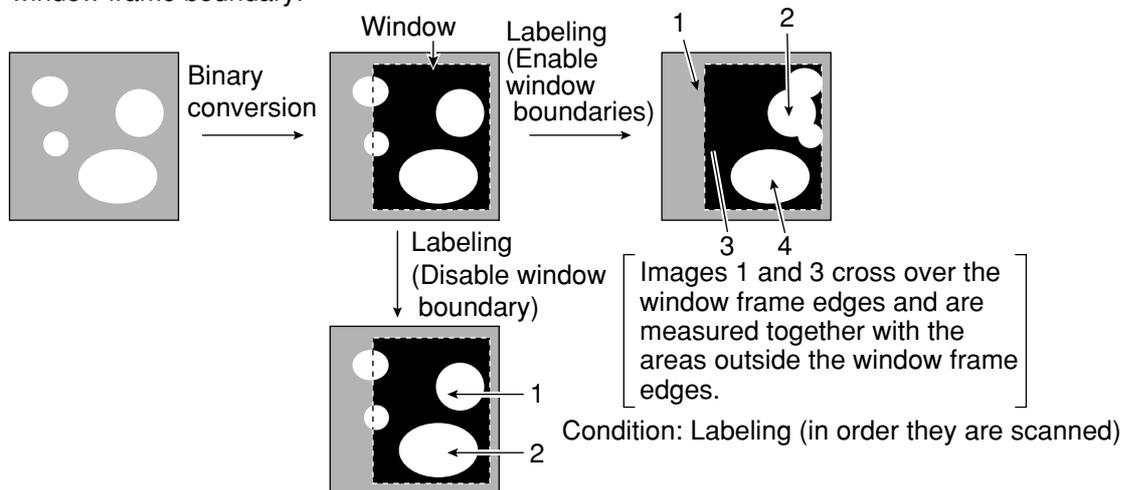
The relationship between detection precision and search speed, and also between pixel contraction (reduce the number of pixels in the image that must be searched) and search speed, is shown below:

- DETECTION PRECISION: High speed ← [STANDARD-HIGH] → Low speed
- PIXEL CONTRACTION: High speed ← [3 - 2 - 1] → Low speed



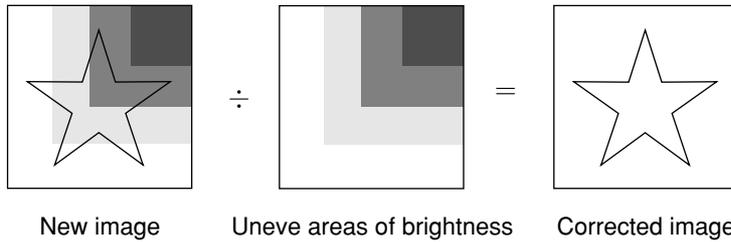
■ **Setting window boundaries (enable/disable)**

This function enables and disables the labeling (object identification) of binary images located that cross over the window frame boundary.



■ **Shading correction**

The process used to remove uneven gray areas (light level) from an image is called a shading correction. The figures below illustrate the principle of the shading correction. The new image has the areas of uneven brightness subtracted from it to produce a corrected image.



■ **Smoothing**

⇒ See "Space filter"

■ **Space filter**

Space filter includes various image manipulation processes that create more readable images by removing noise and distortion in the image data. And, by extracting or emphasizing certain image features, it is easier to evaluate or identify target objects by converting the images into standard patterns.

In the IV-S30, you can select a "smoothing (average, center)," "edge emphasis," "edge extraction," "horizontal edge," and "vertical edge."

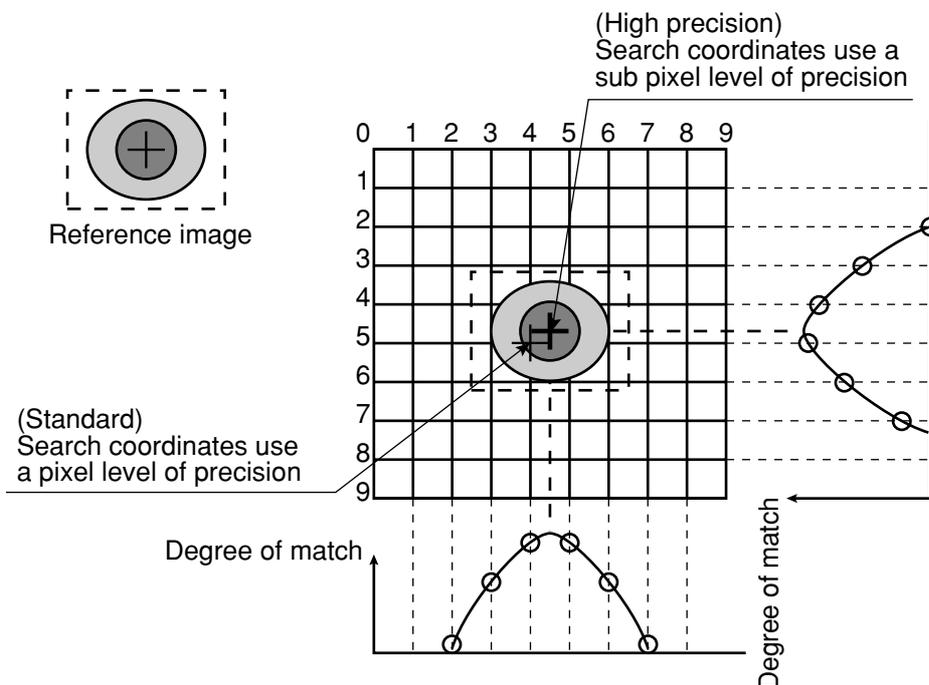
Item	Contents	
Smoothing (center)	- Specify the median pixel gray level from the surrounding 3 x 3 area. - Since noise elements are difficult to select, they will not affect the output.	- Display smooth images with decreased noise. - Used to eliminated surface flaws and unevenness in the reflected light caused by protrusions or dents. - This type of smoothing (averaging) is faster than the median smoothing.
Smoothing (average)	- Specify the average pixel gray level from the surrounding 3 x 3 area. - Since noise elements are included in the average, the noise will affect the output.	
Edge emphasis	- Display images with sharp boundaries between brighter and darker areas. - Used to stabilize and create a binary outline around unclear objects.	
Edge extraction	- Display images after extracting and clarifying the boundaries between the brighter and darker areas.	- Used to measure objects with low contrast.
Horizontal edge	- Horizontal edge extraction: Display only the horizontal boundaries of an object.	
Vertical edge	- Vertical edge extraction: Display only the vertical boundaries of an object.	

G

■ **Sub pixel, pixel**

Refers to the pixel precision level to be used with the gray scale search function.

- A "pixel" is one picture element (DTECT PRECISION: STANDARD (detection precision: standard) in case of the IV-S30). "Sub pixel" refers to a unit smaller than a single pixel (DTECT PRECISION: HIGH (detection precision: high) for 1/10 pixel in case of the IV-S30).



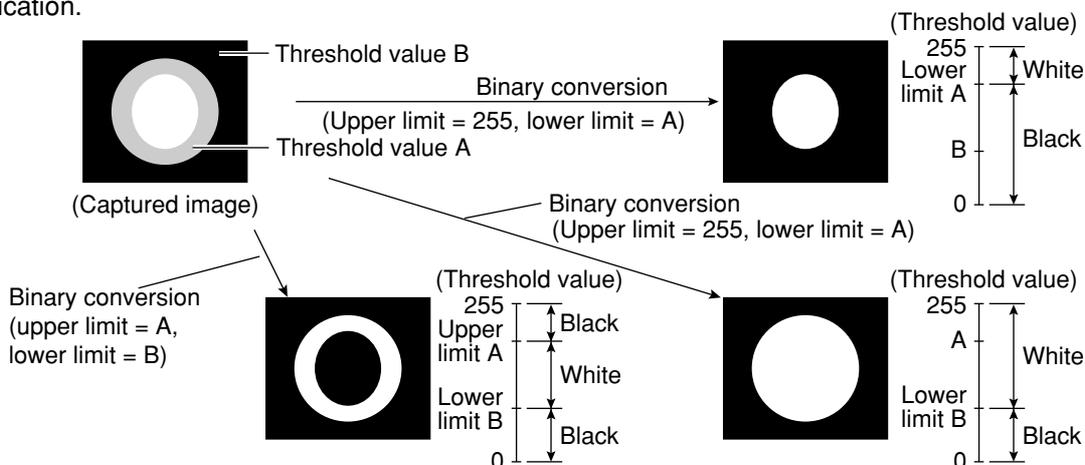
[T]

■ **Threshold value**

The criteria used for binary conversion of a gray scale image. If an area of the image is lighter than this threshold value, it is converted to 1. If an area of the image is darker than the threshold value, it is converted to 0.

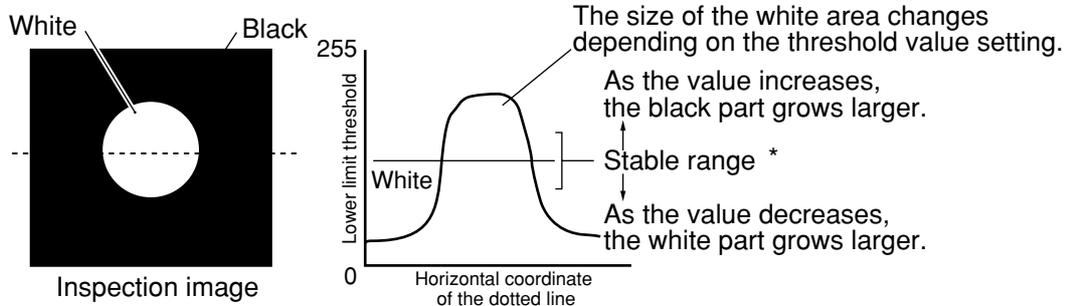
■ **Threshold value setting**

The IV-S30 treats the "areas darker than the lower limit value" or "brighter than the upper limit value" as "black." It treats that the areas between the upper limit value and lower limit value as "white." However, if the white-black reverse function is enabled, conversion to white/black will be reversed. Normally, if you want to use only one threshold value for binary conversion, set the upper limit value to "255." Then you only need to adjust the lower limit value to a threshold value that works for our application.



(Example for adjustment)

An example of adjustment is shown below, using a white object on a black background. When the dotted line in the window is converted to a binary image, if the lower limit is set higher, the black part in the binary image will become larger. If the lower limit is set lower, the white part will become larger. Increase and decrease the lower limit value, find the value at which the white part in the binary image starts growing and the value at which the black part starts growing. Then set the lower limit at the value halfway between these points. This will ensure reliable operation.



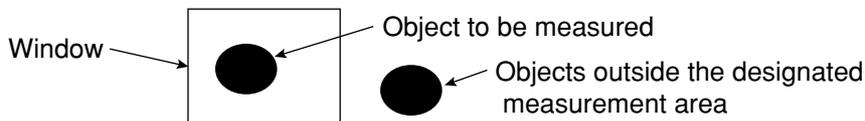
Changing the lower limit threshold value

[* If the stable range in the lower limit threshold value is less than 20, (actual measurement) measurement errors may occur.]

[W]

Window

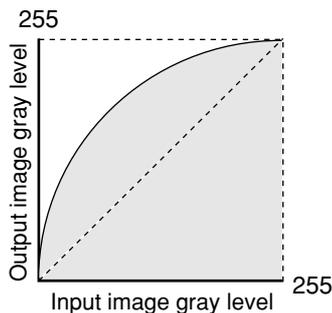
The IV-S30 captures images using CCDs, which are the light sensitive elements in the camera. The IV-S30 may capture more than one target image to be measured for image processing, and it may capture images not required for measurement. In these cases, a window is used to pick out just the desired target for measurement. The area inside the window will contain the object to be measured and the areas outside the window will be ignored.



[γ]

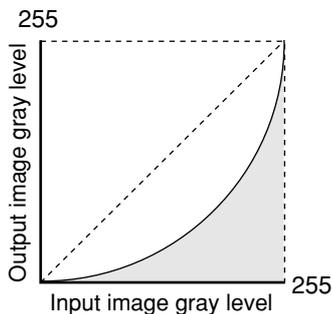
γ positive correction

Used when the mid gray level is too low.



γ negative correction

Used when the mid gray level is too high.



Appendix

Appendix 1: Commercially available peripheral devices

Described below for your reference are peripheral devices needed to build a system around the IV-S30. (Items handled by SHARP are listed on the next page.)

(1) Lighting equipment

Supplier	Address	Phone
Moritex Corporation	3-1-14, Jingumae, Shibuya Ku, Tokyo, 150-0001	03-3401-9711
Nippoin-PI	1-17-1, Toranomom, Minato Ku, Tokyo, 105-000	03-3504-3321
Dentsu Sangyo Co., Ltd	6-1, 3 Chome, Kamifukuoka, Kamifukuoka City, Saitama, 356-0004	0492-64-1391
Hayashi Watch-Works Co., Ltd., Special Item Department	1-28-3, Kita Otshuka, Toshima Ku, Tokyo, 170-000	03-3918-5237

(2) Lens (mirror barrel)

Supplier	Address	Phone
Moritex Corporation	3-1-14, Jingumae, Shibuya Ku, Tokyo, 150-0001	03-3401-9711
Seiwa Optical Mfg. Co., Ltd.	12-17, 4 Chome, Yayoi Cho, Nakano Ku, Tokyo, 164-0013	03-3383-6301
Asahi Precision Co., Ltd., Optical machine Department	1-21, 1 Chome, Shirako, Wako City, Saitama 351-0101	048-466-8801
CBC Co., Ltd.	2-15-13, Tsukishima, Chuo ku, Tokyo, 104-0052	03-3536-4766
Tamuron Co., Ltd., Special Item Sales Department	1385, Hasunuma, Ohmiya City, Saitama, 330-0015	048-684-9129
Canon Sales Co., Ltd., Optical Lens Sales Department	2-13-29, Minato Minami, Minato Ku, Tokyo, 108-0072	03-3740-3388

(3) Optical filter

Supplier	Address	Phone
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App.

■ Table of standard items related to the IV-S30 handled by SHARP

SHARP's article Nbr.	Moritex's article Nr.	Item name	Specifications
IV-1A0101	ML-0614	CCTV lens	C mount f = 6 mm
IV-1A0102	ML-0813	CCTV lens	C mount f = 8 mm
IV-1A0103	ML-1214	CCTV lens	C mount f = 12 mm
IV-1A0104	ML-2514	CCTV lens	C mount f = 25 mm
IV-1A0105	ML-3514	CCTV lens	C mount f = 35 mm
IV-1A0106	ML-5018	CCTV lens	C mount f = 50 mm
IV-1A0107	ML-7527	CCTV lens	C mount f = 75 mm
IV-1A0201	ML-EXR	Close up ring	A set of 7 intermediate rings
IV-1A0301	MIML1-65D	Telecentric lens MY	C mount 1x
IV-1A0302	MIML2-65D	Telecentric lens	C mount 2x
IV-1A1101	ML17-07516	CCTV lens	φ17 mm mount f = 7.5 mm
IV-1A1102	ML17-1520	CCTV lens	φ17 mm mount f = 15 mm
IV-1A1103	ML17-2431	CCTV lens	φ17 mm mount f = 24 mm
IV-1A1301	MML1-65D-CM1	Telecentric lens	φ17 mm mount 1x
IV-1A1302	MML2-65D-CM1	Telecentric lens	φ17 mm mount 2x
IV-2A0101	MHF-H50LR	Halogen light source	50 W
IV-2A0102	MHF-D100LR	Halogen light source	100 W
IV-2A0103	MHF-150L	Halogen light source	150 W
IV-2A0201	LM-50	Halogen lamp	12 V, 50 W
IV-2A0202	LM-100	Halogen lamp	12 V, 100 W
IV-2A0203	LM-150	Halogen lamp	12 V, 150 W (high luminous)
IV-2A0204	LM-150C	Halogen lamp	12 V, 150 W (long life)
IV-2A0301	MRG31-1500S	Ring light guide	φ 31 x 1500 mm
IV-2A0302	MRG48-1500S	Ring light guide	φ 48 x 1500 mm
IV-2A0401	MSG4-1100S	Straight light guide	φ 4 mm, 1100 mm
IV-2A0701	MPP60-1500S	Surface illuminating light guide	60 x 60 mm, 1500 mm
IV-2A0901	KA-03	Crystal adapter	Needed when the IV-2A0701 is used with an IV-2A0102

The items listed above are all Moritex products.

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